

New consistent truncations and applications

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Based on : [to appear] Inverso & CS

Motivations and key results

Why consistent truncations?

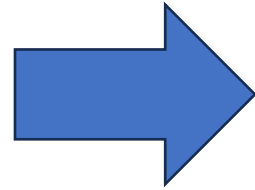
Low-d SUGRA solution

- Black holes
- Solitons
- Domain-walls

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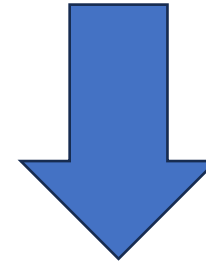
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Type II/M-theory solution

KK-like solution



String theory interpretation

AdS/CFT, probe branes,

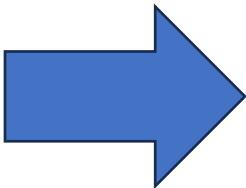
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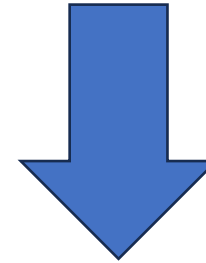
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Key results

- Algorithm for classifying embeddings of $(3 <)d$ -dimensional gSUGRA in 10/11D SUGRA.
- Constraints on the internal manifold.
- **Example:** Uplift of $N = 4$ $D = 4$ gauged SUGRA in
 - Type IIB on $S^2 \times S^2 \times \Sigma$ Dual to D3-D5-NS5 brane setups [Gaiotto-Witten]
Include Janus/S-folds/... [D'Hoker, Estes, Gutperle]
 - Not shown: M-theory embedding on $S^3 \times S^3 \times I$

Consistent truncations

State of the art

Consistent truncations

Definition

A *truncation* where the equations of motion of the reduced theory imply those of the full theory.

Non-examples:

- KK-compactification without the dilaton (*not* consistent)
- **Effective descriptions:** keep modes with $m \leq \Lambda_{cut-off}$
E.g.: Calabi-Yau compactifications \Rightarrow CY-moduli (\mathbb{C} -structure, Kähler, ...)

Consistent truncations

Examples

Classical examples

- Supergravities on group manifold (Scherk-Schwarz reduction)

Using Exceptional Field Theory (ExFT)

- Truncations on product of spheres/hyperboloids
 \Rightarrow 4D/5D *maximal* gSUGRA
- 5D N=2 [Cassani, Josse, Malek, Petrini, Waldram]
- ...

A 4d $\mathcal{N} = 4$ example

[D'Hoker, Estes, Gutperle]

Uplifts are rarely unique

M-theory:

Type IIB:

[Lu, Cvetič, Pope]

[Guarino, Trigiante, CS]

A 4d $\mathcal{N} = 4$ example

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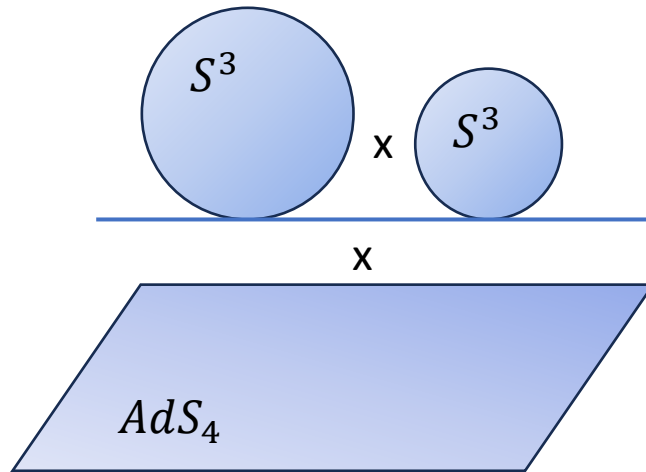
M-theory: On $S^3 \times S^3 \rightarrow M_{int} = S^7$
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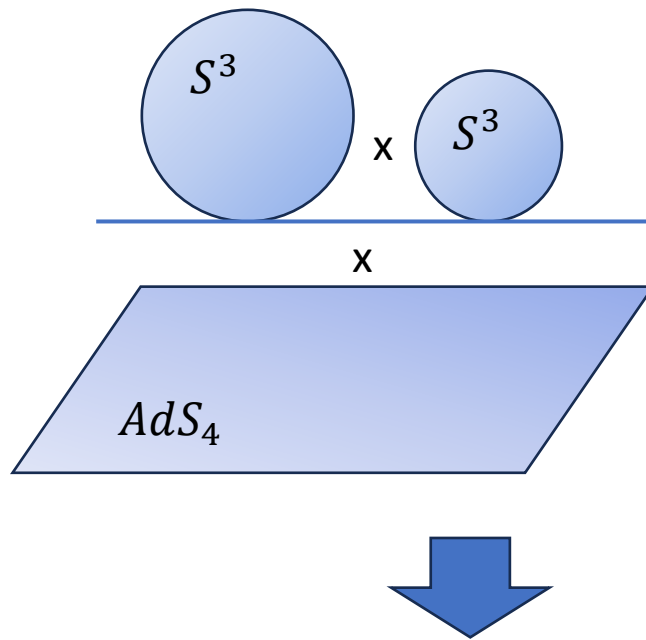
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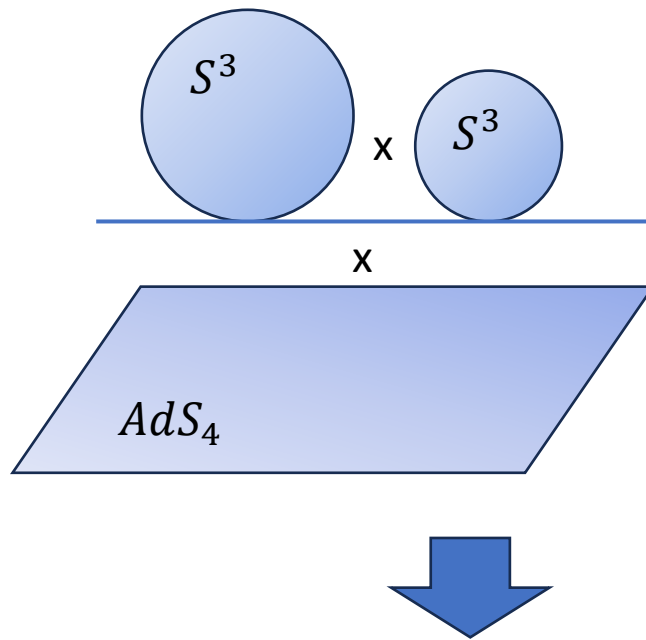


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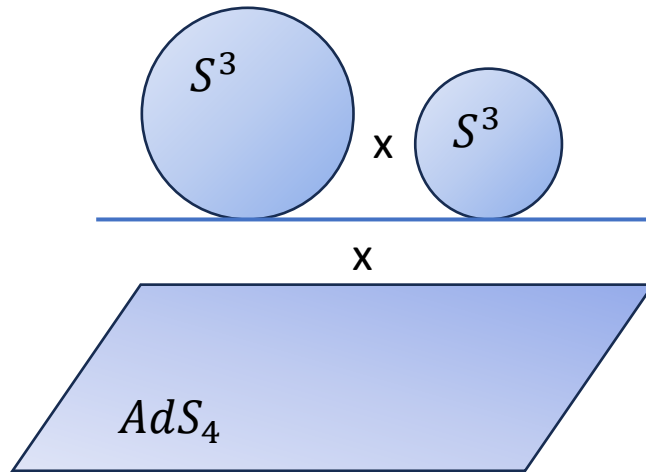


$D = 4 \mathcal{N} = 4$ SO(4)-gauged supergravity

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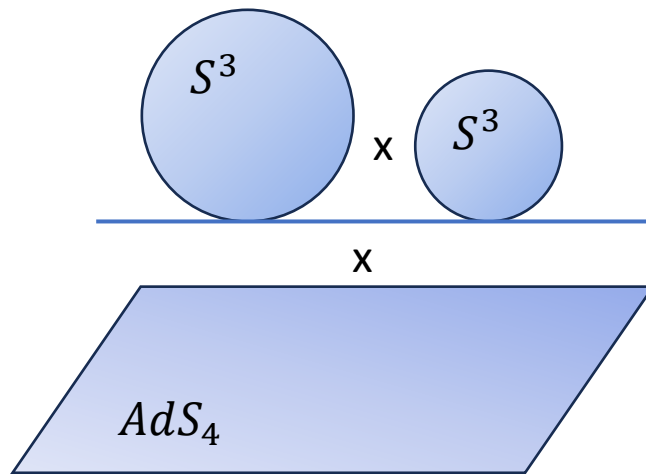
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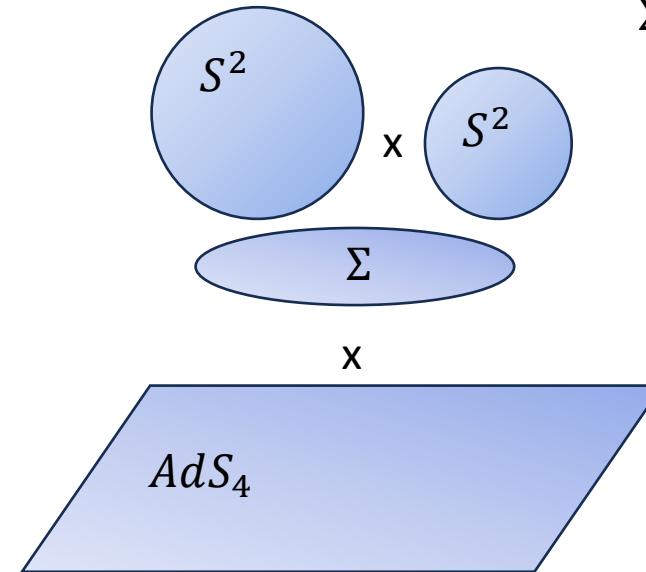
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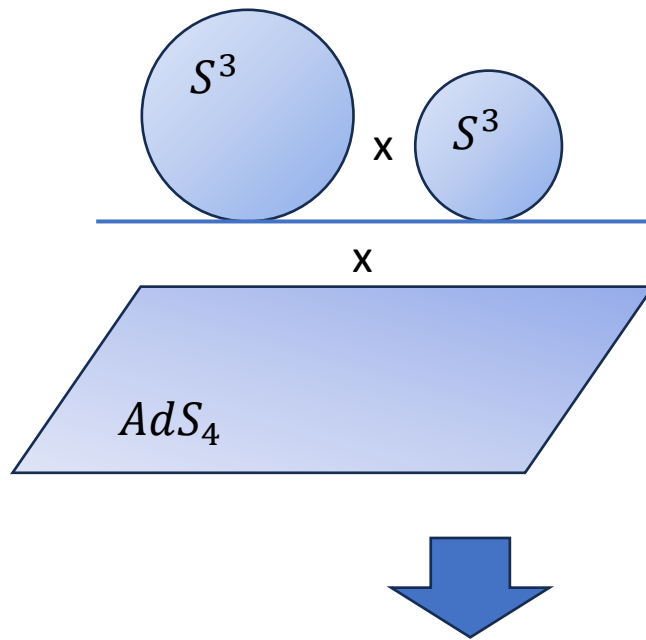


[Guarino, Trigiante, CS]

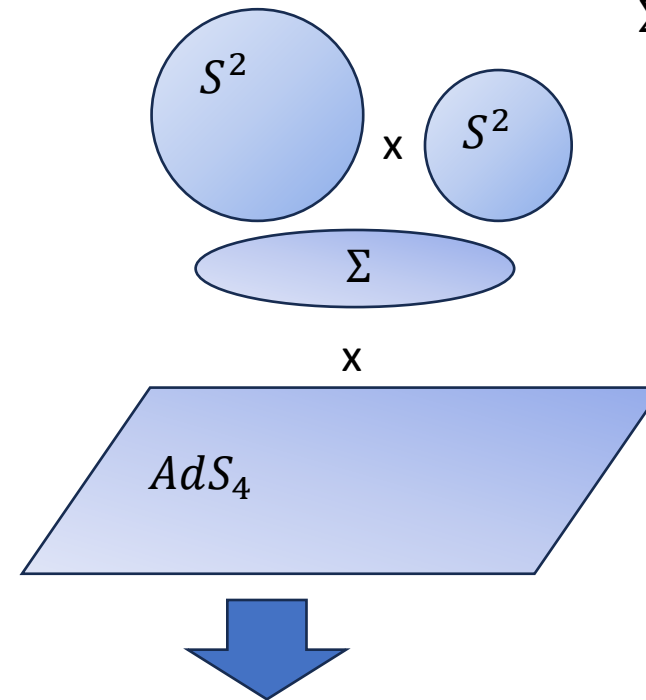
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2) Inverse problem?

Given a gauged SUGRA in d -dimension, what are its uplifts ?

- With maximal supersymmetry: solved! [Inverso][Inverso, Rovere]
- Non-pure/Non-maximal sugra: Open

Today: How to uplift non-maximal gauged SUGRA ?

Systematics of consistent truncations

Exceptional field theories

Frames, sections and torsion

Exceptional field theories

[Hull] [Pacheco, Waldram] [Hohm, Samtleben][...]

Type IIA/B/ 11D $\xrightarrow{\text{Dictionary}}$ $E_{d(d)}$ -Exceptional field theory
on M_{ext} of dimension $11 - d$

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Gauge transformations

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Diffeomorphisms



Gauge transformations

- Redefine the Lie derivative:

$$\begin{aligned} (L_\Lambda V)^M &:= \Lambda^N \partial_N V^M - \mathbb{P}^M{}_N{}^P{}_Q \partial_P \Lambda^Q V^N \\ &:= \mathcal{L}_{\Lambda^m} V^M + \text{correction in } \partial_m \Lambda^M \end{aligned}$$

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- Field content:

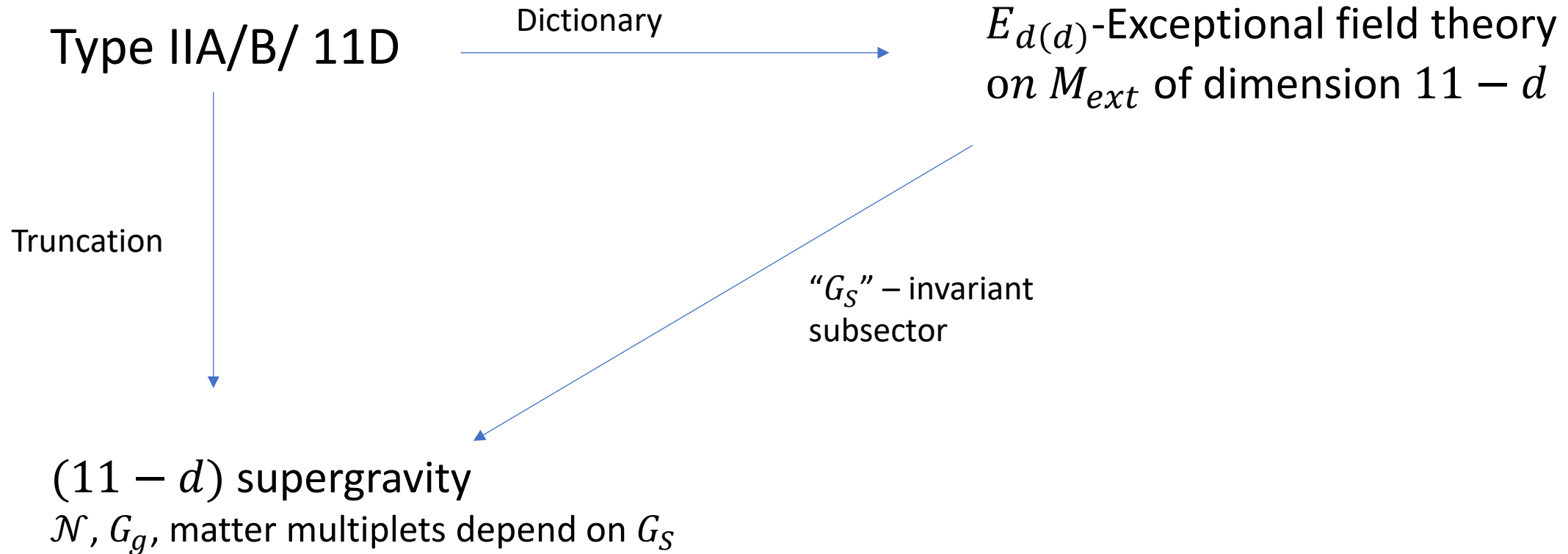
$E \in E_{d(d)}/K_d$ "gen. metric", A_μ^M "gen. KK modes", p-forms

Consistent truncations

Methods

[Hohm Samtleben]

[Cassani, Josse, Petrini, Waldram]



Statement

In ExFT, consistent truncations are equivalent to generalised G_S -structure with constant and G_S -invariant intrinsic torsion.

Generalised G-structure

In terms of sections

In terms of frame

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- K_A^M s.t. $Stab(K_A(p)) = G_S$

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- $E \in E_{7(7)}/G_S$ which is *globally* well-defined

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- Let ∇ be a connection s.t.

$$\nabla_{E_M} E_N = 0$$

Then the *intrinsic torsion* of ∇ must be a constant G_S singlet.

Generalised G-structure

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$$K_A^N = \mathbb{P}_A^M E_M^N$$

The projector on G_S singlets

Classification of uplift

Given a gauged SUGRA, what are the generalised G_S -structure with singlet constant torsion equal to a given embedding tensor?



$X_{AB}{}^C$
specifying the gauging

Truncation to non-maximal SUGRA

Start from D -dim SUGRA with gauge group G_g

We show that:

1) The internal manifold is locally:

$$M_{int} \cong \frac{G_g}{H} \times B.$$

H specifies the type of uplift (IIB/M-theory)

2) When $H^{1,3,5}(G_g/H) = 0$ (IIB), then \exists a gauge s.t.

$$L_{K_A} W = \mathcal{L}_{k_A} W.$$

\Rightarrow Simplifies the torsion condition!

Truncation to non-maximal SUGRA

The double ansatz

We build the most generic sections:

We build the most generic frame:

$$K_A = \theta_A^\alpha k_\alpha^m + K_A^{(p)}$$



Equivariant and closed polyforms
on $M_{int} = G_g/H \times B$.

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$$E = L \cdot Z \cdot Flux \cdot e \text{ where } E \in G_S \setminus E_{d(d)}$$

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$$\mathbb{P}_A{}^M Z_M{}^N \mathcal{E}_N{}^m = \theta_A{}^m$$

Always solves the compatibility
constraints ($Stab(K_A) = G_S$)

Final torsion constraint

$$\mathbb{P}Z\mathcal{E} = \Theta$$

Diagram illustrating the components of the final torsion constraint equation $\mathbb{P}Z\mathcal{E} = \Theta$:

- Projector on G_S -singlets (matter content) points to \mathbb{P} .
- Section constraints tensor (IIA/B/M) points to Z .
- Embedding tensor (gauging) points to \mathcal{E} .

$$d(L \cdot Z \cdot e)_{(p)} = 0$$

PDE on B only

An application

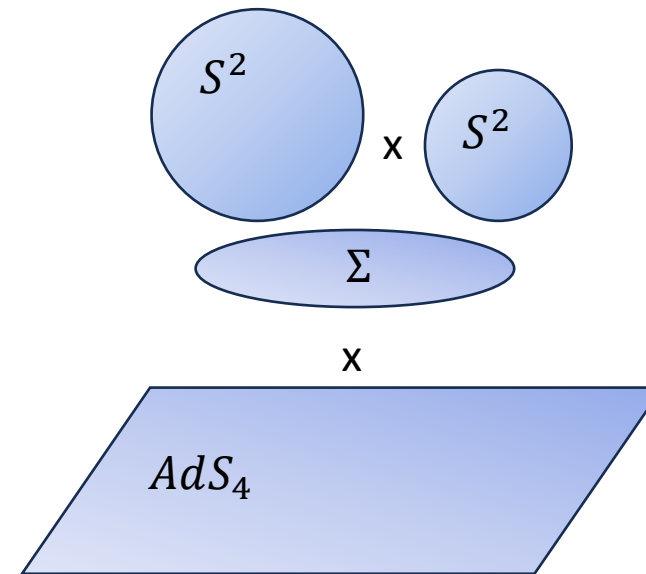
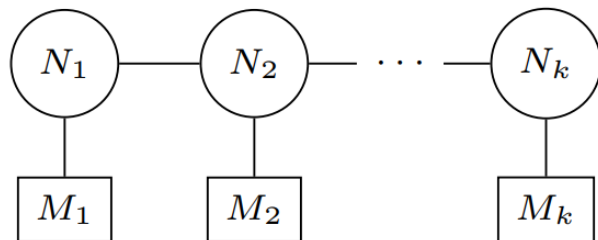
Example:

Consistent truncation of the DEG solutions

Solutions:

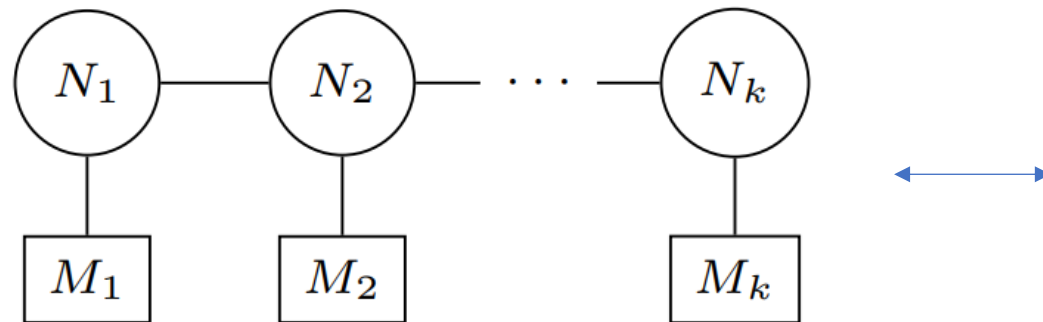
Depend on two holomorphic functions on Σ

$$\mathcal{A}_1 = h_1 + i h_1^D \text{ and } \mathcal{A}_2 = h_2 + i h_2^D$$

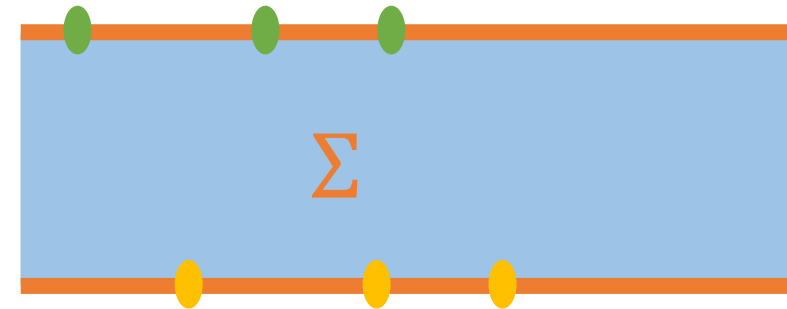


Holographic duals

- Type IIB solutions are dual to 3d $\mathcal{N} = 4$ linear quivers



D5-branes



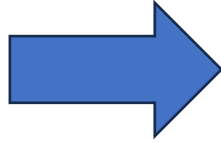
NS5-branes

Example:

Consistent truncation of the DEG solutions

$$G_g = SO(3) \times SO(3)$$

$$H = U(1) \times U(1)$$



$$S^2 \times S^2 \rightarrow M_{int}$$

$$\downarrow$$

$$\Sigma$$

The sections:

Depend on two holomorphic functions

$$\mathcal{A}_1 = h_1 + i h_1^D \text{ and } \mathcal{A}_2 = h_2 + i h_2^D$$

$$K_{i+} = k_i + d(2h_2^D Y^i)^+ - d((2h_1 h_2 + 2h_1^D h_2^D - \lambda) \text{vol}_2 Y^i) - \star d((2\bar{\partial}(\lambda h_2^D) + 4A_2(h_1 \bar{\partial} h_2^D - h_2^D \bar{\partial} h_1)) \epsilon_{ijk} Y^j dY^k \wedge \text{vol}_2 \wedge dz)^- + 0$$

$$K_{\bar{i}+} = 0 + d(-2h_2 Y^{\bar{i}})^+ + d(8(h_2 \bar{\partial} h_1^D - h_1^D \bar{\partial} h_2) \epsilon_{ijk} Y^j dY^k \wedge dz) + \star d((2\bar{\partial}(\lambda h_2) + 4i A_2(h_2 \bar{\partial} h_1^D - h_1^D \bar{\partial} h_2)) \epsilon_{ijk} Y^j dY^k \wedge \text{vol}_1 \wedge dz)^- + 4\sqrt{g_{S^2 \times S^2}} (2h_1 h_2 + 2h_1^D h_2^D - \lambda) (\partial h_1 \bar{\partial} h_2 + \bar{\partial} h_1 \partial h_2) k_i^*$$

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$$K_{\bar{i}-} = k_{\bar{i}} + d(-2h_1^D Y^{\bar{i}})^- + d((2h_1 h_2 + 2h_1^D h_2^D + \lambda) \text{vol}_1 Y^{\bar{i}}) + \star d((2\bar{\partial}(\lambda h_1^D) + 4i A_1(h_2 \bar{\partial} h_1^D - h_1^D \bar{\partial} h_2)) \epsilon_{ijk} Y^j dY^k \wedge \text{vol}_1 \wedge dz)^+ + 0$$

The invariant sections

$$\begin{aligned}
 K_{i+} = & k_i + d(2h_2^D Y^i)^+ \\
 & - d\left((2h_1 h_2 + 2h_1^D h_2^D - \lambda) \text{vol}_2 Y^i\right) \\
 & - \star d\left((2\bar{\partial}(\lambda h_2^D) + 4A_2(h_1 \bar{\partial} h_2^D - h_2^D \bar{\partial} h_1)) \epsilon_{ijk} Y^j dY^k \wedge \text{vol}_2 \wedge dz\right)^- \\
 & + 0
 \end{aligned}$$

$$\begin{aligned}
 K_{\bar{i}+} = & 0 + d(-2h_2 Y^{\bar{i}})^+ \\
 & + d\left(8(h_2 \bar{\partial} h_1^D - h_1^D \bar{\partial} h_2) \epsilon_{ijk} Y^{\bar{j}} dY^{\bar{k}} \wedge dz\right) \\
 & + \star d\left((2\bar{\partial}(\lambda h_2) + 4i A_2(h_2 \bar{\partial} h_1^D - h_1^D \bar{\partial} h_2)) \epsilon_{ijk} Y^{\bar{j}} dY^{\bar{k}} \wedge \text{vol}_1 \wedge dz\right)^- \\
 & + 4\sqrt{g_{S^2 \times S^2}} (2h_1 h_2 + 2h_1^D h_2^D - \lambda) (\partial h_1 \bar{\partial} h_2 + \bar{\partial} h_1 \partial h_2) k_{\bar{i}}^*
 \end{aligned}$$

$$\begin{aligned}
 K_{i-} = & 0 + d(-2h_1 Y^i)^- \\
 & - d\left(8(h_1 \bar{\partial} h_2^D - h_2^D \bar{\partial} h_1) \epsilon_{ijk} Y^j dY^k \wedge dz\right) \\
 & + \star d\left((2\bar{\partial}(\lambda h_1) + 4A_1(h_2^D \bar{\partial} h_1 - h_1 \bar{\partial} h_2^D)) \epsilon_{ijk} Y^j dY^k \wedge \text{vol}_2 \wedge dz\right)^+ \\
 & - 4\sqrt{g_{S^2 \times S^2}} (2h_1 h_2 + 2h_1^D h_2^D + \lambda) (\partial h_1 \bar{\partial} h_2 + \bar{\partial} h_1 \partial h_2) k_{\bar{i}}^*
 \end{aligned}$$

$$K_{\bar{i}} = k_{\bar{i}} + d(-2h_2^D Y^{\bar{i}})^-$$

The SUGRA fields

From the sections/frame, we use the ExFT dictionary to obtain:

$$ds^2 = \Delta^{-1} \left(ds_{\text{ext}}^2 - n_1^{-1} ds_{S_1^2}^2 - n_2^{-1} ds_{S_2^2}^2 - 2w ds_{\Sigma}^2 \right)$$

$$B_2^{(0)} = -2\chi e^{\xi} \frac{h_1}{n_1} \text{vol}_{S_1^2} + 2h_1^D \text{vol}_{S_2^2} + 2h_1 \frac{(\log h_1 \wedge \log h_2)}{n_2 w} \text{vol}_{S_2^2}$$

$$C_2^{(0)} = 2h_2^D \text{vol}_{S_1^2} - 2h_2 \frac{(\log h_1 \wedge \log h_2)}{n_1 w} \text{vol}_{S_1^2} + 2\chi e^{\xi} \frac{h_2}{n_2} \text{vol}_{S_2^2}$$

$$\exp(\Phi) = e^{\xi} |\tau|^2 \frac{h_1}{h_2} \frac{n_0}{(n_1 n_2)^{1/2}}$$

$$C_0 = \frac{\chi}{|\tau|^2} \frac{h_1 \wedge h_2}{h_1^2 n_0 w}$$

+ vector contributions,...

Thank you!

Summary

- Algorithm for classifying embeddings of $(3 <)d$ -dimensional gSUGRA in 10/11D SUGRA.
- $M_{int} = \frac{G_g}{H} \times B$
- Classification reduces to a PDE on B
- **Example:** Uplift of $N = 4$ $D = 4$ gauged SUGRA in
 - Type IIB on $S^2 \times S^2 \times \Sigma$ Dual to D3-D5-NS5 brane setups [Hanany-Witten]
Include Janus/S-folds/... [D'Hoker, Estes, Gutperle]