

Quantum Gravity and Strings

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ON GENERALISED DISCRETE TORSION IN STRING THEORY

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Based on w.i.p. with **Giorgio Leone** and **Diego Perugini**

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WHAT IS DISCRETE TORSION?

[Vafa 1986, Vafa, Witten 1994]

*In $T^d/\mathbb{Z}_M \times \mathbb{Z}_N$ orbifold compactifications,
it is the freedom to combine independent modular orbits*

It is associated to a non-trivial flat B field taking values in $H^2(\Gamma, \mathbb{U}(1))$

It determines the co-homology of the associated (smooth) Calabi-Yau

A working example: $T^6/\mathbb{Z}_2 \times \mathbb{Z}_2$

$g : (+, -, -)$

$h : (-, -, +)$

$f : (-, +, -)$

$$\mathcal{Z} = \frac{1}{4} \sum_{\alpha, \beta} \beta \begin{array}{|c|} \hline \square \\ \hline \alpha \\ \hline \end{array} =$$

1	$\begin{array}{ c } \hline \square \\ \hline 1 \\ \hline \end{array}$	g	$\begin{array}{ c } \hline \triangle \\ \hline 1 \\ \hline \end{array}$	h	$\begin{array}{ c } \hline \star \\ \hline 1 \\ \hline \end{array}$	f	$\begin{array}{ c } \hline \star \\ \hline 1 \\ \hline \end{array}$
1	$\begin{array}{ c } \hline \triangle \\ \hline g \\ \hline \end{array}$	g	$\begin{array}{ c } \hline \triangle \\ \hline g \\ \hline \end{array}$	h	$\begin{array}{ c } \hline \star \\ \hline g \\ \hline \end{array}$	f	$\begin{array}{ c } \hline \star \\ \hline g \\ \hline \end{array}$
1	$\begin{array}{ c } \hline \star \\ \hline h \\ \hline \end{array}$	g	$\begin{array}{ c } \hline \star \\ \hline h \\ \hline \end{array}$	h	$\begin{array}{ c } \hline \star \\ \hline h \\ \hline \end{array}$	f	$\begin{array}{ c } \hline \star \\ \hline h \\ \hline \end{array}$
1	$\begin{array}{ c } \hline \star \\ \hline f \\ \hline \end{array}$	g	$\begin{array}{ c } \hline \star \\ \hline f \\ \hline \end{array}$	h	$\begin{array}{ c } \hline \star \\ \hline f \\ \hline \end{array}$	f	$\begin{array}{ c } \hline \star \\ \hline f \\ \hline \end{array}$

.....

$S : \quad \beta \begin{array}{|c|} \hline \square \\ \hline \alpha \\ \hline \end{array} \rightarrow \alpha^{-1} \begin{array}{|c|} \hline \square \\ \hline \beta \\ \hline \end{array}$

$T : \quad \beta \begin{array}{|c|} \hline \square \\ \hline \alpha \\ \hline \end{array} \rightarrow \alpha \beta \begin{array}{|c|} \hline \square \\ \hline \alpha \\ \hline \end{array}$

For instance, in the g -twisted sector

$$\mathcal{Z}_g = \frac{1}{4} \left[1 \square_g + g \square_g + \epsilon \left(h \square_g + gh \square_g \right) \right]$$

$$\epsilon = +1 \swarrow$$

$$(h_{11}, h_{21})_g = (16, 0)$$

blow up

$$\searrow \epsilon = -1$$

$$(h_{11}, h_{21})_g = (0, 16)$$

deformation

Altogether, $(h_{11}, h_{21}) = (51, 3)$

$$\epsilon = +1$$

$(h_{11}, h_{21}) = (3, 51)$

$$\epsilon = -1$$

WHAT IS GENERALISED DISCRETE TORSION?

[Gaberdiel, Kaste 2004]

*It is the freedom to associate a different
discrete torsion at each fixed locus*

(A number is trivially modular invariant!)

$$h \boxed{}_g = 16$$

$$\mathcal{Z}_g = \frac{1}{4} \sum_{i=1}^{16} \left[1 \boxed{}_g + g \boxed{}_g + \epsilon_i \left(h \boxed{}_g + gh \boxed{}_g \right) \right]$$

$$\mathcal{H}_g = \bigoplus_{i=1}^{16} \mathcal{H}_g^{(i)}$$

Calabi-Yau 3-folds with $(h_{11}, h_{12}) = (51 - 3\ell, 3 + 3\ell)$

$(\ell = 0, \dots, 16)$

A SIMILAR STORY HOLDS FOR THE G_2 MANIFOLD

[Gaberdiel, Kaste 2004]

$$G_2 \sim T^7 / \mathbb{Z}^3 \text{ with}$$

$$\alpha = (-, -, -, -, +, +, + | 0, 0, 0, 0, 0, 0, 0) ,$$

$$\beta = (-, -, +, +, -, -, + | 0, 1/2, 0, 0, 0, 0, 0) ,$$

$$\gamma = (-, +, -, +, -, +, - | 1/2, 0, 0, 0, 0, 0, 0) ,$$

Generalised discrete torsion describes families of G_2 manifolds with

$$(b_0, \dots, b_7) = (1, 0, 8 + \ell, 47 - \ell, 47 - \ell, 8 + \ell, 0, 1) \quad (\ell = 0, \dots, 8)$$

All this looks plausible but ...

A number is of course modular invariant,
but modular invariance is much trickier

In the twisted sector, the vacuum is dressed with twist fields

$$\sigma_\alpha \tilde{\sigma}_\beta |0, \tilde{0}\rangle \quad \text{and} \quad \sigma_{\dot{\alpha}} \tilde{\sigma}_\beta |0, \tilde{0}\rangle ,$$

and these states carry different charges

The (plain) partition function does not
carry enough information

$$\hat{\mathcal{Z}} \left[\begin{smallmatrix} \alpha \\ 1 \end{smallmatrix} \right] \sim \left| \frac{\eta^2}{\vartheta_4^2} \right|^2 \Lambda_{2,2}^{(i)} \simeq 1 + 4 q^{1/2} + 4 \bar{q}^{1/2} + 16 (q \bar{q})^{1/2} + 12 q + 12 \bar{q} + \dots ,$$

$$\hat{\mathcal{Z}} \left[\begin{smallmatrix} \alpha \\ \alpha \end{smallmatrix} \right] \sim \left| \frac{\eta^2}{\vartheta_3^2} \right|^2 \Lambda_{2,2}^{(i)} \simeq 1 - 4 q^{1/2} - 4 \bar{q}^{1/2} + 16 (q \bar{q})^{1/2} + 12 q + 12 \bar{q} + \dots ,$$

$$\hat{\mathcal{Z}} \left[\begin{smallmatrix} \alpha \\ \beta \end{smallmatrix} \right] \sim \left| \frac{2\eta^3}{\vartheta_2 \vartheta_3 \vartheta_4} \right|^2 = 1 ,$$

What is the twisted vacuum “1”?

$$\sigma_\alpha \tilde{\sigma}_\beta |0, \tilde{0}\rangle , \quad \sigma_{\dot{\alpha}} \tilde{\sigma}_\beta |0, \tilde{0}\rangle , \quad \dots$$

How to overcome this problem?

Turn on chemical potentials or sit at a
special point in moduli space

The CFT becomes rational and the partition function can be written in terms of characters which carry a lot more information

These RCFT's can be *continuously* deformed *via* marginal deformations, so the RCFT analysis is fully general

The SO(12) point

Start from the toroidal compactification

$$\mathcal{Z} = |O_{12}|^2 + |V_{12}|^2 + |S_{12}|^2 + |C_{12}|^2$$

the orbifold action breaks

$$\mathrm{SO}(12) \rightarrow \mathrm{SO}(4) \times \mathrm{SO}(4) \times \mathrm{SO}(4)$$

$$g : (+, -, -)$$

$$h : (-, -, +)$$

$$f : (-, +, -)$$

The ground states in the twisted sectors are

$$\mathcal{Z}\left[\begin{smallmatrix} g \\ 1 \end{smallmatrix}\right] = |S_4 O_4 O_4 + \dots|^2 + |C_4 O_4 O_4 + \dots|^2$$

$$\sigma_\alpha \tilde{\sigma}_\beta |0, \tilde{0}\rangle,$$

$$\sigma_{\dot{\alpha}} \tilde{\sigma}_{\dot{\beta}} |0, \tilde{0}\rangle,$$

$$\mathcal{Z}\left[\begin{smallmatrix} h \\ 1 \end{smallmatrix}\right] = |O_4 O_4 S_4 + \dots|^2 + |O_4 O_4 C_4 + \dots|^2$$

[This orbifold has only 8 (and not 16) fixed tori
per twisted sector. They carry a non-trivial
representation of the residual $\text{SO}(4)^3$]

$$g : (+, -, -)$$

$$h : (-, -, +)$$

$$f : (-, +, -)$$

The role of (generalised) discrete torsion

$$\mathcal{Z}\left[\begin{smallmatrix} g \\ 1 \end{smallmatrix}\right] = |S_4 O_4 O_4 + \dots|^2 + |C_4 O_4 O_4 + \dots|^2$$

$$\sigma_\alpha \tilde{\sigma}_\beta |0, \tilde{0}\rangle,$$

$$\sigma_{\dot{\alpha}} \tilde{\sigma}_{\dot{\beta}} |0, \tilde{0}\rangle,$$

$$\mathcal{Z}\left[\begin{smallmatrix} g \\ h \end{smallmatrix}\right] = \epsilon_1 |S_4 O_4 O_4 + \dots|^2 + \epsilon_2 |C_4 O_4 O_4 + \dots|^2$$

No DT:	$(\epsilon_1, \epsilon_2) = (+1, +1)$	$\Rightarrow$	$(h_{11}, h_{21})_g = (8, 0)$	full blow up
DT:	$(\epsilon_1, \epsilon_2) = (-1, -1)$	$\Rightarrow$	$(h_{11}, h_{21})_g = (0, 8)$	full deformation
GDT:	$(\epsilon_1, \epsilon_2) = (+1, -1)$	$\Rightarrow$	$(h_{11}, h_{21})_g = (4, 4)$	blow up and deformation

[C.A., Leone, Perugini 2026]

The choice of generalised discrete torsion in the g -twisted sector
destroys particle interpretation in the other twisted sectors!!

$$S \cdot \mathcal{Z} \left[\begin{smallmatrix} g \\ h \end{smallmatrix} \right] = \mathcal{Z} \left[\begin{smallmatrix} h \\ g \end{smallmatrix} \right] = (O_4 O_4 S_4 + \dots)(\bar{O}_4 \bar{O}_4 \bar{C}_4 \dots) \\
+ (O_4 O_4 C_4 + \dots)(\bar{O}_4 \bar{O}_4 \bar{S}_4 + \dots)$$

$$\sigma_\alpha \tilde{\sigma}_{\dot{\beta}} |0, \tilde{0}\rangle , \\
\sigma_{\dot{\alpha}} \tilde{\sigma}_\beta |0, \tilde{0}\rangle ,$$

is *incompatible* with the structure of the h -twisted sector

$$\mathcal{Z} \left[\begin{smallmatrix} h \\ 1 \end{smallmatrix} \right] = |O_4 O_4 S_4 + \dots|^2 + |O_4 O_4 C_4 + \dots|^2$$

$$\sigma_\alpha \tilde{\sigma}_\beta |0, \tilde{0}\rangle , \\
\sigma_{\dot{\alpha}} \tilde{\sigma}_{\dot{\beta}} |0, \tilde{0}\rangle ,$$

[C.A., Leone, Perugini 2026]

Similar results for other special points and for the G_2 manifold

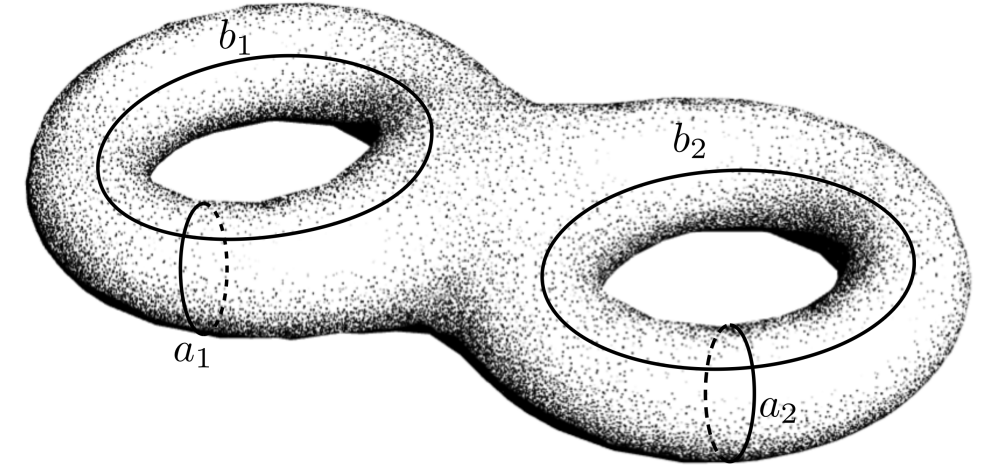
1	1	α 1	β 1	γ 1	$\alpha\beta$ 1	$\alpha\gamma$ 1	$\beta\gamma$ 1	$\alpha\beta\gamma$ 1
1	α	α α						
1	β		β β					
1	γ			γ γ	$\alpha\beta$ γ			$\alpha\beta\gamma$ γ
1	$\alpha\beta$			γ $\alpha\beta$	$\alpha\beta$ $\alpha\beta$			$\alpha\beta\gamma$ $\alpha\beta$
1	$\alpha\gamma$					$\alpha\gamma$ $\alpha\gamma$		
1	$\beta\gamma$						$\beta\gamma$ $\beta\gamma$	
1	$\alpha\beta\gamma$			γ $\alpha\beta\gamma$	$\alpha\beta$ $\alpha\beta\gamma$			$\alpha\beta\gamma$ $\alpha\beta\gamma$

$$(b_2, b_3) = (8, 47), (16, 39)$$

These sectors are massive
and thus do not determine
(classical) cohomology

[C.A., Leone, Perugini 2026]

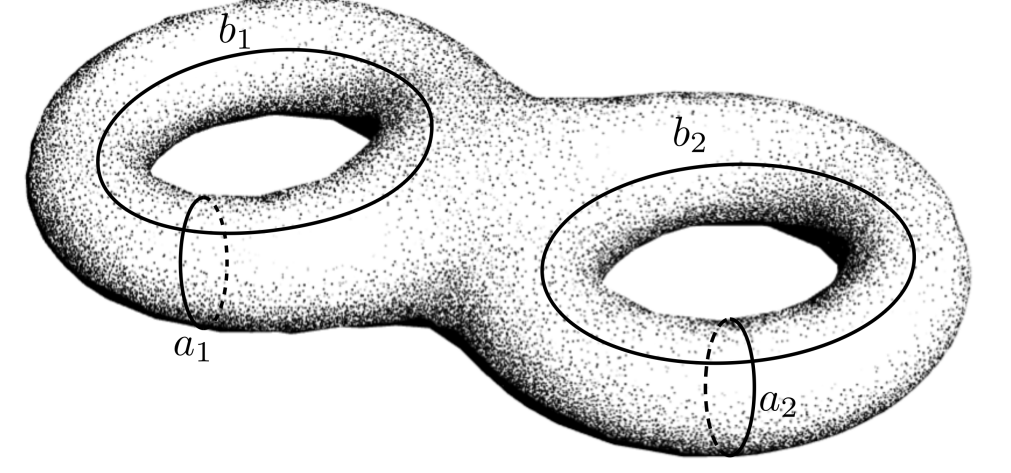
Also, generalised discrete torsion is incompatible with two-loop modular invariance and factorisation



$$\begin{aligned} \mathcal{Z}_2 = & \frac{1}{16} \left[\prod_{v=1,2,3} \Lambda_{2,2}^{(v)}(\Omega) + \sum_{v=1,2,3} \Lambda_{2,2}^{(v)}(\Omega) \sum_{i=1}^{15} \left| \frac{\theta[\delta_i] \theta[\delta_i + \zeta_i]}{\mathcal{Z}_0(\Omega)^2} \frac{\eta(\pi_i)^2}{\vartheta_3(\pi_i)^2} \right|^4 \prod_{u \neq v} \Lambda_{2,2}^{(u)}(\pi_i) \right. \\ & + \sum_{\substack{i,j \\ i \neq j}} \left| \frac{\theta[\delta_i] \theta[\delta_i + \zeta_i]}{\mathcal{Z}_0(\Omega)^2} \frac{\eta(\pi_i)^2}{\vartheta_3(\pi_i)^2} \right|^2 \Lambda_{2,2}^{(1)}(\pi_i) \left| \frac{\theta[\delta_j] \theta[\delta_j + \zeta_j]}{\mathcal{Z}_0(\Omega)^2} \frac{\eta(\pi_j)^2}{\vartheta_3(\pi_j)^2} \right|^2 \Lambda_{2,2}^{(3)}(\pi_j) \\ & \left. \times \left| \frac{\theta[\delta_{i+j}] \theta[\delta_{i+j} + \zeta_i + \zeta_j]}{\mathcal{Z}_0(\Omega)^2} \frac{\eta(\pi_{i+j})^2}{\vartheta_3(\pi_{i+j})^2} \right|^2 \Lambda_{2,2}^{(2)}(\pi_{i+j}) \right]. \end{aligned}$$

[C.A., Leone, Perugini 2026]

The genus-two partition function involves six independent modular orbits which factorise as



$$\mathcal{O}_1 \rightarrow \mathcal{Z} \begin{bmatrix} 1 \\ 1 \end{bmatrix} (\tau_1) \mathcal{Z} \begin{bmatrix} 1 \\ 1 \end{bmatrix} (\tau_2),$$

$$\mathcal{O}_2 \rightarrow \mathcal{Z} \begin{bmatrix} 1 \\ 1 \end{bmatrix} (\tau_1) \mathcal{Z}_g(\tau_2) + \mathcal{Z}_g(\tau_1) \mathcal{Z} \begin{bmatrix} 1 \\ 1 \end{bmatrix} (\tau_2) + \mathcal{Z}_g(\tau_1) \mathcal{Z}_g(\tau_2),$$

$$\mathcal{O}_3 \rightarrow \mathcal{Z} \begin{bmatrix} 1 \\ 1 \end{bmatrix} (\tau_1) \mathcal{Z}_h(\tau_2) + \mathcal{Z}_h(\tau_1) \mathcal{Z} \begin{bmatrix} 1 \\ 1 \end{bmatrix} (\tau_2) + \mathcal{Z}_h(\tau_1) \mathcal{Z}_h(\tau_2),$$

$$\mathcal{O}_4 \rightarrow \mathcal{Z} \begin{bmatrix} 1 \\ 1 \end{bmatrix} (\tau_1) \mathcal{Z}_f(\tau_2) + \mathcal{Z}_f(\tau_1) \mathcal{Z} \begin{bmatrix} 1 \\ 1 \end{bmatrix} (\tau_2) + \mathcal{Z}_f(\tau_1) \mathcal{Z}_f(\tau_2),$$

$$\mathcal{O}_5 \rightarrow \sum_{\substack{\alpha, \beta = g, h, f \\ \alpha \neq \beta}} \mathcal{Z}_\alpha(\tau_1) \mathcal{Z}_\beta(\tau_2) + \mathcal{Z}_{g, h}(\tau_1) \mathcal{Z}_{g, h}(\tau_2),$$

$$\mathcal{O}_6 \rightarrow \mathcal{Z}_{g, h}(\tau_1) \left(\mathcal{Z} \begin{bmatrix} 1 \\ 1 \end{bmatrix} (\tau_2) + \sum_{\alpha = g, h, f} \mathcal{Z}_\alpha(\tau_2) \right) + \left(\mathcal{Z} \begin{bmatrix} 1 \\ 1 \end{bmatrix} (\tau_1) + \sum_{\alpha = g, h, f} \mathcal{Z}_\alpha(\tau_1) \right) \mathcal{Z}_{g, h}(\tau_2).$$

$$\Omega = \begin{pmatrix} \tau_1 & t \\ t & \tau_2 \end{pmatrix}$$

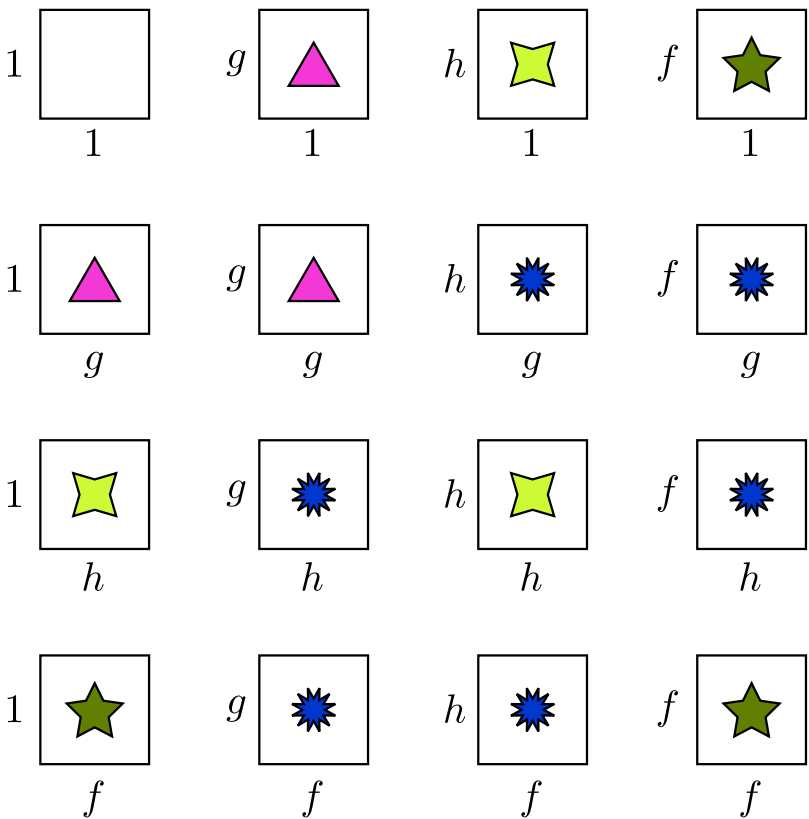
$$t \rightarrow 0$$

In particular, from the factorisation

$$\mathcal{O}_5 \rightarrow \sum_{\substack{\alpha, \beta = g, h, f \\ \alpha \neq \beta}} \mathcal{Z}_\alpha(\tau_1) \mathcal{Z}_\beta(\tau_2) + \mathcal{Z}_{g,h}(\tau_1) \mathcal{Z}_{g,h}(\tau_2)$$

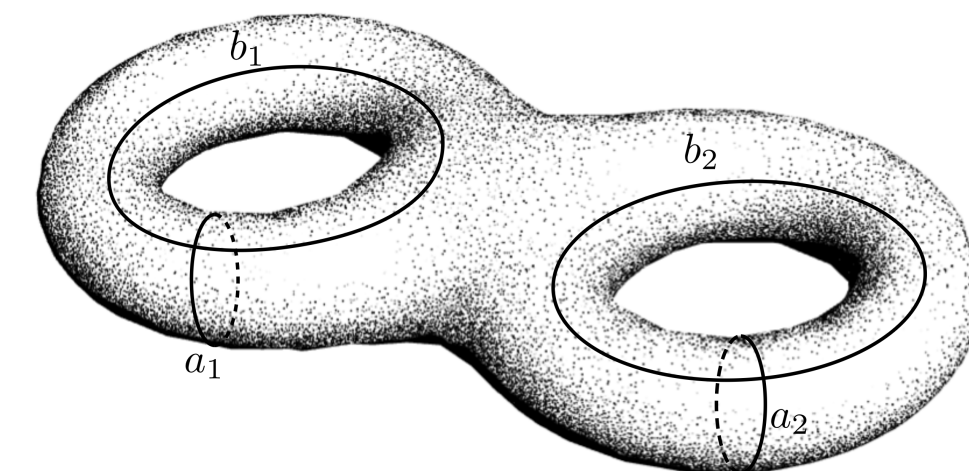
consistency implies

$$\epsilon_i \epsilon_j = 1$$



[C.A., Leone, Perugini 2026]

Also, generalised discrete torsion is incompatible with
two-loop modular invariance and factorisation



$$\epsilon(g_1, h_1, i; g_2, h_2, j) = \epsilon(g_1 h_2 h_1^{-1}, h_1, i'; g_2 h_1 h_2^{-1}, h_2, j')$$

Two-loop modular invariance

$$\epsilon(g_1, h_1, i; g_2, h_2, j) = \epsilon(g_1, h_1, i) \epsilon(g_2, h_2, j)$$

Factorisation

Combining the two conditions

$$\epsilon(g, g, i; f, f, j) = \epsilon(g, g, i) \epsilon(f, f, j) = 1 = \epsilon(f, g, i'; g, f, j') = \epsilon(f, g, i') \epsilon(g, f, j'),$$

$$\Rightarrow \epsilon(f, g, i') = \epsilon(g, f, j')$$

Topological deformations take value in the equivariant
cohomology of target space

[Boyle Smith, Tachikawa 2026]

These corresponds to standard discrete torsion, flat untwisted
 B fields and/or Scherk-Schwarz deformations, but not the
generalised discrete torsion of Gaberdiel and Kaste

[C.A., Leone, Perugini 2026]

CONCLUSION

No generalised discrete torsion in string theory

OUTLOOK

*In classical algebraic geometry it seems possible to build many
desingularisations of orbifolds.*

[Joyce 1998]

*Why this is not possible in String Theory?
How to implement them in String Theory?*