

Topological R-fects in Chern-Simons theory and 3d gravity

Saskia Demulder

Ben Gurion University

[2410.XXXX] in collaboration with Alex Arvanitakis, Lewis Cole, Daniel Thompson

Corfu Workshop on Noncommutative and Generalized Geometry in String Theory, Gauge Theory and Related Physical Models 22 Sept. 2024

Topological defects

A defect is called topological when the energy momentum tensor

satisfies $T_L = T_R$ & $\overline{T}_L = \overline{T}_R$ at the defect locus

 \rightarrow "Topological" = can be deformed and moved at no cost

 \rightarrow Encode dualities and symmetries

[Bachas, de Boer, Dijkgraaf, Ooguri, Kapustin, Tikhonov, Fröhlich, Fuchs, Gaberdiel, Runkel, Schweigert, Brunner, Roggenkamp, Carqueville,...]

 \rightarrow "Fusion" = move and compose topological defects







 \cong

Motivation/digression

T-duality is an example of a topology defect [Fuchs, Gaberdiel, Runkel, Schweigert] [Kapustin, Saulina][Niro, Roumpedakis, Sela]

Motivation/digression

T-duality is an example of a topology defect [Fuchs, Gaberdiel, Runkel, Schweigert] [Kapustin, Saulina][Niro, Roumpedakis, Sela]



is a topological defect !

.... but is also a topological defect !

[SD, Raml]

Goal: Use the technology of defects and their fusion to understand generalised T-duality

Motivation/digression

T-duality is an example of a topology defect [Fuchs, Gaberdiel, Runkel, Schweigert] [Kapustin, Saulina][Niro, Roumpedakis, Sela]



```
is a topological defect !
```

[SD, Raml]

Goal: Use the technology of defects and their fusion to understand generalised T-duality

 \rightarrow problem: fusion remained a difficult question

.... but is also a topological defect !

→ needed a way to construct topological defects for non-Abelian Chern-Simons...





$$\begin{split} S_{\mathrm{unfolded}}[A_N,A_S] &= S_{\mathrm{CS}}[A_N] + S_{\mathrm{CS}}[A_S] + S_D[\mathbb{A}] \\ & \text{with} \quad A_S \in \mathfrak{u}(1)_S^d \;, \quad A_N \in \mathfrak{u}(1)_N^d \end{split}$$



$$\begin{split} S_{\mathrm{unfolded}}[A_N,A_S] &= S_{\mathrm{CS}}[A_N] + S_{\mathrm{CS}}[A_S] + S_D[\mathbb{A}] \\ & \text{with} \quad A_S \in \mathfrak{u}(1)_S^d \ , \quad A_N \in \mathfrak{u}(1)_N^d \end{split}$$

♠

$$\downarrow$$

$$S_{\text{folded}}[A_N, A_S] = S_{\text{CS}}[A_N] - S_{\text{CS}}[A_S] + S_D[\mathbb{A}]$$



$$\begin{split} S_{\mathrm{unfolded}}[A_N,A_S] &= S_{\mathrm{CS}}[A_N] + S_{\mathrm{CS}}[A_S] + S_D[\mathbb{A}] \\ & \text{with} \quad A_S \in \mathfrak{u}(1)_S^d \;, \quad A_N \in \mathfrak{u}(1)_N^d \end{split}$$

 $\mathbf{\Lambda}$

=

√

$$egin{aligned} & \mathcal{G}_{ ext{folded}}[A_N,A_S] = k \int_{M_N} \langle\!\langle \mathbb{A}\,,\mathrm{d}\mathbb{A}
angle\!
angle + S_D[\mathbb{A}] \ & ext{with} \quad \mathbb{A} = (A_N,A_S) \ \in \ \mathfrak{u}(1)^{2d} = \mathfrak{u}(1)^d_N \oplus \mathfrak{u}(1)^d_S \ & ext{$\langle\!\langle \mathbb{X}\,,\mathbb{Y}
angle\!
angle} = \langle\!\langle X_N\,,Y_N
angle - \langle\!\langle X_S\,,Y_S
angle \end{aligned}$$



In the 3d Abelian Chern-Simons:

when does Chern-Simons theory admit a topological surface ?

Elegant algebraic answer: [Kapustin, Saulina] Look for Lagrangian subalgebras !



$$S_{\rm CS} = k \int_{M_N} \langle\!\langle \mathbb{A}, d\mathbb{A} \rangle\!\rangle \qquad \text{where} \quad \langle\!\langle \mathbb{X}, \mathbb{Y} \rangle\!\rangle = \langle X_N, Y_N \rangle - \langle X_S, Y_S \rangle$$

with gauge group $\mathfrak{u}(1)^{2d} = \mathfrak{u}(1)^d_N \oplus \mathfrak{u}(1)^d_S$



$$S_{\mathrm{CS}} = k \int_{M_N} \langle\!\langle \mathbb{A} \,, \mathrm{d}\mathbb{A}
angle\!
angle$$
 where $\langle\!\langle \mathbb{X} \,, \mathbb{Y}
angle\!
angle = \langle\!\langle X_N \,, Y_N
angle - \langle\!\langle X_S \,, Y_S
angle$
with gauge group $\mathfrak{u}(1)^{2d} = \mathfrak{u}(1)^d_N \oplus \mathfrak{u}(1)^d_S$

Varying the action

$$\delta S_{\rm CS} = 2 k \int_{M_N} \langle\!\langle \delta \mathbb{A} , \mathrm{d} \mathbb{A} \rangle\!\rangle + k \int_D \langle\!\langle \delta \mathbb{A} , \mathbb{A} \rangle\!\rangle$$

Vanishes by the e.o.m. $F[\mathbb{A}] \equiv d\mathbb{A} = 0$

requires a **boundary cond**. that we will take to be **topological**

Demand that $\mathbb{A}|_D \in$ "Lagrangian subspace S" of $\mathfrak{u}(1)^{2d} = \mathfrak{u}(1)^d_N \oplus \mathfrak{u}(1)^d_S$ $\langle\!\langle \mathbb{X}, \mathbb{Y} \rangle\!\rangle = 0 \qquad \forall \mathbb{X}, \mathbb{Y} \in S$



$$S_{\mathrm{CS}} = k \int_{M_N} \langle\!\langle \mathbb{A} \,, \mathrm{d}\mathbb{A}
angle\!
angle$$
 where $\langle\!\langle \mathbb{X} \,, \mathbb{Y}
angle\!
angle = \langle\!\langle X_N \,, Y_N
angle - \langle\!\langle X_S \,, Y_S
angle$
with gauge group $\mathfrak{u}(1)^{2d} = \mathfrak{u}(1)^d_N \oplus \mathfrak{u}(1)^d_S$

Varying the action

$$\delta S_{\rm CS} = 2 k \int_{M_N} \langle\!\langle \delta \mathbb{A} , \mathrm{d} \mathbb{A} \rangle\!\rangle + k \int_D \langle\!\langle \delta \mathbb{A} , \mathbb{A} \rangle\!\rangle$$

Vanishes by the e.o.m. $F[\mathbb{A}] \equiv d\mathbb{A} = 0$

requires a **boundary cond**. that we will take to be **topological**

Demand that $\mathbb{A}|_D \in$ "Lagrangian subspace S" of $\mathfrak{u}(1)^{2d} = \mathfrak{u}(1)^d_N \oplus \mathfrak{u}(1)^d_S$ $\langle\!\langle \mathbb{X}, \mathbb{Y} \rangle\!\rangle = 0 \qquad \forall \mathbb{X}, \mathbb{Y} \in S$

Instead of **boundary condition**: include the **boundary term**

🥎 projector

$$S = k \int_{M_N} \langle\!\langle \mathbb{A} \,, \mathrm{d} \mathbb{A} \rangle\!\rangle + k \int_D \langle\!\langle \mathbb{A} \,, P_S \, \mathbb{A} \rangle\!\rangle$$



For Abelian Chern-Simons, the gauge group is

$$\mathfrak{u}(1)^{2d} = \mathfrak{u}(1)_N^d \oplus \mathfrak{u}(1)_S^d$$

Take the **two Lagrangians**

diagonal	:	$\mathfrak{u}(1)_{+}^{d} = \{ (X_{N}, X_{S}) \in \mathfrak{u}(1)^{2d} \mid X_{N} = X_{S} \} ,$
anti-diagonal	:	$\mathfrak{u}(1)_{-}^{d} = \{ (X_N, X_S) \in \mathfrak{u}(1)^{2d} \mid X_N = -X_S \}$



For Abelian Chern-Simons, the gauge group is

$$\mathfrak{u}(1)^{2d} = \mathfrak{u}(1)_N^d \oplus \mathfrak{u}(1)_S^d$$

Take the two Lagrangians

diagonal	:	$\mathfrak{u}(1)_{+}^{d} = \{ (X_N, X_S) \in \mathfrak{u}(1)^{2d} \mid X_N = X_S \} ,$
anti-diagonal	:	$\mathfrak{u}(1)_{-}^{d} = \{ (X_N, X_S) \in \mathfrak{u}(1)^{2d} \mid X_N = -X_S \}$



Yields the fusion algebra

$$\mathfrak{u}(1)^d_- \circ \mathfrak{u}(1)^d_- = \mathfrak{u}(1)^d_+ \qquad \mathfrak{u}(1)^d_+ \circ \mathfrak{h} = \mathfrak{h} \ , \qquad \mathfrak{h} \circ \mathfrak{u}(1)^d_+ = \mathfrak{h}$$

That is
$$\left(\left\{\mathfrak{u}(1)^d_+,\mathfrak{u}(1)^d_-\right\},\circ\right)\cong\mathbb{Z}_2$$

identity

idempotent

Topological surfaces in non-Abelian Chern-Simons

In the 3d non-Abelian Chern-Simons:

when does Chern-Simons theory admit a topological surface ?

$$S_{\mathrm{CS}} = k \int_{M_N} \left(\langle\!\langle \mathbb{A} \, , \mathrm{d} \mathbb{A} \rangle\!\rangle + \frac{1}{3} \langle\!\langle \mathbb{A} \, , [\![\mathbb{A} \, , \mathbb{A}]\!] \rangle\!\rangle \right)$$

$$\mathbb{A} = (A_N, A_S) \in \mathfrak{d} = \mathfrak{g}_N \oplus \mathfrak{g}_S \qquad \langle\!\langle \mathbb{X}, \mathbb{Y} \rangle\!\rangle = \langle X_N, Y_N \rangle - \langle X_S, Y_S \rangle$$



Topological surfaces in non-Abelian Chern-Simons

In the 3d non-Abelian Chern-Simons:

when does Chern-Simons theory admit a topological surface ?

$$S_{\mathrm{CS}} = k \int_{M_N} \left(\langle\!\langle \mathbb{A} \, , \mathrm{d} \mathbb{A} \rangle\!\rangle + \frac{1}{3} \langle\!\langle \mathbb{A} \, , [\![\mathbb{A} \, , \mathbb{A}]\!] \rangle\!\rangle \right)$$

$$\mathbb{A} = (A_N, A_S) \in \mathfrak{d} = \mathfrak{g}_N \oplus \mathfrak{g}_S \qquad \langle \langle \mathbb{X}, \mathbb{Y} \rangle \rangle = \langle X_N, Y_N \rangle - \langle X_S, Y_S \rangle$$



We showed: [Arvanitakis, Cole, SD, Thompson]

- \rightarrow Canonical way to construct topological defects
- → Crucial tool: (modified) Yang-Baxter equation
- \rightarrow Defined and studied their fusion

Lagrangians via the mCYBE: *R*-defects

Strategy: simplify one's life a little by looking for a subclass of defects

Solve the modified classical Yang-Baxter equation

$$[\mathcal{R}X, \mathcal{R}Y] - \mathcal{R}([\mathcal{R}X, Y] + [X, \mathcal{R}Y]) + [X, Y] = 0 \qquad X, Y \in \mathfrak{g}$$

Yields a Lagrangian subalgebra

$$\mathfrak{g}_{\mathcal{R}} = \{ ((\mathcal{R}+1)X, (\mathcal{R}-1)X) \in \mathfrak{d} \}$$

With Lie-bracket $[X, Y]_{\mathcal{R}} = [\mathcal{R}X, Y] + [X, \mathcal{R}Y]$

Lagrangians via the mCYBE: *R*-defects

Strategy: simplify one's life a little by looking for a subclass of defects

Solve the modified classical Yang-Baxter equation

$$[\mathcal{R}X, \mathcal{R}Y] - \mathcal{R}([\mathcal{R}X, Y] + [X, \mathcal{R}Y]) + [X, Y] = 0 \qquad X, Y \in \mathfrak{g}$$

Yields a Lagrangian subalgebra $\mathfrak{g}_{\mathcal{R}} = \{ ((\mathcal{R}+1)X, (\mathcal{R}-1)X) \in \mathfrak{d} \}$

With Lie-bracket $[X, Y]_{\mathcal{R}} = [\mathcal{R}X, Y] + [X, \mathcal{R}Y]$

Called a "bi-algebra" or "Manin triple" $\mathfrak{d} = \mathfrak{g}_{\Delta} \oplus \mathfrak{g}_{\mathcal{R}}$

 \rightarrow Directly generalises the Abelian case $\mathfrak{u}(1)^{2d} = \mathfrak{u}(1)^d_{\Lambda} \oplus \mathfrak{u}(1)^d_{-}$

 \rightarrow Technical requirement $\mathfrak{d} = \mathfrak{g}_{\Delta} \oplus \mathfrak{g}_{\mathcal{R}} \cong \mathfrak{g} \oplus \mathfrak{g}$

Effectively specialising to **non-compact algebras**

North

South

Lagrangians via the mCYBE: *R*-defects

We have a topological boundary condition for the Lagrangian subalgebra

$$\mathfrak{g}_{\mathcal{R}} = \{ ((\mathcal{R}+1)X, (\mathcal{R}-1)X) \in \mathfrak{d} \}$$

Since with the **R-matrix** we can construct a **projector**

$$\langle\!\langle \mathbb{A}, \mathcal{P}_{\mathcal{R}} \mathbb{A} \rangle\!\rangle = \langle A_S, A_N \rangle + \frac{1}{2} \langle A_N - A_S, \mathcal{R}(A_N - A_S) \rangle$$

Yielding the (folded) Chern-Simon action

Boundary for
$$\mathfrak{g}_{\mathcal{R}}$$

Nothing $S_{\text{folded}} = \int \operatorname{CS}[\mathbb{A}] + \int_D \langle\!\langle \mathbb{A}, \mathcal{P}_{\mathcal{R}} \mathbb{A} \rangle\!\rangle$



$$\mathfrak{h}_{NI} \circ \mathfrak{h}_{IS} = \Pi_{NS} \Big(\big(\mathfrak{h}_{NI} \oplus \mathfrak{h}_{IS} \big) \cap \big(\mathfrak{g}_N \oplus \mathfrak{g}_\Delta \oplus \mathfrak{g}_S \big) \Big)$$

$$\checkmark$$

 $\mathfrak{g}_{\mathcal{R}} \circ \mathfrak{g}_{\mathcal{R}} = \{ (X_N, X_S) \in \mathfrak{d} \mid X_N^{\mathfrak{t}} = X_S^{\mathfrak{t}}, X_N^- = 0, X_S^+ = 0 \}$

 \rightarrow Proved that $\mathfrak{h}_{NI} \circ \mathfrak{h}_{IS}$ is

- ✓ Lagrangian
- ✓ a subalgebra
- with identity element $\mathfrak{g}_{\Delta} \circ \mathfrak{h} = \mathfrak{h}$, $\mathfrak{h} \circ \mathfrak{g}_{\Delta} = \mathfrak{h}$
- reduces to Lagrangian fusion in the Abelian case



 AdS_3 gravity a re-formulation in terms of Chern-Simons theories

$$S_{\text{grav}} = S_{\text{CS}}[A] - S_{\text{CS}}[\overline{A}] + S_{\text{bdy}}$$

"folded" Chern-Simons theory for the gauge group $\mathfrak{sl}(2,\mathbb{R})\oplus\mathfrak{sl}(2,\mathbb{R})$

Where the gauge connections are related to the metric vielbein and the soldering form

$$A^a = \omega^a + \frac{1}{\ell}e^a$$
, $\tilde{A}^a = \omega^a - \frac{1}{\ell}e^a$

With respect to the $\mathfrak{sl}(2,\mathbb{R})$ -generators $[L_a,L_b]=(a-b)L_{a+b}$

AdS₃ higher-spin gravity



"folded" Chern-Simons theory for the gauge group $\mathfrak{sl}(2,\mathbb{R}) \oplus \mathfrak{sl}(2,\mathbb{R})$

Where the gauge connections are related to the metric vielbein and the soldering form

$$A^a = \omega^a + \frac{1}{\ell}e^a$$
, $\tilde{A}^a = \omega^a - \frac{1}{\ell}e^a$

and with spin fields $\phi_{\mu_1...\mu_{s-1}\mu_s} \sim \operatorname{Tr}\left(e_{(\mu}....e_{\mu_{s-1}}e_{\mu_s})\right)$



 AdS_3 gravity a re-formulation in terms of Chern-Simons theories

$$S_{\text{grav}} = S_{\text{CS}}[A] - S_{\text{CS}}[\bar{A}] + S_{\text{bdy}}$$

"folded" Chern-Simons theory for the gauge group $\mathfrak{sl}(2,\mathbb{R})\oplus\mathfrak{sl}(2,\mathbb{R})$



 AdS_3 gravity a re-formulation in terms of Chern-Simons theories

$$S_{\text{grav}} = S_{\text{CS}}[A] - S_{\text{CS}}[\overline{A}] + S_{\text{bdy}}$$

"folded" Chern-Simons theory for the gauge group $\mathfrak{sl}(2,\mathbb{R})\oplus\mathfrak{sl}(2,\mathbb{R})$

In the Feffer-Graham gauge the boundary term is [Llabres; Apolo; Ebert, Hijano, Kraus, Monten, Myers]

$$S_{\text{bdy}} = \frac{k}{4\pi} \int_{\partial M} \operatorname{tr} A \wedge \bar{A} - \frac{k}{2\pi} \int_{\partial M} \operatorname{tr} \left(L_0(A - \bar{A}) \wedge (A - \bar{A}) \right)$$

$$(A - \bar{A}) = \frac{k}{4\pi} \int_{\partial M} \operatorname{tr} \left(L_0(A - \bar{A}) \wedge (A - \bar{A}) \right)$$

$$(A - \bar{A}) = \frac{k}{4\pi} \int_{\partial M} \operatorname{tr} \left(L_0(A - \bar{A}) \wedge (A - \bar{A}) \right)$$

$$(A - \bar{A}) = \frac{k}{4\pi} \int_{\partial M} \operatorname{tr} \left(L_0(A - \bar{A}) \wedge (A - \bar{A}) \right)$$

$$(A - \bar{A}) = \frac{k}{4\pi} \int_{\partial M} \operatorname{tr} \left(L_0(A - \bar{A}) \wedge (A - \bar{A}) \right)$$

$$(A - \bar{A}) = \frac{k}{4\pi} \int_{\partial M} \operatorname{tr} \left(L_0(A - \bar{A}) \wedge (A - \bar{A}) \right)$$

$$(A - \bar{A}) = \frac{k}{4\pi} \int_{\partial M} \operatorname{tr} \left(L_0(A - \bar{A}) \wedge (A - \bar{A}) \right)$$

$$(A - \bar{A}) = \frac{k}{4\pi} \int_{\partial M} \operatorname{tr} \left(L_0(A - \bar{A}) \wedge (A - \bar{A}) \right)$$

$$(A - \bar{A}) = \frac{k}{4\pi} \int_{\partial M} \operatorname{tr} \left(L_0(A - \bar{A}) \wedge (A - \bar{A}) \right)$$

$$(A - \bar{A}) = \frac{k}{4\pi} \int_{\partial M} \operatorname{tr} \left(L_0(A - \bar{A}) \wedge (A - \bar{A}) \right)$$

The R-boundary term where the R-matrix is the Drinfel'd-Jimbo R-matrix for $\mathfrak{sl}(2,\mathbb{R})$

$$S_{\text{bdy}} = \int_{\partial M} \langle A, \bar{A} \rangle - \frac{1}{2} \langle \bar{A} - A, \mathcal{R}(\bar{A} - A) \rangle \qquad \mathcal{R}L_0 = 0, \qquad \mathcal{R}L_{\pm} = \pm L_{\pm}$$
$$= \frac{k}{4\pi} \int_{\partial M} \operatorname{tr} A \wedge \bar{A} - \frac{k}{2\pi} \int_{\partial M} \operatorname{tr} \left(L_0(A - \bar{A}) \wedge (A - \bar{A}) \right)$$

matches precisely the bdy term from GHY

AdS₃ higher-spin gravity

More generally we can always define **boundary term**

$$S_{\text{bdy}} = \int_{\partial M} \langle A, \bar{A} \rangle - \frac{1}{2} \langle \bar{A} - A, \mathcal{R}(\bar{A} - A) \rangle$$

where the R-matrix is the Drinfel'd-Jimbo R-matrix for $\mathfrak{sl}(N,\mathbb{R})$

$$\mathcal{R}H_i = 0$$
, $\mathcal{R}E_{\alpha} = +c E_{\alpha}$, $\mathcal{R}E_{-\alpha} = -c E_{-\alpha}$

 \rightarrow get a canonical boundary condition for higher spin AdS_3 gravity

AdS₃ higher-spin gravity

More generally we can always define **boundary term**

$$S_{\text{bdy}} = \int_{\partial M} \langle A, \bar{A} \rangle - \frac{1}{2} \langle \bar{A} - A, \mathcal{R}(\bar{A} - A) \rangle$$

where the R-matrix is the Drinfel'd-Jimbo R-matrix for $\mathfrak{sl}(N,\mathbb{R})$

$$\mathcal{R}H_i = 0$$
, $\mathcal{R}E_{\alpha} = +c E_{\alpha}$, $\mathcal{R}E_{-\alpha} = -c E_{-\alpha}$

 \rightarrow get a canonical boundary condition for higher spin AdS_3 gravity

For example for $\mathfrak{sl}(3,\mathbb{R})$ -gravity

$$\begin{split} S_{\text{bdy}} &= \int_{\partial M} \langle A, \bar{A} \rangle - \frac{k}{2\pi} \langle \bar{A} - A \stackrel{\wedge}{,} \mathcal{R}_{\text{DJ}}(\bar{A} - A) \rangle \\ &= \int_{\partial M} \langle A, \bar{A} \rangle - \frac{k}{4\pi} \int_{\partial M} \text{tr}[(A - \bar{A}) \wedge (A - \bar{A})L_0] \\ &+ \frac{k}{64\pi} \int_{\partial M} \text{tr}[(A - \bar{A})W_{+2}] \wedge \text{tr}[(A - \bar{A})W_{-2}] \,. \end{split}$$

Coincides with the boundary term constructed by [Apolo]

See review [Campoleoni, Fredenhagen]

Gauge transfo *A* $\delta A = d\lambda + [A, \lambda]$ \updownarrow $\delta e = d\xi + [\omega, \xi] + [e, \Lambda]$ $\xi = \frac{\ell}{2} (\lambda - \tilde{\lambda})$

diffeos metric



Celebrated result: Brown-Henneaux boundary conditions → two copies of Virasoro

$$A - A_{AdS} \sim \mathcal{O}(1)$$
 $\bar{A} - \bar{A}_{AdS} \sim \mathcal{O}(1)$



Instead the R-boundary condition (and restricting to AAdS₃)

$$(\mathcal{R}-1)A = (\mathcal{R}+1)\bar{A}$$

[Campoleoni, Fredenhagen, Raeymaekers] [Arvanitakis, Cole, SD, Thompson]

 \downarrow

Free boson realisation of a single copy of Virasoro

\rightarrow Summary

Constructed topological boundary conditions in non-Abelian Chern-Simons

- Led to a subclass: R-defects
- Looked into their fusion
- Application to AdS₃-gravity

 \rightarrow What's next ?

- ► Can we identify the surface defect for Poisson-Lie T-duality ?
- Does the R-defect boundary make sense in higher spin 3d gravity
- SymTFT description ?

Thank you for your attention !