

AXION-SCALAR DYNAMICS & NON-GEODESIC DISTANCES

Workshop on Quantum Gravity and Strings, Corfu

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2510.XXXX with Thomas Grimm, Damian van de Heisteeg

PART 1

DYNAMICS & THE DISTANCE CONJECTURE

MOTIVATION – THE DISTANCE CONJECTURE

Swampland Distance Conjecture (SDC)

*Infinite distance points
in moduli space*



*towers of
light states*

[Ooguri, Vafa '06]

[Ooguri, Palti, Shiu, Vafa '19]

Invalidate EFT

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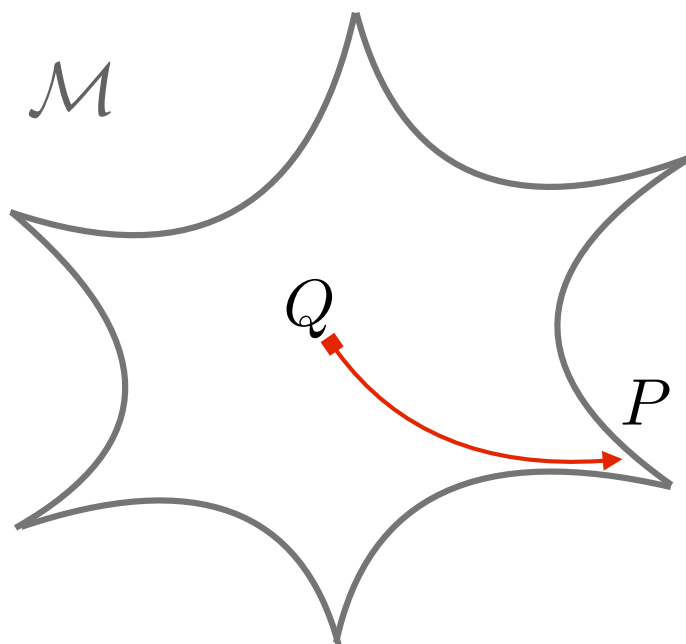
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*towers of
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Invalidate EFT



$$m(P) = m(Q)e^{-\lambda d(P,Q)}$$



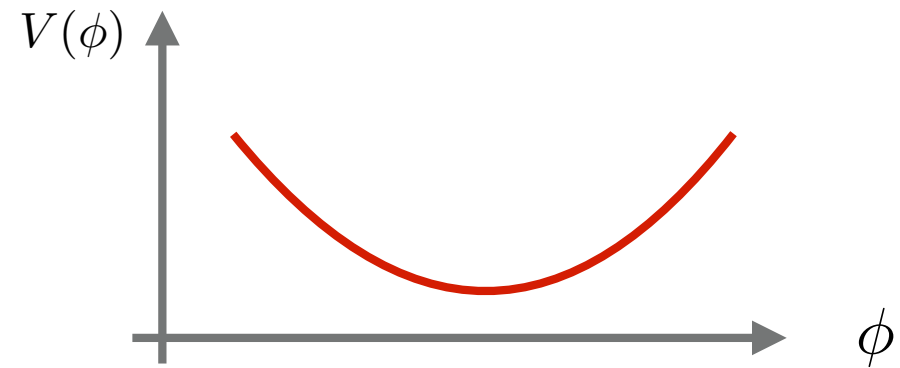
geodesic distance

*Best established for **exact** moduli spaces*

SDC WITH A POTENTIAL

*Moduli **must** be stabilised*

*SDC still thought to hold,
far less evidence*



[Klaewer, Palti '16] [Calderon, Uranga, Valenzuela '20] + ...

SDC WITH A POTENTIAL

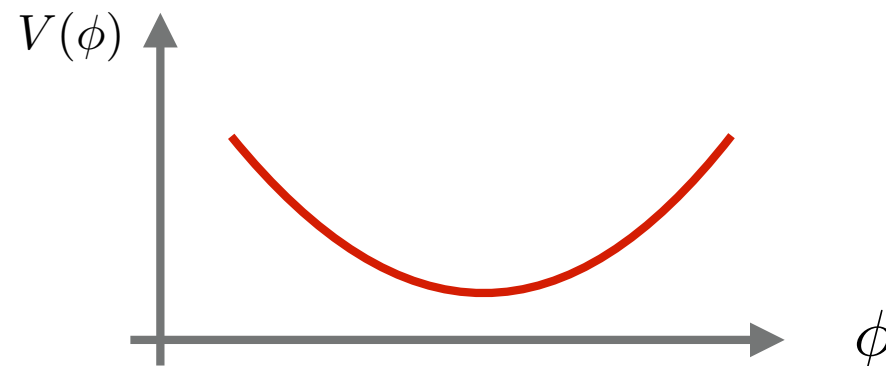
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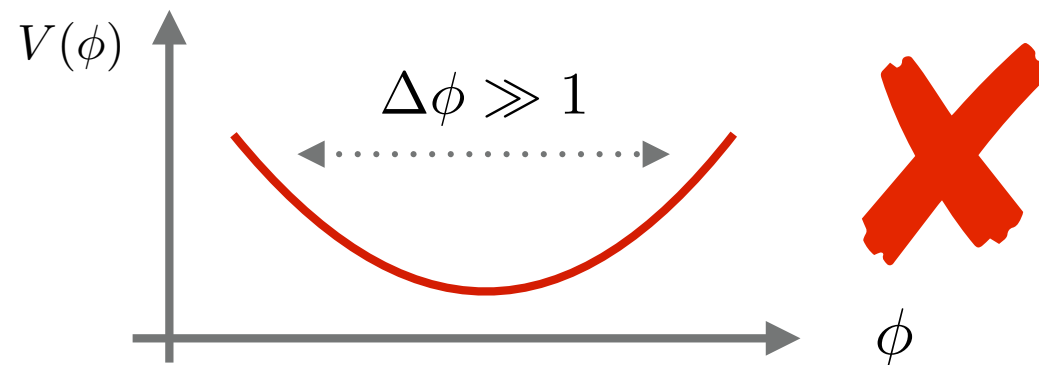
*Typical application:
Rule out **large field inflation***

*Compact directions (axions) important:
e.g. monodromy inflation*

*More recent:
generalised notion of distance, including V ?*



[Klaewer, Palti '16] [Calderon, Uranga, Valenzuela '20] + ...



[Tonioni, Van Riet '24]

[Montero, Mohseini, Vafa, Valenzuela '24]

DYNAMICS

Related issue: SDC applies to adiabatic field variations

$$V = 0$$

$$V \neq 0$$

adiabatic: $\dot{\phi} \rightarrow 0$

geodesic trajectories

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(space)time dependence $\dot{\phi} \neq 0$

geodesic trajectories

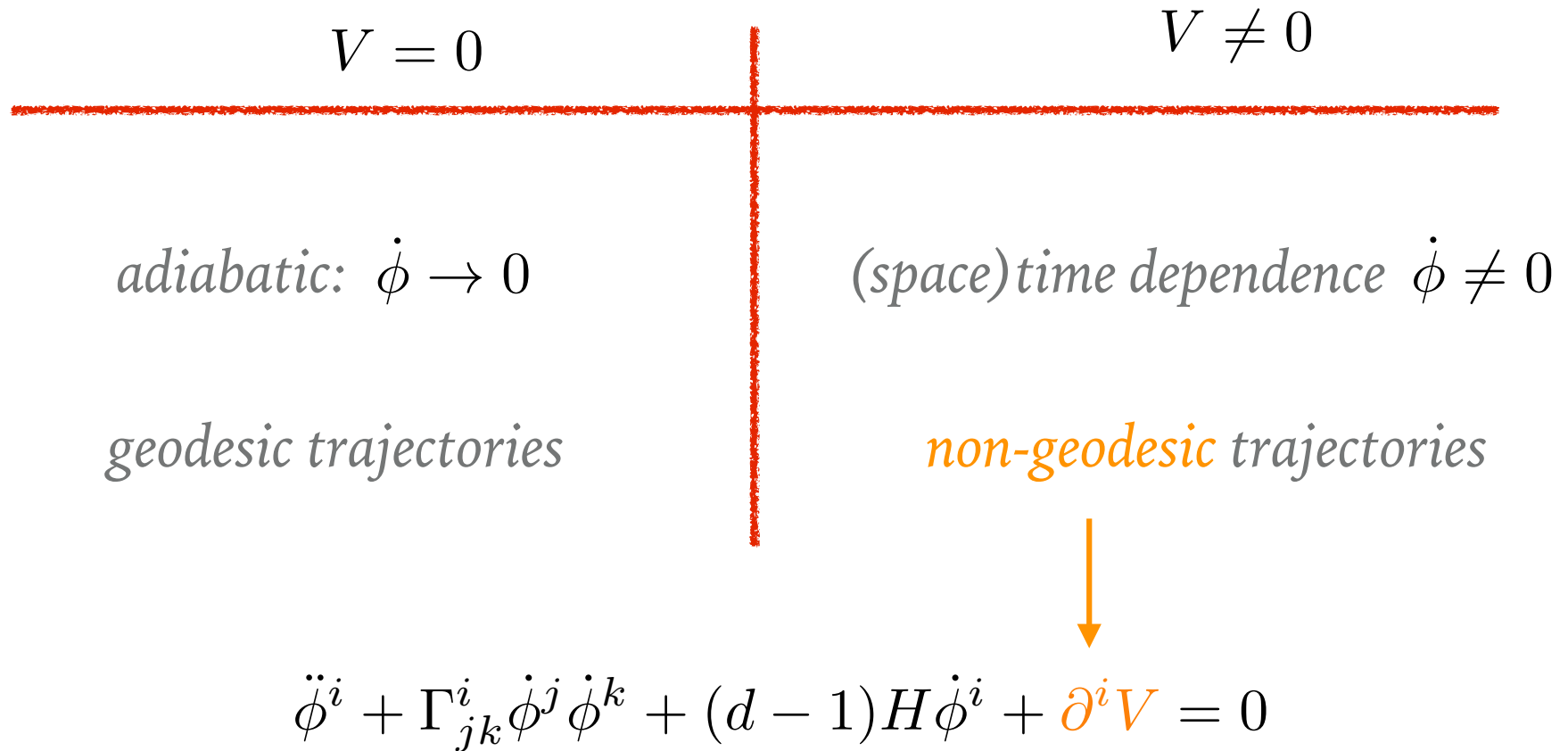
non-geodesic trajectories



$$\ddot{\phi}^i + \Gamma_{jk}^i \dot{\phi}^j \dot{\phi}^k + (d-1)H\dot{\phi}^i + \partial^i V = 0$$

DYNAMICS

Related issue: SDC applies to adiabatic field variations



What becomes of the SDC in a cosmological setting?

Some (sparse) comments appear in [Conlon,FR '22][Tonioni,Tran,Shiu' 23][Tonioni, Van Riet '24]

Similar issues for species scale discussed in [Bedroya, Lu, Steinhardt '24][Bedroya, Lee, Steinhardt '25]

A POSSIBLE GENERALISATION*

Question:

*For trajectories approaching the boundary of moduli space, do towers of states become exponentially light in the **dynamical distance** ?*

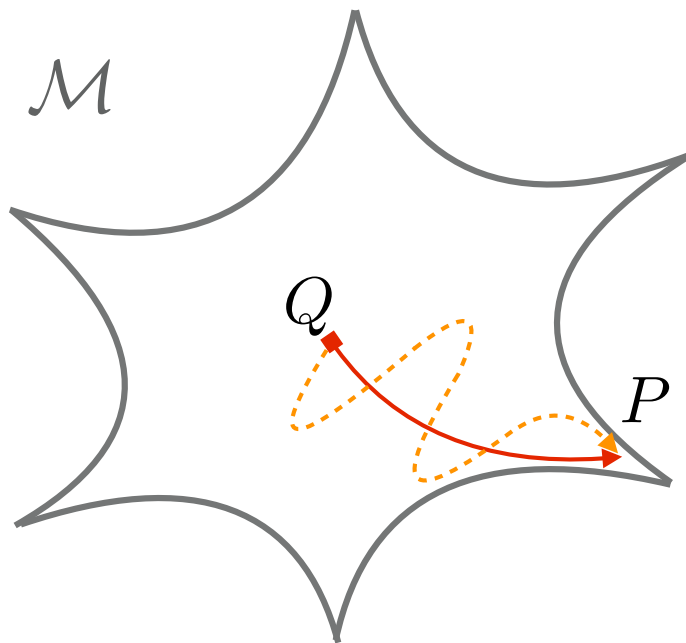
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$$m(P) = m(Q)e^{-\lambda\Delta(P,Q)}$$



$$\Delta = \int_{t_1}^{t_2} d\tau \sqrt{G_{I\bar{J}} \dot{\Phi}^I \dot{\Phi}^{\bar{J}}}$$

along trajectory

From usual SDC, equivalent to relationship between length of trajectories and geodesics

PART 2

CLASSIFICATION OF 1-MODULUS ASYMPTOTIC COSMOLOGIES

SETTING

Cosmology of asymptotic limits in type F-theory flux compactifications

[See also Calderon-Infante, Ruiz, Valenzuela '22, FR '23]

$$S = \frac{M_{P,d}^2}{2} \int d^d x \sqrt{-g} \left\{ \mathcal{R} + \frac{1}{2} G_{IJ} \partial_\mu \Phi^I \partial^\mu \bar{\Phi}^{\bar{J}} + V(\Phi, \bar{\Phi}) \right\}$$

Complex Structure moduli

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Complex Structure moduli

EFTs classified with Asymptotic Hodge Theory

[Grana, Grimm, Herraez, Monnee, Plauschinn, Palti, Lanza, Li, Schlechter, Valenzuela, van de Heisteeg... '19-24]

$$V \sim \sum_{\ell \in \mathcal{E}} \left(\frac{s^1}{s^2} \right)^{\ell_1 - 4} \cdots \left(\frac{s^{\hat{n}-1}}{s^{\hat{n}}} \right)^{\ell_{\hat{n}-1} - 4} (s^{\hat{n}})^{\ell_{\hat{n}} - 4} \|\rho_\ell(G_4, a_i)\|_\infty^2$$

[Bonus]

Complete classification of F-theory scalar potentials with $h^{3,1} = 1$

$$\Phi = s + ia$$

Including leading non-perturbative corrections

EQUATIONS OF MOTION

Solve coupled EOMs of scalar fields, on FLRW background

$$\ddot{\phi}^i + \Gamma_{jk}^i \dot{\phi}^j \dot{\phi}^k + (d-1)H\dot{\phi}^i + \partial^i V = 0$$

$$\frac{(d-1)(d-2)}{2}H^2 = \frac{1}{2}G_{ij}\partial_\mu\phi^i\partial^\mu\phi^j - V(\phi^i)$$

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$$G_{ij} = \frac{C}{s^2}\delta_{ij}$$

Hyperbolic metric

$$V(s, a) = \frac{1}{s^\lambda} \sum_{n=0}^N \frac{1}{s^n} P_n\left(\frac{a}{s}\right)$$

Polynomials

Flux scalar potential, positive definite

Complete classification for

$$V \geq 0, \quad V(a, s) \rightarrow 0$$

$s \rightarrow +\infty$

DYNAMICAL SYSTEM FORMULATION

$$\textit{Simpler case} \quad V(s, a) = \frac{P_n(\textcolor{red}{w})}{s^\lambda} \quad \left(\quad V(s, a) = \frac{1}{s^\lambda} \sum_{i=0}^n \frac{P_i(\textcolor{red}{w})}{s^i} \quad \right)$$

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$$\textcolor{brown}{x} = \frac{\dot{s}}{\alpha H s} \quad \textcolor{brown}{y} = \frac{\dot{a}}{\alpha H s} \quad \textcolor{red}{w} = \frac{a}{s} \quad x^2, y^2 \text{ normalized kinetic terms}$$

$$\begin{cases} \frac{d\textcolor{brown}{x}}{dN} = -\alpha \textcolor{brown}{y}^2 - (1 - \textcolor{brown}{x}^2 - \textcolor{brown}{y}^2) \left[(d-1)\textcolor{brown}{x} - \frac{\alpha}{2} \left(\lambda + \frac{\textcolor{red}{w} \partial_{\textcolor{red}{w}} P_n(\textcolor{red}{w})}{P_n(\textcolor{red}{w})} \right) \right] \\ \frac{d\textcolor{brown}{y}}{dN} = \alpha \textcolor{brown}{x} \textcolor{brown}{y} - (1 - \textcolor{brown}{x}^2 - \textcolor{brown}{y}^2) \left[(d-1)\textcolor{brown}{y} + \frac{\alpha}{2} \frac{\partial_{\textcolor{red}{w}} P_n(\textcolor{red}{w})}{P_n(\textcolor{red}{w})} \right] \\ \frac{d\textcolor{red}{w}}{dN} = \alpha (\textcolor{brown}{y} - \textcolor{red}{w} \textcolor{brown}{x}) \end{cases}$$

[Copeland, Liddle, Wands '97] [Russo, Townsend '06-'19] [(Brinkmann), Cicoli, Dibitetto, Pedro '20-'22] [FR '23]
[Tonioni, Tran, Shiu '23-'24] [Andriot, Parameswaran, Tsimpis, Wrase, Zavala '24] [Licciardello, Rahimy, Zavala '25] + ...

SCHEMATIC CLASSIFICATION

Asymptotic behaviour



1) Kination

SCHEMATIC CLASSIFICATION

Asymptotic behaviour



1) *Kination*



New variable:

$$T = x + yw \sim \frac{1}{H^2} \frac{s\dot{s} + a\dot{a}}{s^2}$$

$$V(s, a) = \frac{P_n(w)}{s^\lambda}$$



$$T \rightarrow \frac{\alpha\lambda}{2(d-1)}$$

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$$T \rightarrow \frac{\alpha(\lambda + i_{\min})}{2(d-1)}$$

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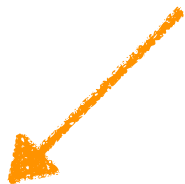


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2) *Fixed point - easy*

$$w \rightarrow w_0$$

|

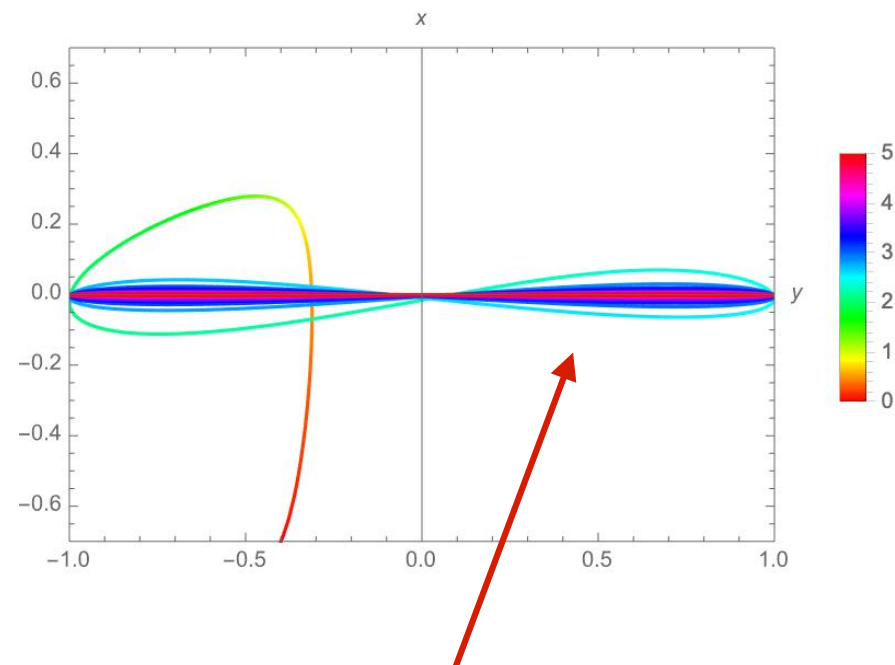
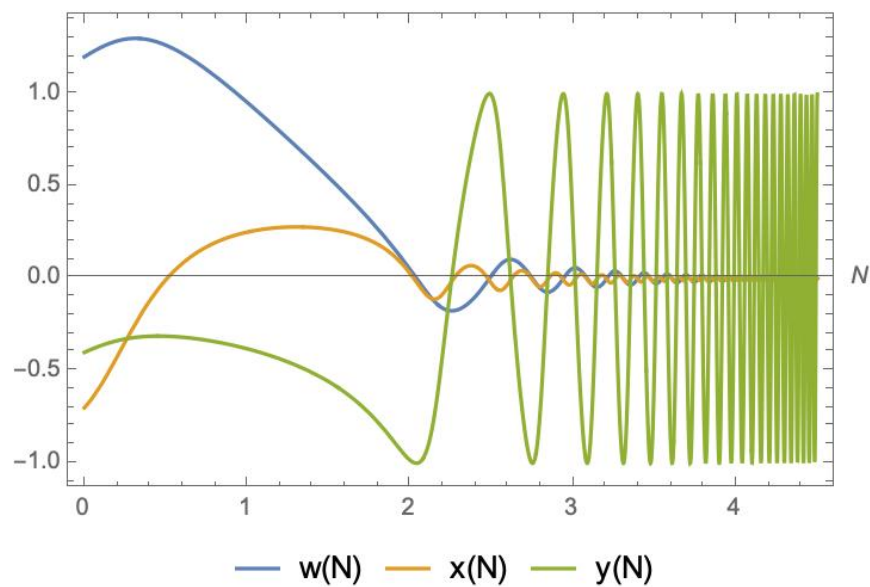
$$P_0(w_0) = 0$$



3) *New oscillating solutions*

OSCILLATING SOLUTIONS

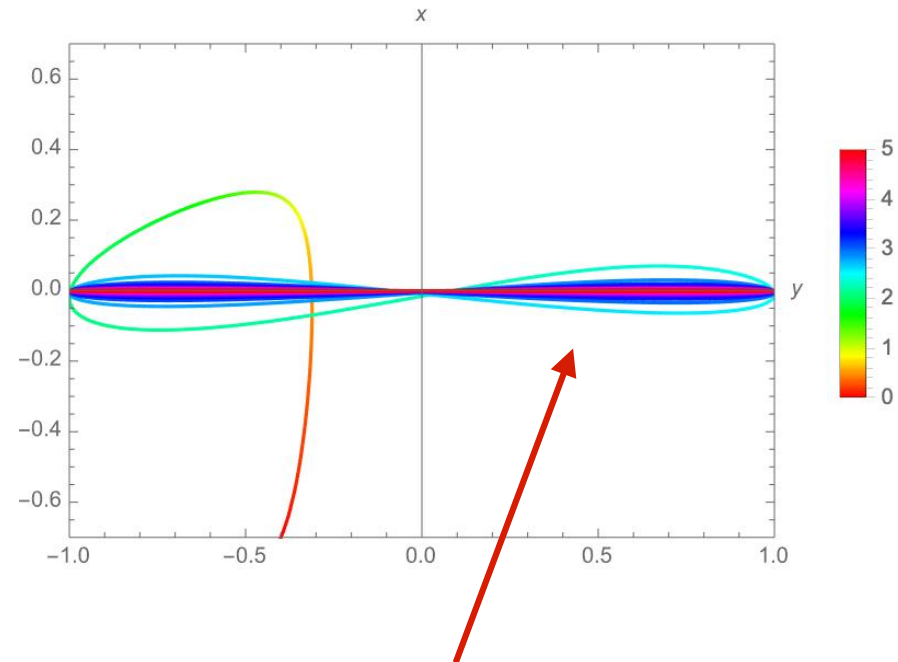
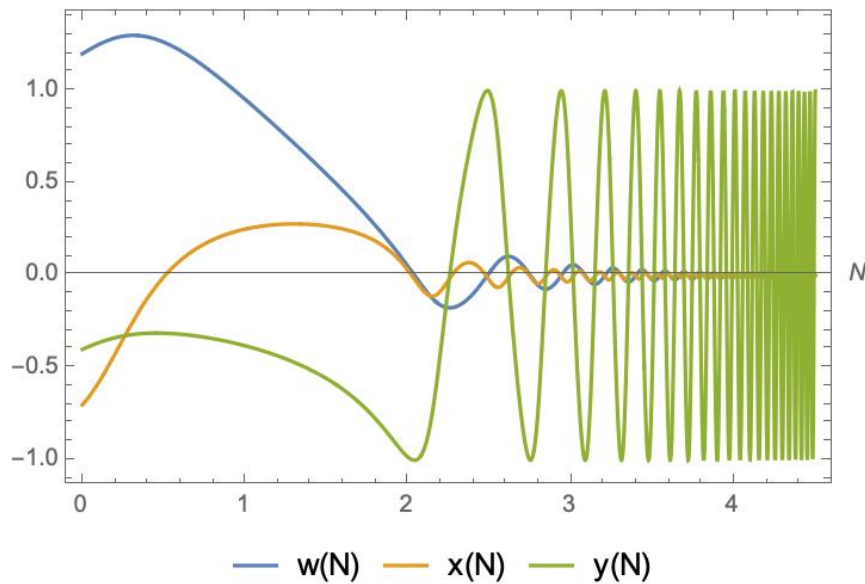
Potential of the form $P(w) = f^2(w - w_0)^{2m}$



Fixed line

OSCILLATING SOLUTIONS

Potential of the form $P(w) = f^2(w - w_0)^{2m}$



Fixed line

Asymptotic analytical solution: generalised trig. functions

E.g. $S \equiv x^2 + y^2 \sim C_1 \sin_{2,2m} (e^{-\gamma N}) + C_2$

TECHNIQUES FOR DYNAMICAL SYSTEMS

Autonomous system

$$\dot{x} = f(x)$$

$$t \rightarrow +\infty \quad ?$$

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Deduce local (in)stability from linearisation

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Lyapunov-like theorems:

Global

Find Lyapunov function $\mathcal{L}(x(t))$ s.t. $\dot{\mathcal{L}}(x(t)) \leq 0$ everywhere

If $\mathcal{L}(x(t)) > 0, \mathcal{L}(\bar{x}) = 0$  $x \rightarrow \bar{x}$

*On compact set $x \rightarrow \left\{ y \quad | \quad \dot{\mathcal{L}}(y) = 0 \right\}$ *Not only points!**

Trivial example: $\dot{x} = -x, \quad \mathcal{L} = x^2 \quad \dot{\mathcal{L}} = 2x\dot{x} = -x^2 \leq 0$

IMPLICATIONS FOR THE DISTANCE CONJECTURE

Distance conjecture tower:

$$m_t \sim s^{-\alpha} \stackrel{?}{\sim} f(\Delta)$$

How does Δ scale with s ?

$$\Delta = \sqrt{C} \int_{s(P)}^{s(Q)} \frac{ds}{s} \sqrt{1 + \left(\frac{da}{ds} \right)^2}$$

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$$\frac{y^2}{x^2}$$

bounded



$$m_t \sim \Delta^{-\beta}$$

Kination:



Fixed points:



Oscillating solutions:



if $w \rightarrow 0$

$$P(w) = w^{2m} Q(w) \quad \text{leads to violation}$$



A COUNTER-EXAMPLE?

LCS point (type $V_{1,1}$): $P(w) = 3g_3^2 w^2 (1 + w^2)$ $\lambda = 0$

Apparent *counterexample* to “dynamical” distance conjecture

A COUNTER-EXAMPLE, AND HOW TO RESOLVE IT

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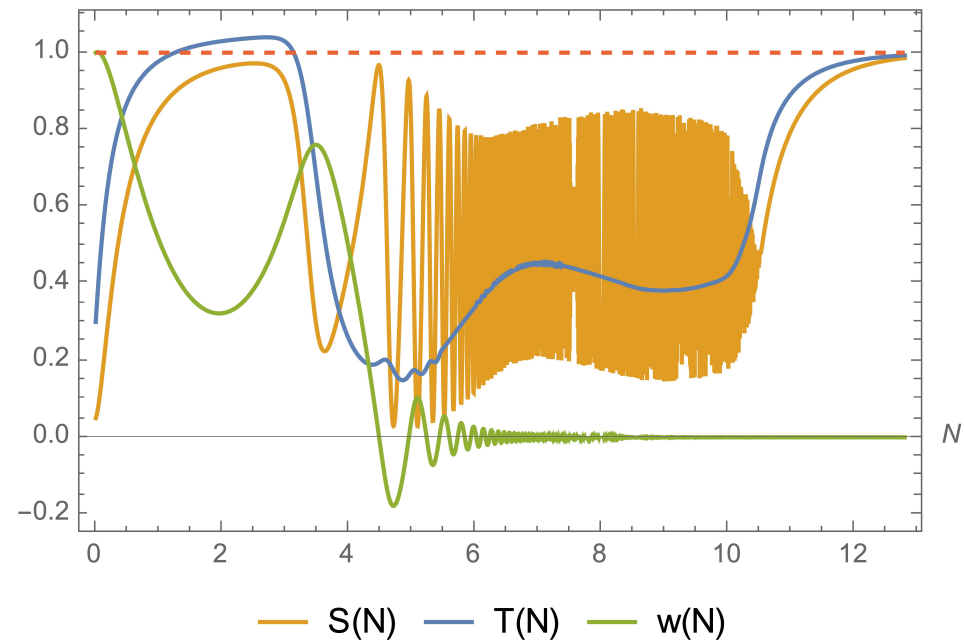
Apparent *counterexample* to “dynamical” distance conjecture

Way out: subleading corrections

$$K = -\log \left(\frac{2}{3}s^4 - 4s\xi \right)$$

↓

$$V(s, a) \supset \frac{243g_3^3 \xi^2}{s^6}$$



Additional arguments:

lack of explicit realisation (other singularity types), “physical” decays (as in reheating)

COMMENTS ON PHENO

Many caveats for *realistic* scenarios:

Kahler + spectator moduli, moduli stabilisation...

$$V = e^K K^{I\bar{J}} D_I W D_{\bar{J}} \bar{W} \quad \longrightarrow \quad V = \frac{\tilde{V}}{\mathcal{V}^3} \quad \text{Runaway!}$$

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Peculiar case: $\lambda = 0$ *Modulus “fixed” along runaway, thanks to axion + Hubble friction*
E.g. $V = \frac{a^2}{s^2}$ *See also [Tonioni '24]*

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General lessons?

SDC for traversed distance

Hard to realise axion monodromy inflation close to boundary
See also [Lanza, Westphal '24]

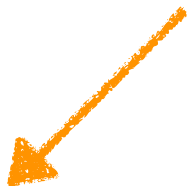
Don't forget the axions!

Often set to zero, but can have qualitative effects on the dynamics

Dynamical system techniques can be powerful !

OUTLOOK

Cosmology of 1-modulus asymptotic limits



Dynamical version of SDC

$$d(P, Q) \longleftrightarrow \Delta(P, Q)$$

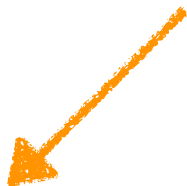
More examples: finite distance singularities?

*Universal patterns
& bottom up arguments* $\left[G_{I\bar{J}} \frac{d}{dN} \left(\phi^I \bar{\phi}^{\bar{J}} \right) \rightarrow \frac{\lambda(d-2)}{2} \right]$

Connection to Tameness

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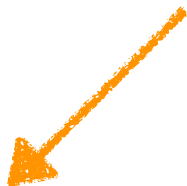
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Moduli fixing

Acc. expansion?

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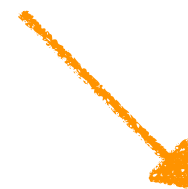
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Big picture:

“Dynamical” Swampland constraints for cosmological backgrounds

THANK YOU FOR YOUR ATTENTION!