

On the Extended Geometry of Kac-Moody Symmetries of Quantum Gravity

Keith Glennon



Trinity College Dublin
Coláiste na Tríonóide, Baile Átha Cliath
The University of Dublin

Based on: [1] WIP (K.G.); [2] 2607.01999, [3] 2102.02152 (K.G., Peter West).

11-9-2026

Corfu2026: Quantum Gravity and Strings Workshop



Origins of 11D SUGRA

On the light cone, $i, j = 3, \dots, 11$, find graviton, three-form of $SO(9)$

$$h_{ij} = h_{ji} \quad (44), \quad (1)$$

$$A_{i_1 i_2 i_3} = A_{[i_1 i_2 i_3]} \quad (84), \quad (2)$$

Here $h^i{}_i = 0$; $44 + 84 = 128$ dof. Instead of seeking non-linear theory:

Origins of 11D SUGRA

On the light cone, $i, j = 3, \dots, 11$, find graviton, three-form of $SO(9)$

$$h_{ij} = h_{ji} \quad (44), \quad (1)$$

$$A_{i_1 i_2 i_3} = A_{[i_1 i_2 i_3]} \quad (84), \quad (2)$$

Here $h^i{}_i = 0$; $44 + 84 = 128$ dof. Instead of seeking non-linear theory:

Let's Study Dualities

Origins of 11D SUGRA

On the light cone, $i, j = 3, \dots, 11$, find graviton, three-form of $SO(9)$

$$h_{ij} = h_{ji} \quad (44), \quad (1)$$

$$A_{i_1 i_2 i_3} = A_{[i_1 i_2 i_3]} \quad (84), \quad (2)$$

Here $h^i{}_i = 0$; $44 + 84 = 128$ dof. Instead of seeking non-linear theory:

Let's Study Dualities

Introduce 'dual' formulations of above fields

$$A_{i_1 \dots i_6} = A_{[i_1 \dots i_6]} \quad (84) \quad (3)$$

$$h_{i_1 \dots i_8, j} = h_{[i_1 \dots i_8], j} \quad (81) \quad (4)$$

Origins of 11D SUGRA

On the light cone, $i, j = 3, \dots, 11$, find graviton, three-form of $SO(9)$

$$h_{ij} = h_{ji} \quad (44), \quad (1)$$

$$A_{i_1 i_2 i_3} = A_{[i_1 i_2 i_3]} \quad (84), \quad (2)$$

Here $h^i{}_i = 0$; $44 + 84 = 128$ dof. Instead of seeking non-linear theory:

Let's Study Dualities

Introduce 'dual' formulations of above fields

$$A_{i_1 \dots i_6} = A_{[i_1 \dots i_6]} \quad (84) \quad (3)$$

$$h_{i_1 \dots i_8, j} = h_{[i_1 \dots i_8], j} \quad (81) \quad (4)$$

Propose **Duality Relations**:

$$D_{ijk}^{1|2} = A_{ijk} + \frac{1}{6!} \epsilon_{ijk}{}^{l_1 \dots l_6} A_{l_1 \dots l_6} = 0 \quad (5)$$

$$D_{ij}^{0|3} = h_{ij} + \frac{1}{8!} \epsilon_i{}^{k_1 \dots k_8} h_{k_1 \dots k_8, j} = 0 \quad (6)$$

$h^i{}_i = 0$ gives $h_{[i_1 \dots i_8, j]} = 0$ ($81 \rightarrow 80$); $D_{ij}^{0|3} = 0$ gives $D_{[ij]} = 0$ ($80 \rightarrow 44$).

Origins of 11D SUGRA

On the light cone, $i, j = 3, \dots, 11$, find graviton, three-form of $SO(9)$

$$h_{ij} = h_{ji} \quad (44), \quad (1)$$

$$A_{i_1 i_2 i_3} = A_{[i_1 i_2 i_3]} \quad (84), \quad (2)$$

Here $h^i{}_i = 0$; $44 + 84 = 128$ dof. Instead of seeking non-linear theory:

Let's Study Dualities

Introduce 'dual' formulations of above fields

$$A_{i_1 \dots i_6} = A_{[i_1 \dots i_6]} \quad (84) \quad (3)$$

$$h_{i_1 \dots i_8, j} = h_{[i_1 \dots i_8], j} \quad (81) \quad (4)$$

Propose **Duality Relations**:

$$D_{ijk}^{1|2} = A_{ijk} + \frac{1}{6!} \epsilon_{ijk}{}^{l_1 \dots l_6} A_{l_1 \dots l_6} = 0 \quad (5)$$

$$D_{ij}^{0|3} = h_{ij} + \frac{1}{8!} \epsilon_i{}^{k_1 \dots k_8} h_{k_1 \dots k_8, j} = 0 \quad (6)$$

$h^i{}_i = 0$ gives $h_{[i_1 \dots i_8, j]} = 0$ ($81 \rightarrow 80$); $D_{ij}^{0|3} = 0$ gives $D_{[ij]} = 0$ ($80 \rightarrow 44$).

Why Stop Dualizing Here?

Continue the Dual Descriptions

Find ∞ no. of duals by appending blocks of 9 indices on previous via

$$X_{i_1 \dots i_9, J} = \epsilon_{i_1 \dots i_9} X_J. \quad (7)$$

Continue the Dual Descriptions

Find ∞ no. of duals by appending blocks of 9 indices on previous via

$$X_{i_1 \dots i_9, J} = \epsilon_{i_1 \dots i_9} X_J. \quad (7)$$

Introduce the set of fields

$$\begin{aligned} h_{ij}, \quad A_{i_1 i_2 i_3}, \quad A_{i_1 \dots i_6}, \quad h_{i_1 \dots i_8, j}, \\ A_{i_1 \dots i_9, j_1 j_2 j_3}, \quad A_{i_1 \dots i_9, j_1 \dots j_6}, \quad h_{i_1 \dots i_9, j_1 \dots j_8, k}, \\ A_{i_1 \dots i_9, j_1 \dots j_9, k_1 k_2 k_3}, \quad \dots \end{aligned} \quad (8)$$

Continue the Dual Descriptions

Find ∞ no. of duals by appending blocks of 9 indices on previous via

$$X_{i_1 \dots i_9, J} = \epsilon_{i_1 \dots i_9} X_J. \quad (7)$$

Introduce the set of fields

$$\begin{aligned} h_{ij}, \quad A_{i_1 i_2 i_3}, \quad A_{i_1 \dots i_6}, \quad h_{i_1 \dots i_8, j}, \\ A_{i_1 \dots i_9, j_1 j_2 j_3}, \quad A_{i_1 \dots i_9, j_1 \dots j_6}, \quad h_{i_1 \dots i_9, j_1 \dots j_8, k}, \\ A_{i_1 \dots i_9, j_1 \dots j_9, k_1 k_2 k_3}, \quad \dots \end{aligned} \quad (8)$$

Subject these to duality relations, for example:

$$D_{ijk}^{1|4} = A_{i_1 i_2 i_3} - \frac{1}{9!} \epsilon^{i_1 \dots i_9} A_{i_1 \dots i_9, i_1 i_2 i_3} = 0, \quad (9)$$

$$D_{ij}^{0|6} = h_{ij} + \frac{1}{9!8!} \epsilon_i^{k_1 \dots k_8} \epsilon^{i_1 \dots i_9} h_{i_1 \dots i_9, k_1 \dots k_8, j} = 0. \quad (10)$$

All higher tensors are therefore constrained to describe the original

$$44 + 84 = 128 \quad (11)$$

physical bosonic degrees of freedom.

Continue the Dual Descriptions

Find ∞ no. of duals by appending blocks of 9 indices on previous via

$$X_{i_1 \dots i_9, J} = \epsilon_{i_1 \dots i_9} X_J. \quad (7)$$

Introduce the set of fields

$$\begin{aligned} h_{ij}, \quad A_{i_1 i_2 i_3}, \quad A_{i_1 \dots i_6}, \quad h_{i_1 \dots i_8, j}, \\ A_{i_1 \dots i_9, j_1 j_2 j_3}, \quad A_{i_1 \dots i_9, j_1 \dots j_6}, \quad h_{i_1 \dots i_9, j_1 \dots j_8, k}, \\ A_{i_1 \dots i_9, j_1 \dots j_9, k_1 k_2 k_3}, \quad \dots \end{aligned} \quad (8)$$

Subject these to duality relations, for example:

$$D_{ijk}^{1|4} = A_{i_1 i_2 i_3} - \frac{1}{9!} \epsilon^{i_1 \dots i_9} A_{i_1 \dots i_9, i_1 i_2 i_3} = 0, \quad (9)$$

$$D_{ij}^{0|6} = h_{ij} + \frac{1}{9!8!} \epsilon_i^{k_1 \dots k_8} \epsilon^{i_1 \dots i_9} h_{i_1 \dots i_9, k_1 \dots k_8, j} = 0. \quad (10)$$

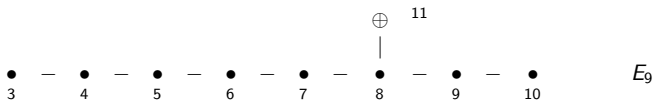
All higher tensors are therefore constrained to describe the original

$$44 + 84 = 128 \quad (11)$$

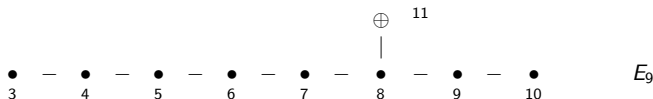
physical bosonic degrees of freedom.

These Fields are in 1-1 Correspondence With Borel Roots of E_9

The E_9 Dynkin Diagram



The E_9 Dynkin Diagram



- Nodes 3, ..., 10 give the $A_8 = \text{SL}(9)$ **gravity line**, with $\text{GL}(9)$'s K^i_j . Simple Roots $E_3 = K^3_4$, $E_4 = K^4_5$, ..., $E_{10} = K^{10}_{11}$.
- Node 11 gives the three-form $R^{i_1 i_2 i_3}$, simple root $E_{11} = R^{9 10 11}$.
- First few generators are:

ℓ	A_8 representation	generator
0	80	K^i_j
1	84	$R^{i_1 i_2 i_3}$
2	$\overline{\mathbf{84}}$	$R^{i_1 \dots i_6}$
3	80	$R^{i_1 \dots i_8, j}$
4	84	$R^{i_1 \dots i_9, j_1 j_2 j_3}$
5	$\overline{\mathbf{84}}$	$R^{i_1 \dots i_9, j_1 \dots j_6}$

Borel Roots of E_9 Come From $E_9/I_c(E_9)$

$E_9/I_c(E_9)$

Schematically,

$$E_9 = \{ \widehat{K}^i_j, R^{i_1 i_2 i_3}, R_{i_1 i_2 i_3}, R^{i_1 \dots i_6}, R_{i_1 \dots i_6}, R^{i_1 \dots i_8 j}, R_{i_1 \dots i_8 j}, \dots \}. \quad (12)$$

Define

$$J^{ij} := \delta^{ik} \widehat{K}^j_k - \delta^{jk} \widehat{K}^i_k, \quad S^{ijk} := R^{ijk} - R_{ijk}, \quad (13)$$

$$T^{ij} := \delta^{ik} \widehat{K}^j_k + \delta^{jk} \widehat{K}^i_k, \quad T^{ijk} := R^{ijk} + R_{ijk}. \quad (14)$$

Then

$$I_c(E_9) = \{ J^{ij}, S^{ijk}, \dots \}, \quad (15)$$

$$E_9/I_c(E_9) = \{ T^{ij}, T^{ijk}, T^{i_1 \dots i_6}, T^{i_1 \dots i_8 j}, \dots \}. \quad (16)$$

$E_9/I_c(E_9)$

Schematically,

$$E_9 = \{ \widehat{K}^i_j, R^{i_1 i_2 i_3}, R_{i_1 i_2 i_3}, R^{i_1 \dots i_6}, R_{i_1 \dots i_6}, R^{i_1 \dots i_8, j}, R_{i_1 \dots i_8, j}, \dots \}. \quad (12)$$

Define

$$J^{ij} := \delta^{ik} \widehat{K}^j_k - \delta^{jk} \widehat{K}^i_k, \quad S^{ijk} := R^{ijk} - R_{ijk}, \quad (13)$$

$$T^{ij} := \delta^{ik} \widehat{K}^j_k + \delta^{jk} \widehat{K}^i_k, \quad T^{ijk} := R^{ijk} + R_{ijk}. \quad (14)$$

Then

$$I_c(E_9) = \{ J^{ij}, S^{ijk}, \dots \}, \quad (15)$$

$$E_9/I_c(E_9) = \{ T^{ij}, T^{ijk}, T^{i_1 \dots i_6}, T^{i_1 \dots i_8, j}, \dots \}. \quad (16)$$

Take

$$g = \exp(\mathcal{V}) \in E_9/I_c(E_9), \quad (17)$$

with

$$\mathcal{V} = h_{ij} T^{ij} + A_{ijk} T^{ijk} + A_{i_1 \dots i_6} T^{i_1 \dots i_6} + h_{i_1 \dots i_8, j} T^{i_1 \dots i_8, j} + \dots \quad (18)$$

Dualities Built From Fields on $E_9/I_c(E_9)$. Preserved by $I_c(E_9)$?

$I_c(E_9)$ Preserves the Dualities

Under a local $h \in I_c(E_9)$ transformation $g \rightarrow gh$

$$\delta \mathcal{V} = [\Lambda_{ijk} S^{ijk}, \mathcal{V}]. \quad (19)$$

The first variations are

$$\delta A_{i_1 i_2 i_3} = -6 h_{[i_1}{}^k \Lambda_{i_2 i_3]k} + A_{i_1 i_2 i_3}{}^{k_1 k_2 k_3} \Lambda_{k_1 k_2 k_3}, \quad (20)$$

$$\delta A_{i_1 \dots i_6} = 120 \Lambda_{[i_1 i_2 i_3} A_{i_4 i_5 i_6]} - \frac{2}{3} \Lambda^{k_1 k_2 k_3} (h_{i_1 \dots i_6 k_1 k_2, k_3} + h_{[i_1 \dots i_5 | k_1 k_2 k_3 |, i_6]}) . \quad (21)$$

$I_c(E_9)$ Preserves the Dualities

Under a local $h \in I_c(E_9)$ transformation $g \rightarrow gh$

$$\delta \mathcal{V} = [\Lambda_{ijk} S^{ijk}, \mathcal{V}]. \quad (19)$$

The first variations are

$$\delta A_{i_1 i_2 i_3} = -6 h_{[i_1}{}^k \Lambda_{i_2 i_3]k} + A_{i_1 i_2 i_3}{}^{k_1 k_2 k_3} \Lambda_{k_1 k_2 k_3}, \quad (20)$$

$$\delta A_{i_1 \dots i_6} = 120 \Lambda_{[i_1 i_2 i_3} A_{i_4 i_5 i_6]} - \frac{2}{3} \Lambda^{k_1 k_2 k_3} (h_{i_1 \dots i_6 k_1 k_2 k_3} + h_{[i_1 \dots i_5 | k_1 k_2 k_3 |, i_6]}) . \quad (21)$$

The dualities vary as

$$\delta D_{i_1 i_2 i_3}^{1|2} = \frac{1}{6} \Lambda_{j_1 j_2 j_3} \epsilon_{i_1 i_2 i_3}{}^{j_1 \dots j_6} D_{j_4 j_5 j_6}^{1|2} - 6 D_{k[i_1}^{0|3} \Lambda^k{}_{i_2 i_3]} . \quad (22)$$

More generally,

$$\delta D^{(r)} = \sum_s M^{(r)}{}_s D^{(s)} \quad (23)$$

so the complete set $D^{(r)} = 0$ is preserved.

The Fields Transform — Space-Time Must Transform Too

Introducing Space-Time

Under $GL(9)$, the i, j indices in $h_{ij}(x)$ transform, but so does x .

Introduce the translation representation

$$I_1^{E_9} = \{P_i, Z^{ij}, Z^{i_1 \dots i_5}, Z^{i_1 \dots i_8}, Z^{i_1 \dots i_7 j}, \dots\}. \quad (24)$$

Already

$$[R^{ijk}, P_l] = 3\delta_l^{[i} Z^{jk]}, \quad (25)$$

so $\{P_i\}$ is not closed under E_9 .

Therefore

$$\boxed{E_9 \otimes_s I_1^{E_9} / I_c(E_9)}. \quad (26)$$

Introducing Space-Time

Under $GL(9)$, the i, j indices in $h_{ij}(x)$ transform, but so does x .

Introduce the translation representation

$$I_1^{E_9} = \{P_i, Z^{ij}, Z^{i_1 \dots i_5}, Z^{i_1 \dots i_8}, Z^{i_1 \dots i_7, j}, \dots\}. \quad (24)$$

Already

$$[R^{ijk}, P_l] = 3\delta_l^i Z^{jk}, \quad (25)$$

so $\{P_i\}$ is not closed under E_9 .

Therefore

$$\boxed{E_9 \otimes_s I_1^{E_9} / I_c(E_9)}. \quad (26)$$

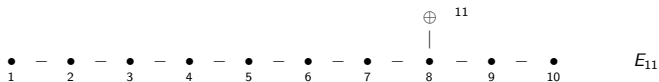
This contains the usual gravitational $GL(9) \otimes_s \{P_i\} / SO(9)$ realization,

$$g \supset e^{x^i P_i} e^{h_i^j(x) K_j^i}, \quad (27)$$

which gives, at linear order,

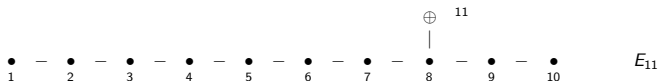
$$e_i^a(x) = \delta_i^a + h_i^a(x) + \dots \quad (28)$$

So Far We Have Used Only Nine Space-Time Directions

From E_9 to E_{11} Go from 9D to 11D via: $A_8 = \text{SL}(9) \longrightarrow A_{10} = \text{SL}(11)$ 

From E_9 to E_{11}

Go from 9D to 11D via: $A_8 = \text{SL}(9) \longrightarrow A_{10} = \text{SL}(11)$



The first fields are

$$h_a{}^b [0], \quad A_{a_1 a_2 a_3} [1], \quad A_{a_1 \dots a_6} [2], \quad h_{a_1 \dots a_8, b} [3]. \quad (29)$$

The nonlinear 3-6 duality relation is

$$F_{a_1 \dots a_7} = \frac{1}{4!} \epsilon_{a_1 \dots a_7 b_1 \dots b_4} F^{b_1 \dots b_4}, \quad (30)$$

$$F_{a_1 \dots a_4} = 4 \partial_{[a_1} A_{a_2 a_3 a_4]}, \quad F_{a_1 \dots a_7} = 7 \partial_{[a_1} A_{a_2 \dots a_7]} + \dots \quad (31)$$

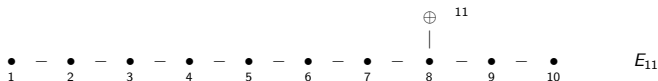
These dualities arise from the coset model

$$\boxed{E_{11} \otimes_s l_1^{E_{11}} / l_c(E_{11})}. \quad (32)$$

This reverses standard story in E_{11} literature [1], see also [3]. Found KMA from lightcone dof and dualities, bypassing long/detailed historical path starting from non-linear 11D SUGRA.

From E_9 to E_{11}

Go from 9D to 11D via: $A_8 = \text{SL}(9) \longrightarrow A_{10} = \text{SL}(11)$



The first fields are

$$h_a{}^b [0], \quad A_{a_1 a_2 a_3} [1], \quad A_{a_1 \dots a_6} [2], \quad h_{a_1 \dots a_8, b} [3]. \quad (29)$$

The nonlinear 3-6 duality relation is

$$F_{a_1 \dots a_7} = \frac{1}{4!} \epsilon_{a_1 \dots a_7 b_1 \dots b_4} F^{b_1 \dots b_4}, \quad (30)$$

$$F_{a_1 \dots a_4} = 4 \partial_{[a_1} A_{a_2 a_3 a_4]}, \quad F_{a_1 \dots a_7} = 7 \partial_{[a_1} A_{a_2 \dots a_7]} + \dots \quad (31)$$

These dualities arise from the coset model

$$\boxed{E_{11} \otimes_s l_1^{E_{11}} / l_c(E_{11})}. \quad (32)$$

This reverses standard story in E_{11} literature [1], see also [3]. Found KMA from lightcone dof and dualities, bypassing long/detailed historical path starting from non-linear 11D SUGRA.

Historically, the Logic Was Reversed

The Historical Route: Dimensional Reduction

Historically, began from full non-linear 11D SUGRA, then studied toroidal reduction of 11D SUGRA to $D = 11 - n$, found:

- hidden E_n symmetries,
- scalar dynamics organised by $E_n/I_c(E_n)$.

D	Hidden symmetry	Coset / nonlinear realization
10 IIA	$O(1, 1)$	–
9	$GL(2)$	$GL(2)/SO(2)$
8	$E_3 = A_2 \times A_1$	$SL(3) \times SL(2)$
7	$E_4 = A_4$	$SO(3) \times SO(2)$
6	$E_5 = D_5$	$SL(5)/SO(5)$
5	E_6	$SO(5, 5)/(SO(5) \times SO(5))$
4	E_7	$E_6/Sp(8)$
3	E_8	$E_7/SU(8)$
2	E_9	$E_8/SO(16)$
1	E_{10}	$E_9/I_c(E_9)$
		$E_{10}/I_c(E_{10})$

The Historical Route: Dimensional Reduction

Historically, began from full non-linear 11D SUGRA, then studied toroidal reduction of 11D SUGRA to $D = 11 - n$, found:

- hidden E_n symmetries,
- scalar dynamics organised by $E_n/I_c(E_n)$.

D	Hidden symmetry	Coset / nonlinear realization
10 IIA	$O(1, 1)$	—
9	$GL(2)$	$GL(2)/SO(2)$
8	$E_3 = A_2 \times A_1$	$SL(3) \times SL(2)$
7	$E_4 = A_4$	$SO(3) \times SO(2)$
6	$E_5 = D_5$	$SL(5)/SO(5)$
5	E_6	$SO(5, 5)/(SO(5) \times SO(5))$
4	E_7	$E_6/Sp(8)$
3	E_8	$E_7/SU(8)$
2	E_9	$E_8/SO(16)$
1	E_{10}	$E_9/I_c(E_9)$
		$E_{10}/I_c(E_{10})$

One way to motivate E_{11} is that the E_{11} diagram explains the table visually, e.g. in 4D



Same Idea Holds for 4D Gravity

4D Gravity and A_1^{+++}

Start from 4D gravity: $e_\mu{}^a(x)$ comes from $GL(4) \otimes \{P_a\}/SO(1,3)$:

$$\begin{array}{ccccccc} \bullet & - & \bullet & - & \bullet & & \bar{\bullet} \\ 1 & & 2 & & 3 & & 4 \end{array} \quad GL(4) \quad (33)$$

4D Gravity and A_1^{+++}

Start from 4D gravity: $e_\mu{}^a(x)$ comes from $GL(4) \otimes \{P_a\}/SO(1,3)$:

$$\begin{array}{ccccccc} \bullet & & - & & \bullet & & - & & \bullet & & & & \overline{\bullet} & & & & GL(4) \\ 1 & & & & 2 & & & & 3 & & & & 4 & & & & \end{array} \quad (33)$$

The known symmetries under dimensional reduction give

D	Symmetry	Diagram									
4	$GL(4)$	$\bullet$	$-$	$\bullet$	$-$	$\bullet$		$\overline{\bullet}$			
		1		2		3		4			
3	$GL(3) \times A_1$	$\bullet$	$-$	$\bullet$		$\overline{\bullet}$		$\bullet$			
		1		2		3		4			
2	$GL(2) \times A_1^+$	$\bullet$		$\overline{\bullet}$		$\bullet$	$=$	$\bullet$			
		1		2		3		4			
1	$GL(1) \times A_1^{++}$	$\overline{\bullet}$		$\bullet$	$-$	$\bullet$	$=$	$\bullet$			
		1		2		3		4			

4D Gravity and A_1^{+++}

Start from 4D gravity: $e_\mu{}^a(x)$ comes from $GL(4) \otimes \{P_a\}/SO(1,3)$:

$$\begin{array}{ccccccc} \bullet & - & \bullet & - & \bullet & & \overline{\bullet} \\ 1 & & 2 & & 3 & & 4 \end{array} \quad GL(4) \quad (33)$$

The known symmetries under dimensional reduction give

D	Symmetry	Diagram					
4	$GL(4)$	$\bullet$ 1	—	$\bullet$ 2	—	$\bullet$ 3	$\overline{\bullet}$ 4
3	$GL(3) \times A_1$	$\bullet$ 1	—	$\bullet$ 2		$\overline{\bullet}$ 3	$\bullet$ 4
2	$GL(2) \times A_1^+$	$\bullet$ 1		$\overline{\bullet}$ 2		$\bullet$ 3	$=$ $\bullet$ 4
1	$GL(1) \times A_1^{++}$	$\overline{\bullet}$ 1		$\bullet$ 2	—	$\bullet$ 3	$=$ $\bullet$ 4

Suggests we should replace the missing link in 4D and activate node 4:

$$\begin{array}{ccccccc} \bullet & - & \bullet & - & \bullet & = & \oplus \\ 1 & & 2 & & 3 & & 4 \end{array} \quad A_1^{+++} \quad (34)$$

Start Again From the 4D Light Cone

On the light cone, $i, j = 3, 4$, find

$$h_{ij}^{(0)} = h_{ji}^{(0)}, \quad h^{(0)i}{}_i = 0 \quad (2). \quad (35)$$

Introduce a 'dual' formulation

$$h_{i,j}^{(1)} = h_{j,i}^{(1)} \quad (3), \quad (36)$$

with

$$D_{ij}^{0|1} = h_{ij}^{(0)} + \epsilon_i{}^k h_{k,j}^{(1)} = 0. \quad (37)$$

$D_{[ij]}^{0|1} = 0$ gives

$$h^{(1)i}{}_i = 0 \quad (3 \rightarrow 2). \quad (38)$$

Start Again From the 4D Light Cone

On the light cone, $i, j = 3, 4$, find

$$h_{ij}^{(0)} = h_{ji}^{(0)}, \quad h^{(0)i}{}_i = 0 \quad (2). \quad (35)$$

Introduce a 'dual' formulation

$$h_{i,j}^{(1)} = h_{j,i}^{(1)} \quad (3), \quad (36)$$

with

$$D_{ij}^{0|1} = h_{ij}^{(0)} + \epsilon_i{}^k h_{k,j}^{(1)} = 0. \quad (37)$$

$D_{[ij]}^{0|1} = 0$ gives

$$h^{(1)i}{}_i = 0 \quad (3 \rightarrow 2). \quad (38)$$

Continue by appending complete blocks of two indices:

$$h_{ij}^{(0)}, \quad h_{i,j}^{(1)}, \quad h_{i_1 i_2, j, k}^{(2)}, \quad h_{i_1 i_2, j_1 j_2, k, l}^{(3)}, \quad \dots \quad (39)$$

All are constrained to describe the original two graviton degrees of freedom.

These Fields Again Reproduce the Borel Roots of Affine Algebra A_1^+

The Light-Cone Algebra is A_1^+

$$\bullet_3 = \oplus_4 \quad A_1^+$$

- Node 3 gives the $A_1 = \text{SL}(2)$ **gravity line**, with $\text{GL}(2)$'s K_j^i .
- Node 4 gives the symmetric tensor $R^{ij} = R^{ji}$.
Symmetric indices give the double link.
- First few generators are:

ℓ	A_1 representation	generator
0	3	K_j^i
1	3	R^{ij}
2	3	$R^{i_1 i_2 j, k}$
3	3	$R^{i_1 i_2 j_1 j_2, k, l}$

Restoring the two omitted directions $A_1 = \text{SL}(2) \rightarrow A_3 = \text{SL}(4)$:

$$\bullet_1 - \bullet_2 - \bullet_3 = \oplus_4 \quad A_1^{+++}$$

The Light-Cone Construction Has Reconstructed the Same A_1^{+++}

10D Theory on Doubled Space-Time

The 10D CBS graviton, two-form and dilaton arise from coset model

$$\frac{[\mathrm{SO}(10, 10) \otimes \mathrm{GL}(1)] \otimes_s \{P_a, Q^a\}}{\mathrm{SO}(10) \otimes \mathrm{SO}(10)}. \quad (40)$$

The fields

$$g_{\mu\nu}(x, y), \quad A_{\mu\nu}(x, y) \equiv B_{\mu\nu}(x, y), \quad \phi(x, y) \quad (41)$$

depend on doubled coordinates

$$z^\Pi = (x^\mu, y_\mu), \quad \partial_\Pi = (\partial_\mu, \bar{\partial}^\mu), \quad \bar{\partial}^\mu := \partial/\partial y_\mu. \quad (42)$$

The generalized vielbein is

$$E_\Pi^A = \begin{pmatrix} e_\mu^a & A_{\mu\rho} e_b^\rho \\ 0 & e_b^\nu \end{pmatrix}, \quad (43)$$

10D Theory on Doubled Space-Time

The 10D CBS graviton, two-form and dilaton arise from coset model

$$\frac{[\mathrm{SO}(10, 10) \otimes \mathrm{GL}(1)] \otimes_s \{P_a, Q^a\}}{\mathrm{SO}(10) \otimes \mathrm{SO}(10)}. \quad (40)$$

The fields

$$g_{\mu\nu}(x, y), \quad A_{\mu\nu}(x, y) \equiv B_{\mu\nu}(x, y), \quad \phi(x, y) \quad (41)$$

depend on doubled coordinates

$$z^\Pi = (x^\mu, y_\mu), \quad \partial_\Pi = (\partial_\mu, \bar{\partial}^\mu), \quad \bar{\partial}^\mu := \partial/\partial y_\mu. \quad (42)$$

The generalized vielbein is

$$E_\Pi^A = \begin{pmatrix} e_\mu^a & A_{\mu\rho} e_b^\rho \\ 0 & e_b^\nu \end{pmatrix}, \quad (43)$$

Gauge invariance is imposed via 'generalized diffeomorphism', and uses

$$\partial_\Pi \partial^\Pi F = 0 \quad \text{weak section condition,} \quad (44)$$

$$\partial_\Pi F \partial^\Pi G = 0 \quad \text{strong section condition,} \quad (45)$$

Latter eliminates dependence on doubled coordinate.

Does Gauge Invariance Really Require These Section Conditions

Linearized Alternative to the Section Conditions

[2] studies linearised doubled gauge transformations

$$\begin{aligned}\delta h_{\mu\nu} &= 2\partial_{(\mu}\xi_{\nu)} - 2\bar{\partial}_{(\mu}\Lambda_{\nu)}, \\ \delta A_{\mu\nu} &= 2\partial_{[\mu}\Lambda_{\nu]} - 2\bar{\partial}_{[\mu}\xi_{\nu]}, \quad \delta\phi = 2\bar{\partial}^\mu\Lambda_\mu.\end{aligned}\tag{46}$$

The two-form and graviton equations are schematically

$$\begin{aligned}E_{\mu\nu}^A &= 3\partial^\lambda\partial_{[\lambda}A_{\mu\nu]} + 2\bar{\partial}^\lambda\bar{\partial}_{[\lambda}A_{\mu\nu]} + 2\partial_{[\mu}\bar{\partial}^\lambda h_{|\lambda|\nu]} + \bar{\partial}_{[\mu}\partial^\lambda h_{|\lambda|\nu]} \\ &\quad + 2\partial_{[\mu}\bar{\partial}_{\nu]}h^\kappa{}_\kappa + 4\partial_{[\mu}\bar{\partial}_{\nu]}\phi = 0,\end{aligned}\tag{47}$$

$$\begin{aligned}E_{\mu\nu}^h &= \left(\partial^2 h_{\mu\nu} - 2\partial^\lambda\partial_{(\mu}h_{\nu)\lambda} - \eta_{\mu\nu}\partial^2 h^\kappa{}_\kappa + 2\partial_{(\mu}\bar{\partial}^\lambda A_{\lambda|\nu)}\right) \\ &\quad + \left(\bar{\partial}^2 h_{\mu\nu} - 2\bar{\partial}^\lambda\bar{\partial}_{(\mu}h_{\nu)\lambda} - \eta_{\mu\nu}\bar{\partial}^2 h^\kappa{}_\kappa + 2\bar{\partial}_{(\mu}\partial^\lambda A_{\lambda|\nu)}\right) + \text{mixed terms} = 0.\end{aligned}\tag{48}$$

Linearized Alternative to the Section Conditions

[2] studies linearised doubled gauge transformations

$$\begin{aligned}\delta h_{\mu\nu} &= 2\partial_{(\mu}\xi_{\nu)} - 2\bar{\partial}_{[\mu}\Lambda_{\nu]}, \\ \delta A_{\mu\nu} &= 2\partial_{[\mu}\Lambda_{\nu]} - 2\bar{\partial}_{[\mu}\xi_{\nu]}, \quad \delta\phi = 2\bar{\partial}^\mu\Lambda_\mu.\end{aligned}\tag{46}$$

The two-form and graviton equations are schematically

$$\begin{aligned}E_{\mu\nu}^A &= 3\partial^\lambda\partial_{[\lambda}A_{\mu\nu]} + 2\bar{\partial}^\lambda\bar{\partial}_{[\lambda}A_{\mu\nu]} + 2\partial_{[\mu}\bar{\partial}^\lambda h_{|\lambda|\nu]} + \bar{\partial}_{[\mu}\partial^\lambda h_{|\lambda|\nu]} \\ &\quad + 2\partial_{[\mu}\bar{\partial}_{\nu]}h^\kappa{}_\kappa + 4\partial_{[\mu}\bar{\partial}_{\nu]}\phi = 0,\end{aligned}\tag{47}$$

$$\begin{aligned}E_{\mu\nu}^h &= \left(\partial^2 h_{\mu\nu} - 2\partial^\lambda\partial_{(\mu}h_{\nu)\lambda} - \eta_{\mu\nu}\partial^2 h^\kappa{}_\kappa + 2\partial_{(\mu}\bar{\partial}^\lambda A_{\lambda|\nu)}\right) \\ &\quad + \left(\bar{\partial}^2 h_{\mu\nu} - 2\bar{\partial}^\lambda\bar{\partial}_{(\mu}h_{\nu)\lambda} - \eta_{\mu\nu}\bar{\partial}^2 h^\kappa{}_\kappa + 2\bar{\partial}_{(\mu}\partial^\lambda A_{\lambda|\nu)}\right) + \text{mixed terms} = 0.\end{aligned}\tag{48}$$

Their variations vanish provided the *parameters*, rather than the fields, obey [2]

$$\partial_\lambda\bar{\partial}^\lambda(\partial_{[\mu}\xi_{\nu]} - \bar{\partial}_{[\mu}\Lambda_{\nu]}) = 0,\tag{3.8}$$

$$\partial_\lambda\bar{\partial}^\lambda(\bar{\partial}_{(\mu}\Lambda_{\nu)} - \partial_{(\mu}\xi_{\nu)}) = 0,\tag{3.9}$$

$$\partial_\lambda\bar{\partial}^\lambda(\bar{\partial}^\nu\xi_\nu) = 0,\tag{3.10}$$

$$\partial_\lambda\bar{\partial}^\lambda(\partial^\nu\Lambda_\nu) = 0.\tag{3.11}$$

No section condition on the fields: $g_{\mu\nu}, A_{\mu\nu}, \phi$ may retain dependence on (x^μ, y_μ) .

Extended Coordinates Need Not Be Eliminated