

Topological R-fects in Chern-Simons theory and 3d gravity

Saskia Demulder

Ben Gurion University

[2410.XXXX] in collaboration with Alex Arvanitakis, Lewis Cole, Daniel Thompson

Corfu Workshop on Noncommutative and Generalized Geometry in String Theory, Gauge Theory and Related Physical Models 22 Sept. 2024

Topological defects

A defect is called topological when the energy momentum tensor

satisfies $T_L = T_R$ & $\bar{T}_L = \bar{T}_R$ at the defect locus

 \rightarrow "Topological" = can be deformed and moved at no cost

 \rightarrow Encode dualities and symmetries

[Bachas, de Boer, Dijkgraaf, Ooguri, Kapustin,Tikhonov, Fröhlich, Fuchs, Gaberdiel, Runkel, Schweigert, Brunner, Roggenkamp, Carqueville,…]

 \rightarrow "Fusion" = move and compose topological defects

≅

Motivation/digression

T-duality is an example of **a topology defect** [Fuchs, Gaberdiel, Runkel, Schweigert] [Kapustin, Saulina][Niro, Roumpedakis, Sela]

Motivation/digression

T-duality is an example of **a topology defect** [Fuchs, Gaberdiel, Runkel, Schweigert] [Kapustin, Saulina][Niro, Roumpedakis, Sela]

Exact symmetry of string theory

is **a topological defect** !

…. but **is also a topological defect** ! SUGRA solution generating technique [SD, Raml]

Use the technology of defects and their fusion to understand **generalised T-duality Goal**:

Motivation/digression

T-duality is an example of **a topology defect** [Fuchs, Gaberdiel, Runkel, Schweigert] [Kapustin, Saulina][Niro, Roumpedakis, Sela]

is **a topological defect** !

…. but **is also a topological defect** ! SUGRA solution generating technique [SD, Raml]

Use the technology of defects and their fusion to understand **generalised T-duality Goal**:

 \rightarrow **problem:** fusion remained a difficult question

→ needed a way to **construct topological defects for non-Abelian Chern-Simons**…

 $S_{\text{unfolded}}[A_N, A_S] = S_{\text{CS}}[A_N] + S_{\text{CS}}[A_S] + S_D[\mathbb{A}]$ with $A_S \in \mathfrak{u}(1)_S^d$, $A_N \in \mathfrak{u}(1)_N^d$

 $S_{\text{unfolded}}[A_N, A_S] = S_{\text{CS}}[A_N] + S_{\text{CS}}[A_S] + S_D[\mathbb{A}]$ with $A_S \in \mathfrak{u}(1)_S^d$, $A_N \in \mathfrak{u}(1)_N^d$

 $S_{\text{folded}}[A_N, A_S] = S_{\text{CS}}[A_N] - S_{\text{CS}}[A_S] + S_D[\mathbb{A}]$

=

业

 $S_{\text{unfolded}}[A_N, A_S] = S_{\text{CS}}[A_N] + S_{\text{CS}}[A_S] + S_D[\mathbb{A}]$ with $A_S \in \mathfrak{u}(1)_S^d$, $A_N \in \mathfrak{u}(1)_N^d$

=

↓

个

$$
S_{\text{folded}}[A_N, A_S] = k \int_{M_N} \langle \langle \mathbb{A}, \mathrm{d}\mathbb{A} \rangle \rangle + S_D[\mathbb{A}]
$$

with $\mathbb{A} = (A_N, A_S) \in \mathfrak{u}(1)^{2d} = \mathfrak{u}(1)^d_N \oplus \mathfrak{u}(1)^d_S$

$$
\langle \langle \mathbb{X}, \mathbb{Y} \rangle \rangle = \langle X_N, Y_N \rangle - \langle X_S, Y_S \rangle
$$

In the **3d Abelian Chern-Simons**:

when does Chern-Simons theory **admit** a **topological surface** ?

Elegant algebraic answer: [Kapustin, Saulina] Look for **Lagrangian subalgebras** !

$$
S_{\text{CS}} = k \int_{M_N} \langle \! \langle \mathbb{A}, \mathrm{d} \mathbb{A} \rangle \! \rangle \qquad \text{where} \quad \langle \! \langle \mathbb{X}, \mathbb{Y} \rangle \! \rangle = \langle X_N, Y_N \rangle - \langle X_S, Y_S \rangle
$$

with gauge group $\mathfrak{u}(1)^{2d} = \mathfrak{u}(1)^d_N \oplus \mathfrak{u}(1)^d_S$

$$
S_{\text{CS}} = k \int_{M_N} \langle \langle \mathbb{A}, \mathrm{d} \mathbb{A} \rangle \rangle \quad \text{where} \quad \langle \langle \mathbb{X}, \mathbb{Y} \rangle \rangle = \langle X_N, Y_N \rangle - \langle X_S, Y_S \rangle
$$

with gauge group $\mathfrak{u}(1)^{2d} = \mathfrak{u}(1)^d_N \oplus \mathfrak{u}(1)^d_S$

Varying the action

$$
\delta S_{\text{CS}} = 2 k \int_{M_N} \langle \! \langle \delta \mathbb{A}, \mathrm{d} \mathbb{A} \rangle \! \rangle + k \int_D \langle \! \langle \delta \mathbb{A}, \mathbb{A} \rangle \! \rangle
$$

e.o.m. $F[A] \equiv dA = 0$

Vanishes by the requires a **boundary cond**. that we will take to be **topological**

Demand that $\mathbb{A}|_D \in \mathbb{C}$ **Lagrangian subspace** S" of $\mathfrak{u}(1)^{2d} = \mathfrak{u}(1)^d_N \oplus \mathfrak{u}(1)^d_S$ $\langle \langle X, Y \rangle \rangle = 0 \quad \forall X, Y \in S$

$$
S_{\text{CS}} = k \int_{M_N} \langle \langle \mathbb{A}, \mathrm{d} \mathbb{A} \rangle \rangle \quad \text{where} \quad \langle \langle \mathbb{X}, \mathbb{Y} \rangle \rangle = \langle X_N, Y_N \rangle - \langle X_S, Y_S \rangle
$$

with gauge group $\mathfrak{u}(1)^{2d} = \mathfrak{u}(1)^d_N \oplus \mathfrak{u}(1)^d_S$

Varying the action

$$
\delta S_{\text{CS}} = 2 k \int_{M_N} \langle \! \langle \delta \mathbb{A}, \mathrm{d} \mathbb{A} \rangle \! \rangle + k \int_D \langle \! \langle \delta \mathbb{A}, \mathbb{A} \rangle \! \rangle
$$

e.o.m. $F[A] \equiv dA = 0$

Vanishes by the requires a **boundary cond** that we will take to be **topological**

Demand that $\mathbb{A}|_D \in \mathbb{C}$ **Lagrangian subspace** S " of $\mathfrak{u}(1)^{2d} = \mathfrak{u}(1)^d_N \oplus \mathfrak{u}(1)^d_S$ $\langle \langle X, Y \rangle \rangle = 0 \quad \forall X, Y \in S$

Instead of **boundary condition**: include the **boundary term**

$$
S = k \int_{M_N} \langle \! \langle \mathbb{A} \, , \mathrm{d} \mathbb{A} \rangle \! \rangle + k \int_D \langle \! \langle \mathbb{A} \, , P_{_S} \, \mathbb{A} \rangle \! \rangle
$$

For **Abelian Chern-Simons**, the gauge group is

$$
\mathfrak{u}(1)^{2d}=\mathfrak{u}(1)^d_N\oplus \mathfrak{u}(1)^d_S
$$

Take the **two Lagrangians**

For **Abelian Chern-Simons**, the gauge group is

$$
\mathfrak{u}(1)^{2d}=\mathfrak{u}(1)^d_N\oplus \mathfrak{u}(1)^d_S
$$

Take the **two Lagrangians**

diagonal :
$$
\mathfrak{u}(1)^d_+ = \{(X_N, X_S) \in \mathfrak{u}(1)^{2d} \mid X_N = X_S\}
$$
,
anti-diagonal : $\mathfrak{u}(1)^d_- = \{(X_N, X_S) \in \mathfrak{u}(1)^{2d} \mid X_N = -X_S\}$

N **Yields the fusion algebra**

$$
\mathfrak{u}(1)^d_-\circ \mathfrak{u}(1)^d_-=\mathfrak{u}(1)^d_+\qquad \mathfrak{u}(1)^d_+\circ \mathfrak{h}=\mathfrak{h}\ ,\qquad \mathfrak{h}\circ \mathfrak{u}(1)^d_+=\mathfrak{h}
$$

$$
S \qquad \qquad \text{That is } \left(\left\{ \mathfrak{u}(1)_{+}^{d}, \mathfrak{u}(1)_{-}^{d} \right\}, \circ \right) \cong \mathbb{Z}_{2}
$$

identity idempotent

5/13

Topological surfaces in non-Abelian Chern-Simons

In the **3d non-Abelian Chern-Simons**:

when does Chern-Simons theory **admit** a **topological surface** ?

$$
S_{\text{CS}} = k \int_{M_N} \left(\langle\!\langle \mathbb{A} \, , \mathrm{d} \mathbb{A} \rangle\!\rangle + \frac{1}{3} \langle\!\langle \mathbb{A} \, , \mathbb{[A \, , \mathbb{A}]\rangle\!\rangle \right)
$$

$$
\mathbb{A} = (A_N, A_S) \in \mathfrak{d} = \mathfrak{g}_N \oplus \mathfrak{g}_S \qquad \langle\langle \mathbb{X}, \mathbb{Y} \rangle\rangle = \langle X_N, Y_N \rangle - \langle X_S, Y_S \rangle
$$

Topological surfaces in non-Abelian Chern-Simons

In the **3d non-Abelian Chern-Simons**:

when does Chern-Simons theory **admit** a **topological surface** ?

$$
S_{\text{CS}} = k \int_{M_N} \left(\langle\!\langle \mathbb{A} \, , \mathrm{d} \mathbb{A} \rangle\!\rangle + \frac{1}{3} \langle\!\langle \mathbb{A} \, , \mathbb{[A \, , \mathbb{A}]\rangle\!\rangle \right)
$$

$$
\mathbb{A} = (A_N, A_S) \in \mathfrak{d} = \mathfrak{g}_N \oplus \mathfrak{g}_S \qquad \langle\langle \mathbb{X}, \mathbb{Y} \rangle\rangle = \langle X_N, Y_N \rangle - \langle X_S, Y_S \rangle
$$

We showed: [Arvanitakis, Cole, SD, Thompson]

- → Canonical way to **construct topological defects**
- → Crucial tool: **(modified) Yang-Baxter equation**
- → Defined and **studied their fusion**

Lagrangians via the mCYBE: *R***-defects**

Strategy: simplify one's life a little by looking for a subclass of defects

Solve the **modified classical Yang-Baxter equation**

$$
[\mathcal{R} X \, , \mathcal{R} Y] - \mathcal{R}([\mathcal{R} X \, , Y] + [X \, , \mathcal{R} Y]) + [X \, , Y] = 0 \qquad \qquad X, Y \in \mathfrak{g}
$$

Yields a **Lagrangian subalgebra**

$$
\mathfrak{g}_{\mathcal{R}} = \{ \big((\mathcal{R} + 1)X, (\mathcal{R} - 1)X \big) \in \mathfrak{d} \}
$$

With Lie-bracket $[X, Y]_{\mathcal{R}} = [\mathcal{R}X, Y] + [X, \mathcal{R}Y]$

Lagrangians via the mCYBE: *R***-defects**

Strategy: simplify one's life a little by looking for a subclass of defects

Solve the **modified classical Yang-Baxter equation**

$$
[\mathcal{R} X \, , \mathcal{R} Y] - \mathcal{R}\big([\mathcal{R} X \, , Y] + [X \, , \mathcal{R} Y]\big) + [X \, , Y] = 0 \qquad \qquad X,Y \in \mathfrak{g}.
$$

 $\mathfrak{g}_{\mathcal{R}} = \{ ((\mathcal{R} + 1)X, (\mathcal{R} - 1)X) \in \mathfrak{d} \}$ Yields a **Lagrangian subalgebra**

With Lie-bracket $[X, Y]_{\mathcal{R}} = [\mathcal{R}X, Y] + [X, \mathcal{R}Y]$

Called a "bi-algebra" or "Manin triple" $\mathfrak{d} = \mathfrak{g}_{\Delta} \oplus \mathfrak{g}_{\mathcal{R}}$

 \rightarrow Directly generalises the Abelian case $\mu(1)^{2d} = \mu(1)^d_A \oplus \mu(1)^d_-$

 \rightarrow Technical requirement $\mathfrak{d} = \mathfrak{g}_{\Delta} \oplus \mathfrak{g}_{\mathcal{R}} \cong \mathfrak{g} \oplus \mathfrak{g}$

Effectively specialising to **non-compact algebras**

South

North

Lagrangians via the mCYBE: *R***-defects**

We have a **topological boundary condition** for the Lagrangian subalgebra

$$
\mathfrak{g}_{\mathcal{R}} = \{ \big((\mathcal{R} + 1)X, (\mathcal{R} - 1)X \big) \in \mathfrak{d} \}
$$

Since with the **R-matrix** we can construct a **projector**

$$
\langle\!\langle \mathbb{A}\, , \mathcal{P}_{\mathcal{R}} \mathbb{A} \rangle\!\rangle = \langle A_S \, , A_N \rangle + \frac{1}{2} \langle A_N - A_S \, , \mathcal{R}(A_N - A_S) \rangle
$$

Yielding the (folded) Chern-Simon action

$$
S_{\text{folded}} = \int \text{CS}[\mathbb{A}] + \int_D \langle \langle \mathbb{A}, \mathcal{P}_{\mathcal{R}} \mathbb{A} \rangle \rangle
$$
\n
$$
\longrightarrow \text{Notbing}
$$

$$
\mathfrak{h}_{NI} \circ \mathfrak{h}_{IS} = \Pi_{NS} \Big(\big(\mathfrak{h}_{NI} \oplus \mathfrak{h}_{IS} \big) \cap \big(\mathfrak{g}_{N} \oplus \mathfrak{g}_{\Delta} \oplus \mathfrak{g}_{S} \big) \Big)
$$

$$
\big\downarrow
$$

$$
\circ \mathfrak{a}_{\Box} = \frac{\int (X_{11} \times \overline{X}_{12}) \cap \mathfrak{d} \times \overline{X}_{13}}{\prod_{i=1}^{3} \overline{X}_{1i}^{(i)}} = \overline{X}_{1i}^{(i)} \times \overline{X}_{1i}^{(i)} = \overline{X}_{1i}^{(i)}
$$

 $\mathfrak{g}_{\mathcal{R}}\circ\mathfrak{g}_{\mathcal{R}}=\{(X_N,X_S)\in\mathfrak{d}\mid X_N^{\mathfrak{t}}=X_S^{\mathfrak{t}}\;, X_N^-=0\;, X_S^+=0\}$

 \rightarrow Proved that $\mathfrak{h}_{NI} \circ \mathfrak{h}_{IS}$ is

- ✓ Lagrangian
- ✓ a subalgebra
- with identity element $g_{\Delta} \circ \mathfrak{h} = \mathfrak{h}$, $\mathfrak{h} \circ g_{\Delta} = \mathfrak{h}$
- ‣ reduces to Lagrangian fusion in the Abelian case

AdS₃ gravity a re-formulation in terms of Chern-Simons theories

$$
S_{\text{grav}} = S_{\text{CS}}[A] - S_{\text{CS}}[\bar{A}] + S_{\text{bdy}}
$$

"folded" Chern-Simons theory for the gauge group $\mathfrak{sl}(2,\mathbb{R})\oplus\mathfrak{sl}(2,\mathbb{R})$

Where the **gauge connections** are related to the **metric vielbein and the soldering form**

$$
A^a = \omega^a + \frac{1}{\ell} e^a \; , \qquad \tilde{A}^a = \omega^a - \frac{1}{\ell} e^a
$$

With respect to the $\mathfrak{sl}(2,\mathbb{R})$ -generators $[L_a,L_b]=(a-b)L_{a+b}$

AdS₃ higher-spin gravity

"folded" Chern-Simons theory for the gauge group $\mathfrak{st}(2,\mathbb{R})$

Where the **gauge connections** are related to the **metric vielbein and the soldering form**

$$
A^a = \omega^a + \frac{1}{\ell} e^a \; , \qquad \tilde{A}^a = \omega^a - \frac{1}{\ell} e^a
$$

 $\phi_{\mu_1...\mu_{s-1}\mu_s} \sim \text{Tr}\left(e_{(\mu}...e_{\mu_{s-1}}e_{\mu_s})\right)$ **and with spin fields**

AdS₃ gravity a re-formulation in terms of Chern-Simons theories

$$
S_{\text{grav}} = S_{\text{CS}}[A] - S_{\text{CS}}[\bar{A}] + S_{\text{bdy}}
$$

"folded" Chern-Simons theory for the gauge group $\mathfrak{sl}(2,\mathbb{R})\oplus\mathfrak{sl}(2,\mathbb{R})$

AdS₃ gravity a re-formulation in terms of Chern-Simons theories

$$
S_{\text{grav}} = S_{\text{CS}}[A] - S_{\text{CS}}[\bar{A}] + S_{\text{bdy}}
$$

"folded" Chern-Simons theory for the gauge group $\mathfrak{sl}(2,\mathbb{R})\oplus\mathfrak{sl}(2,\mathbb{R})$

In the Feffer-Graham gauge the boundary term is [Llabres; Apolo; Ebert, Hijano, Kraus, Monten, Myers]

$$
S_{\text{bdy}} = \frac{k}{4\pi} \int_{\partial M} \text{tr} \, A \wedge \bar{A} - \frac{k}{2\pi} \int_{\partial M} \text{tr} \left(L_0 (A - \bar{A}) \wedge (A - \bar{A}) \right)
$$

Cartan generator of $\mathfrak{sl}(2, \mathbb{R})$

The R-boundary term where the R-matrix is the **Drinfel'd-Jimbo R-matrix** for $\mathfrak{sl}(2,\mathbb{R})$

$$
S_{\text{bdy}} = \int_{\partial M} \langle A, \bar{A} \rangle - \frac{1}{2} \langle \bar{A} - A, \mathcal{R}(\bar{A} - A) \rangle \qquad \mathcal{R}L_0 = 0, \qquad \mathcal{R}L_{\pm} = \pm L_{\pm}
$$

$$
= \frac{k}{4\pi} \int_{\partial M} \text{tr} \, A \wedge \bar{A} - \frac{k}{2\pi} \int_{\partial M} \text{tr} \left(L_0(A - \bar{A}) \wedge (A - \bar{A}) \right)
$$

matches precisely the bdy term from GHY

AdS3 higher-spin gravity

More generally we can always define **boundary term**

$$
S_{\text{bdy}} = \int_{\partial M} \langle A, \bar{A} \rangle - \frac{1}{2} \langle \bar{A} - A, \mathcal{R}(\bar{A} - A) \rangle
$$

where the R-matrix is the **Drinfel'd-Jimbo R-matrix** for $\mathfrak{sl}(N,\mathbb{R})$

$$
\mathcal{R}H_i=0\;,\quad \mathcal{R}E_\alpha=+c\,E_\alpha\;,\quad \mathcal{R}E_{-\alpha}=-c\,E_{-\alpha}
$$

 \rightarrow get a canonical boundary condition for higher spin AdS_3 gravity

AdS₃ higher-spin gravity

More generally we can always define **boundary term**

$$
S_{\text{bdy}} = \int_{\partial M} \langle A, \bar{A} \rangle - \frac{1}{2} \langle \bar{A} - A, \mathcal{R}(\bar{A} - A) \rangle
$$

where the R-matrix is the **Drinfel'd-Jimbo R-matrix** for $\mathfrak{sl}(N,\mathbb{R})$

$$
\mathcal{R}H_i=0\;,\quad \mathcal{R}E_\alpha=+c\,E_\alpha\;,\quad \mathcal{R}E_{-\alpha}=-c\,E_{-\alpha}
$$

 \rightarrow get a canonical boundary condition for higher spin AdS_3 gravity

For example for $$f(3,\mathbb{R})$ -gravity

$$
S_{\text{bdy}} = \int_{\partial M} \langle A, \bar{A} \rangle - \frac{k}{2\pi} \langle \bar{A} - A \wedge \mathcal{R}_{\text{DJ}}(\bar{A} - A) \rangle
$$

=
$$
\int_{\partial M} \langle A, \bar{A} \rangle - \frac{k}{4\pi} \int_{\partial M} \text{tr}[(A - \bar{A}) \wedge (A - \bar{A})L_0]
$$

+
$$
\frac{k}{64\pi} \int_{\partial M} \text{tr}[(A - \bar{A})W_{+2}] \wedge \text{tr}[(A - \bar{A})W_{-2}].
$$

Coincides with the boundary term constructed by [Apolo]

See review [Campoleoni, Fredenhagen]

Gauge transfo *A* $\delta A = d\lambda + [A, \lambda]$ \updownarrow $\delta e = d\xi + [\omega, \xi] + [e, \Lambda]$ $\xi = \frac{\ell}{2} (\lambda - \tilde{\lambda})$

diffeos metric

Celebrated result: **Brown-Henneaux boundary conditions** → **two copies of Virasoro**

$$
A - A_{\text{AdS}} \sim \mathcal{O}(1) \qquad \bar{A} - \bar{A}_{\text{AdS}} \sim \mathcal{O}(1)
$$

Instead the **R-boundary condition** (and **restricting to** *AAdS3*)

[Arvanitakis, Cole, SD, Thompson] [Campoleoni, Fredenhagen, Raeymaekers]

$$
(\mathcal{R}-1)A=(\mathcal{R}+1)\bar{A}
$$

↓

Free **boson realisation** of a **single copy of Virasoro**

→ **Summary**

Constructed **topological boundary conditions in non-Abelian Chern-Simons**

- ‣ Led to a subclass: R-defects
- ‣ Looked into their fusion
- Application to $AdS₃$ -gravity

 \rightarrow What's next?

- ‣ Can we identify the surface defect for Poisson-Lie T-duality ?
- ‣ Does the R-defect boundary make sense in higher spin 3d gravity
- ‣ SymTFT description ?

Thank you for your attention !