

Accretion, mergers, and metastability of fuzzy spheres in a three-matrix model

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The goal

Take a matrix model with many (fuzzy-sphere) vacua and figure out whether the **lowest energy** one can actually be reached.

The question in one slide

We picked a three-matrix model that contains a multitude of fuzzy sphere states, with the largest one being the only stable one.

Is that state **reachable** in a finite amount of *time*?

It depends — on the dispersion of the initial configuration.

- ▶ **cold** start $\Rightarrow$ stuck in an *onion* state,
- ▶ **hot** start $\Rightarrow$ the global minimum.

Crucial mechanism: **accretion, driven by fluctuations of the sphere centres and instabilities.**

Why who choice this model?

It is simple, numerically accessible, and well-researched.

The real target is IKKT:

- ▶ many saddle points, quantum spaces of various dimensions,
- ▶ candidates for near-realistic cosmological backgrounds.

Are such backgrounds long-lived enough to support physics?

Here: the same question, in a model simple enough to simulate.

The model

$$S[A] = N \operatorname{tr} \left(-\frac{1}{4} [A_i, A_j]^2 + \frac{2}{3} i\alpha \epsilon_{ijk} A_i A_j A_k \right)$$

$$Z = \int dA e^{-S}$$

Three traceless Hermitian $N \times N$ matrices, $i = 1, 2, 3$. Yang–Mills plus a Myers term, invariant under $A_i \rightarrow A_i + a_i \mathbf{1}$.

Two phases, with $\tilde{\alpha} = \alpha\sqrt{N}$ and $\tilde{\alpha}_{crit} \approx 2.1$:

- ▶ $\tilde{\alpha} < \tilde{\alpha}_{crit}$: diagonal matrices, $S = 0$,
- ▶ $\tilde{\alpha} > \tilde{\alpha}_{crit}$: the fuzzy sphere $A_i = \alpha L_i$.

We keep $\alpha = 1$, deep in the fuzzy-sphere phase.

Alekseev, Recknagel, Schomerus; Azuma, Bal, Nagao, Nishimura 2004.

A plethora of classical solutions

$$[X_i, X_j] = \lambda i \varepsilon_{ijk} X_k, \quad X_i X_i = \frac{\lambda^2 (N^2 - 1)}{4} \mathbf{1}$$

so any block-diagonal stack of fuzzy spheres solves the model:

$$A_i = \begin{pmatrix} X_i^{(n_1)} & 0 & 0 \\ 0 & \ddots & 0 \\ 0 & 0 & X_i^{(n_K)} \end{pmatrix} \equiv \mathbf{X}(n_1, \dots, n_K), \quad N = \sum_{k=1}^K n_k$$

$$S_0(n_1, \dots, n_K) = -\frac{N\alpha^4}{24} \sum_k n_k (n_k^2 - 1)$$

Minimised by $\mathbf{X}(N)$, a single largest sphere. The competitors are **all partitions of N** .

Simulation setup

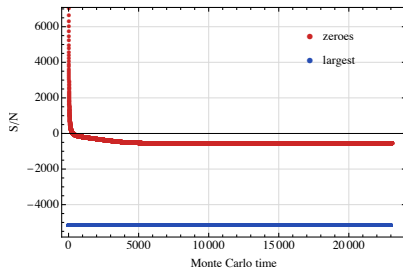
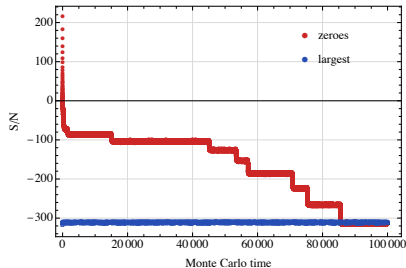
Hamiltonian Monte Carlo, deliberately **without** enhancements such as cluster flipping — those algorithms exist to hop between vacua, and the hopping is exactly what we want to watch.

Two observables suffice:

- ▶ S/N ,
- ▶ the eigenvalues of the radial operator $X^2 = X_i X_i$.

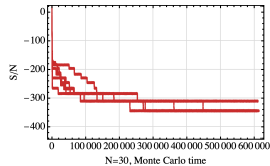
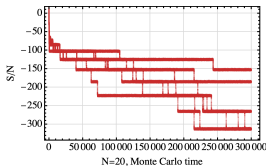
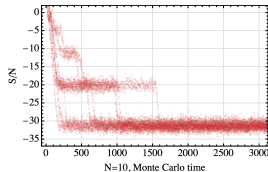
Metastability: the system stays near a given point for a large, but not infinite, number of HMC steps.

Reaching the minimum



Two runs each, one from the zero configuration and one from $\mathbf{X}(N)$, with $\alpha = 1$. Left $N = 20$, right $N = 50$.

Not an accident



Ensembles of 8 runs, $N = 10, 20, 30$. Only $N = 10$ reaches the lowest energy state; long plateaus are common everywhere.

What is the system doing on those plateaus?

A tempting explanation: entropy

There is one maximal sphere, but many ways to split N :

$$P(N) \sim \frac{1}{4N\sqrt{3}} \exp\left(\pi\sqrt{\frac{2N}{3}}\right)$$

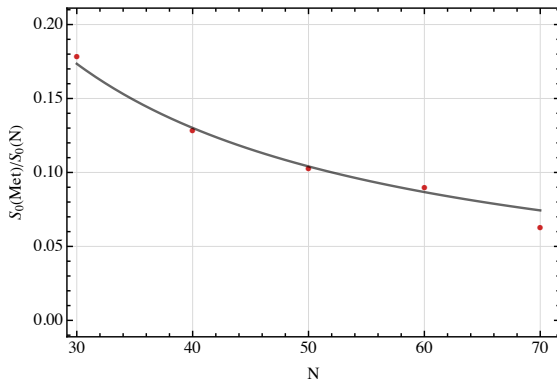
If partitions were sampled uniformly, the typical shape would be the Vershik curve, with $x = n_k/\sqrt{N}$ and $y = k/\sqrt{N}$:

$$e^{-\pi x/\sqrt{6}} + e^{-\pi y/\sqrt{6}} = 1 \quad \Rightarrow \quad S_0(\text{Ver}) \approx -\frac{N^3 \alpha^4}{10}$$

This gives a prediction: $S_0(\text{Ver})/S_0(\mathbf{X}(N)) = 2.4/N$,

with both the size and the number of spheres scaling as $\sqrt{N}$.

But the plateaus are not Vershik states

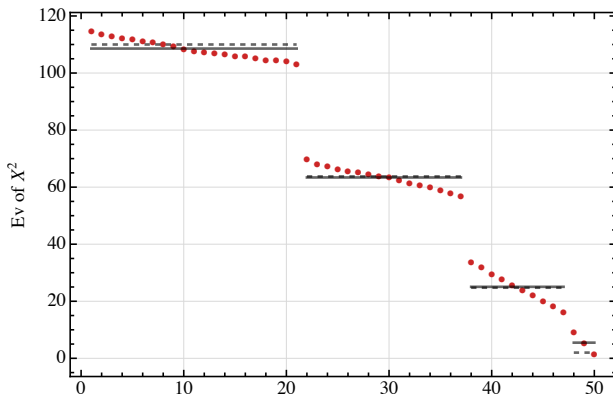


Ratio $S_0(\text{Met})/S_0(\mathbf{X}(N))$ against N , averaged over the last 1000 steps after the plateau is reached.

The N^{-1} trend is confirmed, but the coefficient is **5.20**, not 2.4.

Not typical partitions — far fewer, far larger spheres.

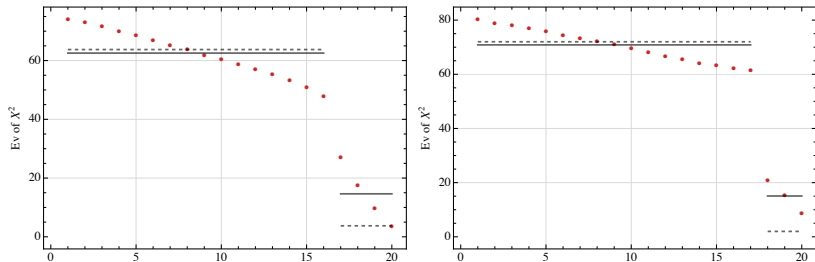
Disecting the states, eigenvalues of $\mathbf{X}^2$



Average $\mathbf{X}$ over 10 steps so the vacuum shows through, then diagonalise $\mathbf{X}^2$. Each sphere gives a plateau at $\alpha^2(n_k^2 - 1)/4$ (dashed); solid lines are cluster means.

For $N = 50$ this state is $\mathbf{X}(21, 16, 10, 3)$. Vershik would want $\sim \sqrt{50}$ spheres of size $\sim \sqrt{50}$.

The elementary transition is an accretion



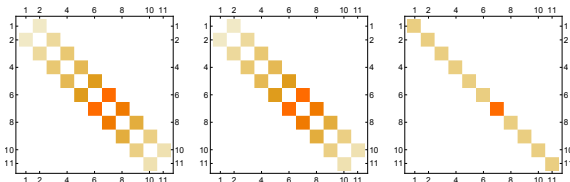
Radial-operator eigenvalues at steps 56 000 and 57 000, $N = 20$.

$$\mathbf{X}(\dots, n_r, \dots, n_s, \dots) \rightarrow \mathbf{X}(\dots, n_r - 1, \dots, n_s + 1, \dots)$$

The larger sphere absorbs **a single unit** from the smaller one. An **accretion**, not a merger.

The obstacle, in the matrix elements

$$d\mathbf{X} = \mathbf{X}(n, n+1) - \mathbf{X}(n-1, n+2)$$

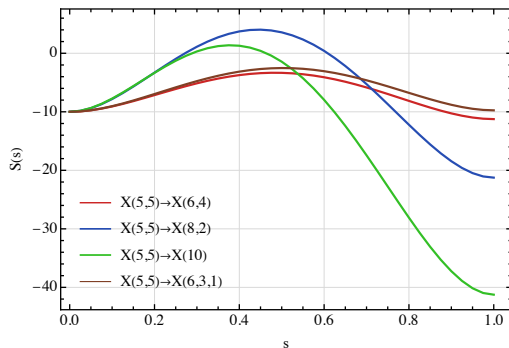


Amplitudes of the difference matrices for $n = 5$.

dX_3 is diagonal with all entries $-1/2$ except one, which equals n . Growing a block requires **a single new element of size $\sim n/2$** . With Gaussian HMC momenta this is **exponentially suppressed**.

The same statement as an energy barrier

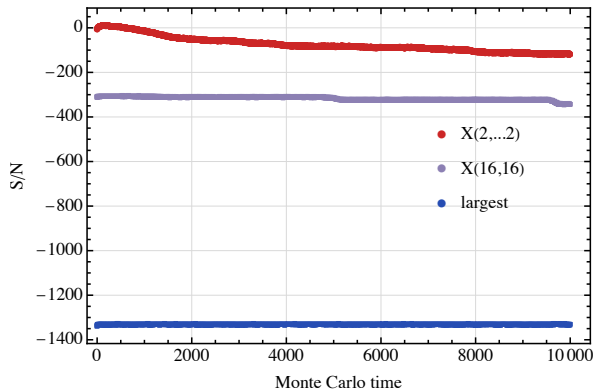
$$D(s) = S((1-s) \mathbf{X}_1 + s \mathbf{X}_2), \quad 0 \leq s \leq 1$$



Here $\mathbf{X}_1 = \mathbf{X}(5, 5)$ and $\mathbf{X}_2 = \mathbf{X}(6, 4), \mathbf{X}(8, 2), \mathbf{X}(10), \mathbf{X}(6, 3, 1)$.

The cheapest route is the smallest accretion, and it is still expensive. For $\mathbf{X}(50, 50) \rightarrow \mathbf{X}(49, 51)$ the available fluctuation is $|\delta S/S| \approx 0.0001$, while $|\delta S/S| \approx 0.76$ is needed.

And mergers do not happen



A merger would be $\mathbf{X}(\dots, r, s, \dots) \rightarrow \mathbf{X}(\dots, r + s, \dots)$.

Tested from $\mathbf{X}(2, \dots, 2)$ and from $\mathbf{X}(16, 16)$: **none observed**, only gradual steps.

D-branes, and how to look at them

Diagonal elements give the positions of *D*0-branes, fuzzy spheres are *D*2-branes, and the cascade is a sequence of **brane accretions and mergers**.

Close *D*0-branes form *D*2-branes, their centres tend to align into concentric shells, and overlapping *D*2-branes are unstable.

To visualise a configuration, define the displacement Hamiltonian

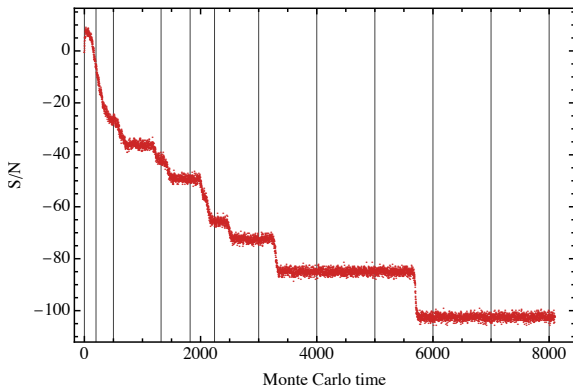
$$H(x) = \frac{1}{2} \sum_{a=1}^D (Y_a - x_a I_N)^2,$$

scan through $\mathbb{R}^D$, keep the lowest eigenvalues and plot

$$Y(x) = (\langle x | Y_1 | x \rangle, \dots, \langle x | Y_D | x \rangle).$$

Schneiderbauer, Steinacker 2016.

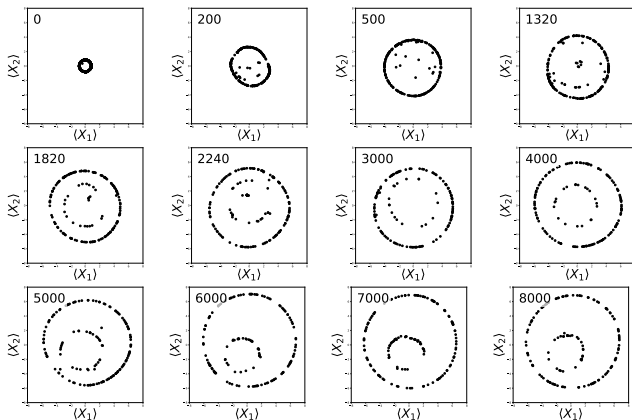
Cascading and plateauing: numerical point of view



$N = 20$, initiated in $\mathbf{X}(2, \dots, 2)$: the smallest possible concentric spheres. Grid lines mark the states visualised next.

Accretion drives the cascade, fluctuations make the gap smaller.

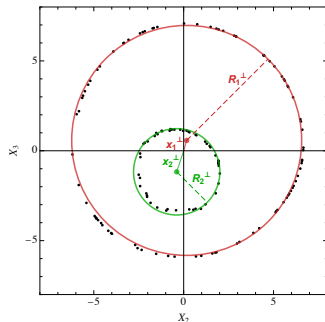
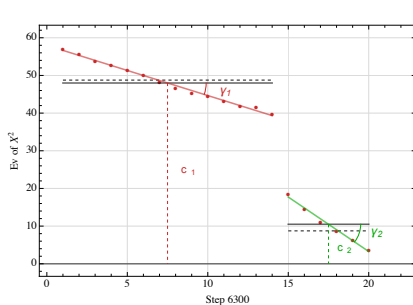
Cascading and plateauing: membrane point of view



Two concentric fuzzy spheres form and grow; the position of the smaller one fluctuates considerably.

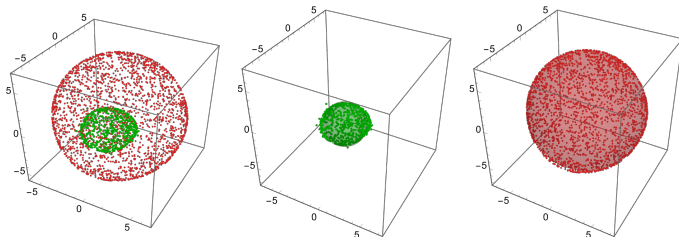
Metastability is stiffness, not entropy.

Two readings of the same configuration



Step 6300 of the previous run. Left: two distinct levels in the radial operator, fitted for the offset and the radius. Right: the visualised points, projected on the $X_1 = 0$ plane and fitted.

Radial levels against quantum geometry



	$ x_1 $	R_1	$ x_2 $	R_2
radial levels	0.66(1)	6.90(2)	1.45(7)	2.9(4)
quantum geometry	0.673(7)	6.405(3)	1.379(9)	2.479(6)

Few-percent agreement between two entirely different extractions.

One-loop effective action for two spheres

Background $\mathbf{X} = \alpha \text{diag} (L^{(n_1)} + x^{(1)}, L^{(n_2)} + x^{(2)})$ with $n_1 \gg n_2$:

$$W = \sum_{j_{\min}}^{j_{\max}} \log w_j, \quad w_j = \frac{h(j, j+1)h(j, -j-1)}{h(j, j)h(j, -j)} \prod_{m=-j}^j h(j, m)$$

with $h(j, m) = \xi^2 + 2\xi m + j(j+1)$ and $\xi_i = x_i^{(1)} - x_i^{(2)}$.

For a sphere inside a sphere the minimum is at $\xi_i = 0$ – they are **concentric** – and for $W = W_0 + \frac{1}{2} M_\xi^2 \xi_i^2 + \dots$ we have the mass as

$$M_\xi^2 = \sum_{j=j_{\min}}^{j_{\max}} (2j+1) \left(\frac{2}{3j(j+1)} - \frac{8}{j^2(j+1)^2} \right).$$

For well-separated spheres there is a **logarithmic attraction**: long-range, and with no barrier.

Azuma, Nagao, Nishimura 2007.

Measuring the centre fluctuations

For a state $\alpha(L_i + x_i \mathbf{1})$ the radial operator is

$$X_i X_i = \alpha^2 (L^2 + 2L_i x_i + x^2),$$

so each level is **lifted** by x^2 and, choosing $\vec{x} = (0, 0, x)$, **tilted** by $2\alpha x m$. The tilt measures $|x|$ accurately.

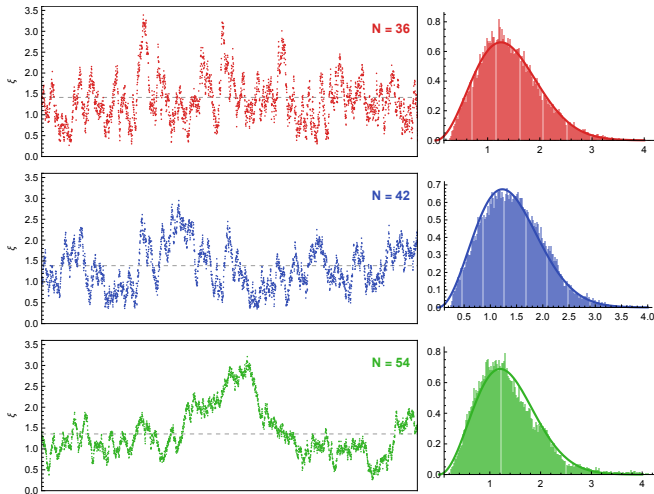
The shifts of a pair are opposite, so $|\xi| = |x_1| + |x_2|$ is

Maxwell-distributed with mean $\sqrt{8/(\pi M_\xi^2)}$ — **a prediction with no free parameters.**

	$\langle \xi \rangle_{mes}$	$\langle \xi \rangle_{pred}$	τ_{aut}
$N = 36$	1.44(3)	1.42	~ 3600
$N = 42$	1.44(4)	1.39	~ 6900
$N = 54$	1.36(6)	1.36	$\sim 19\,400$

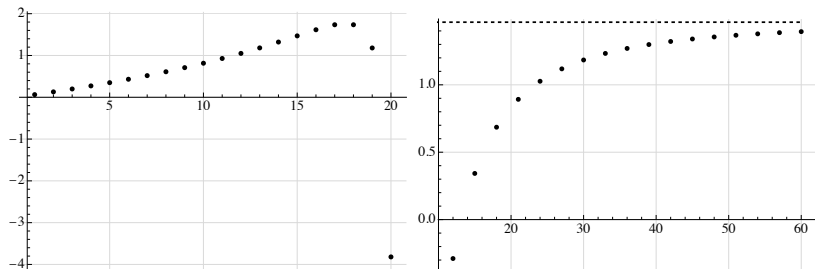
Splits $n_1 = 2N/3$, jackknife errors. Also $\langle n_1|x_1|/n_2|x_2| \rangle = 1.0(1)$, as $\text{Tr} X = 0$ requires.

Trajectories and histograms, nothing fitted



$|x_i|$ measured every 100 steps during runs of 3×10^6 steps. The amplitudes barely change with N , while the autocorrelation time grows rapidly. Right: measured histograms against the one-loop prediction.

Why the accretions stop



Left: the effective mass for $N = 42$ and various splits $\mathbf{X}(42 - n_2, n_2)$. Right: the $n_1 = 2n_2$ splitting and its large- N limit.

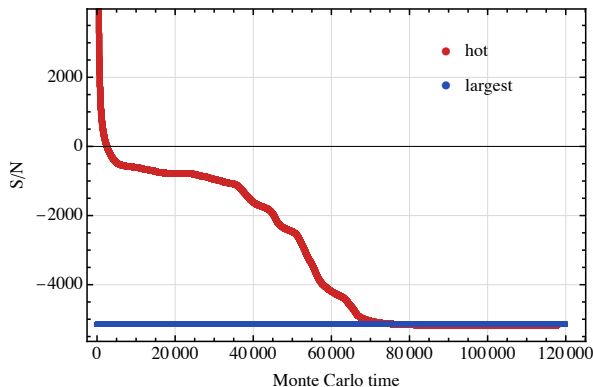
An accretion needs $|\xi| \sim R_1 - R_2$. The **amplitude saturates** while the **gap grows linearly**. For $n_1 = bN$ with $b > 1/2$,

$$\lim_{N \rightarrow \infty} M_{\xi}^2(b) = -\frac{4}{3} \log(2b - 1),$$

negative as $b \rightarrow 1/2$: the known instability of overlapping spheres.

We understand the plateaus now. Can we see a path to the minimum state $\mathbf{X}(N)$?

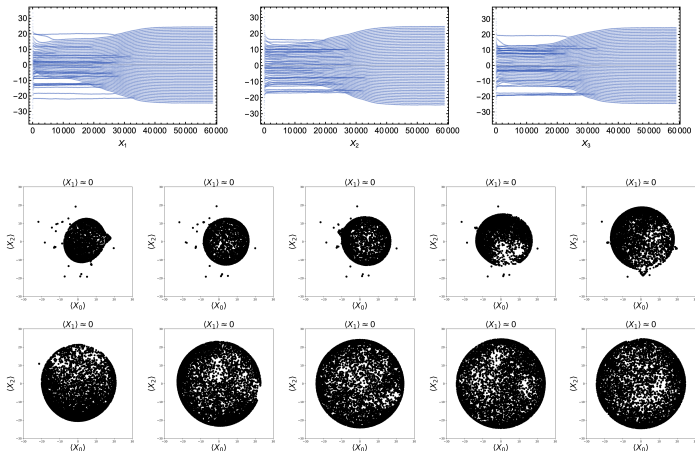
Hot initial conditions



Hermitian matrices with normally distributed entries, dispersion 3 instead of $1/\sqrt{2}$, giving well-separated $D0$ -branes.

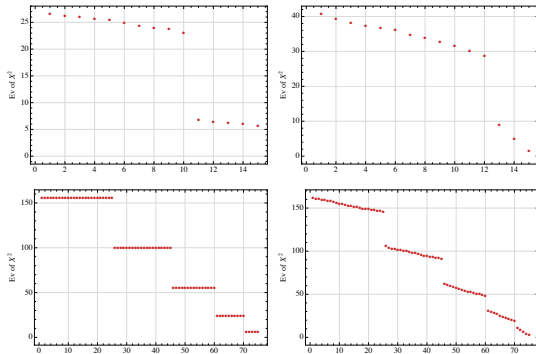
A few of them seed a sphere and the rest **fall in from outside**.
Slow, long-range, but with no barriers to cross.

Infall, seen directly



$N = 50$ from a hot state: HMC trajectories of the three matrices, and the geometry visualised every 1000th step. The lowest energy state is achieved.

The fuzzy onion



Top: $\mathbf{X}(10,5)$ at steps 100 and 1000. Bottom: $\mathbf{X}(25,20,15,10,5)$ at steps 100 and 200 000.

Concentric spheres $n_k = \Delta k$ describe a rotationally invariant 3D quantum space. The two-sphere system decays after $\sim 10^3$ steps; the five-sphere one survives $\sim 232\,000$.

Outer layers stabilise the inner ones.

Stiffening with layers

Generalising to K blocks, the interaction is a sum of pairwise terms:

$$W = W_0 + \frac{1}{2} \sum_{I < J} M_{IJ}^2 \left| \vec{\xi}^{(IJ)} \right|^2 + \dots$$

For the innermost sphere, with the others near the origin,
 $\mathbf{x}^{(2)} = \mathbf{x}^{(3)} = \dots = 0$

$$W_1 = \frac{2}{3} \left(\log \frac{K(K+1)}{2} - \frac{q}{\Delta^2} \right) \left(\mathbf{x}^{(1)} \right)^2, \quad q = \frac{355}{12} \approx 30.$$

The mass **diverges** as $K \rightarrow \infty$: the onion becomes rigid. For finite K the system is unstable below

$$K_C \approx e^{15/\Delta^2}.$$

Conclusions

- ▶ The model is surprisingly rich.
- ▶ Both cold initial configurations and multiple copies of the same fuzzy sphere lead to a slowing cascade of metastable states.
- ▶ Onion state seems stable in the infinite size limit.
- ▶ Hot initial states lead to the largest fuzzy sphere state.

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Thank you for your attention!