

# Symmetries - Killing Vectors

Isometries

Killing Vector Fields

Conserved Quantities (during geodesic motion)

Symmetries

Carroll §3.8-3.9  
Ferrari et al Ch. 8

# Isometries

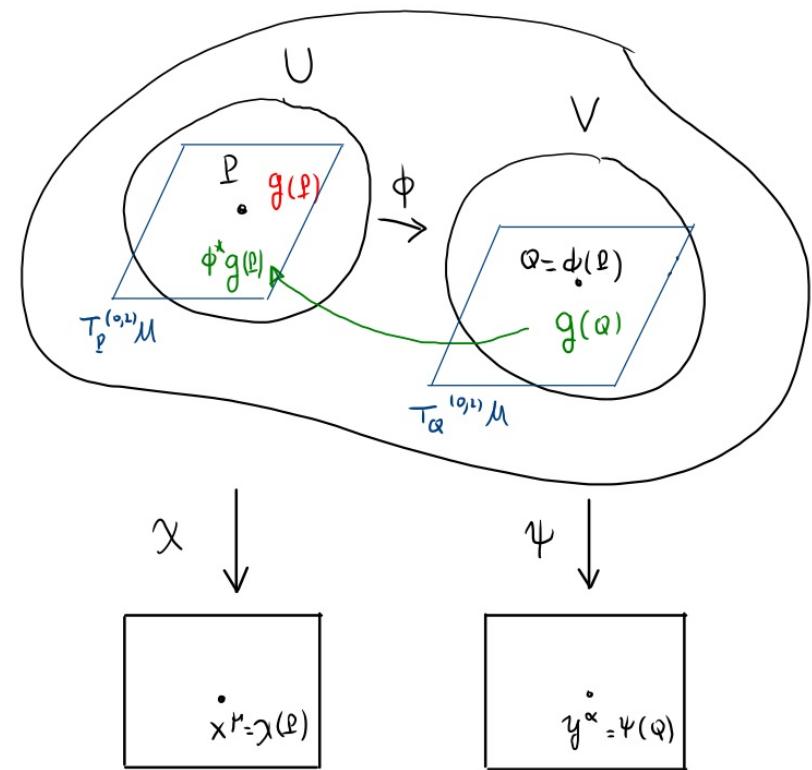
invertible, differentiable

\* Let  $\phi: M \rightarrow M$  a diffeomorphism

$$P \mapsto Q = \phi(P)$$

and charts  $(U, \chi)$ ,  $(V, \psi)$  s.t.

$$x^{\mu} = \chi(P) \quad y^{\alpha} = \psi(Q)$$



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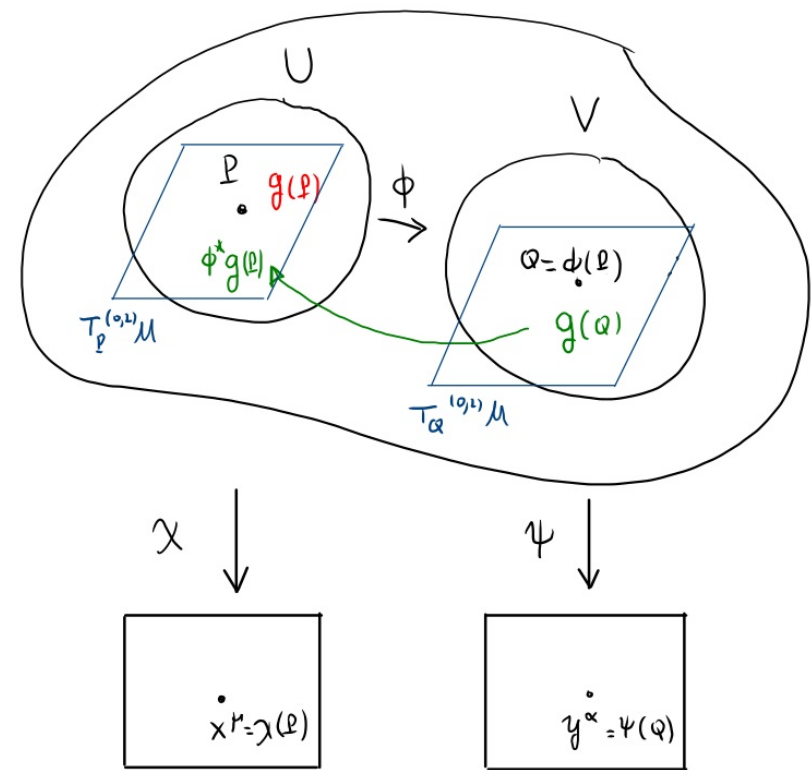
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$g(x) \in T_P^{(0,2)}M$  acts on  $T_P M$

$g(y) \in T_Q^{(0,2)}M$  " "  $T_Q M$



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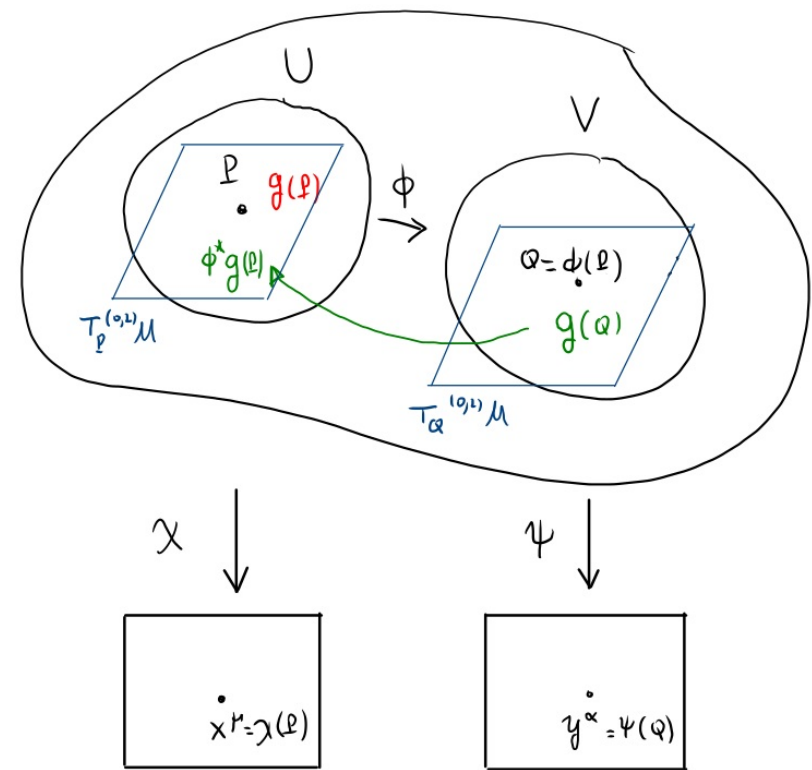
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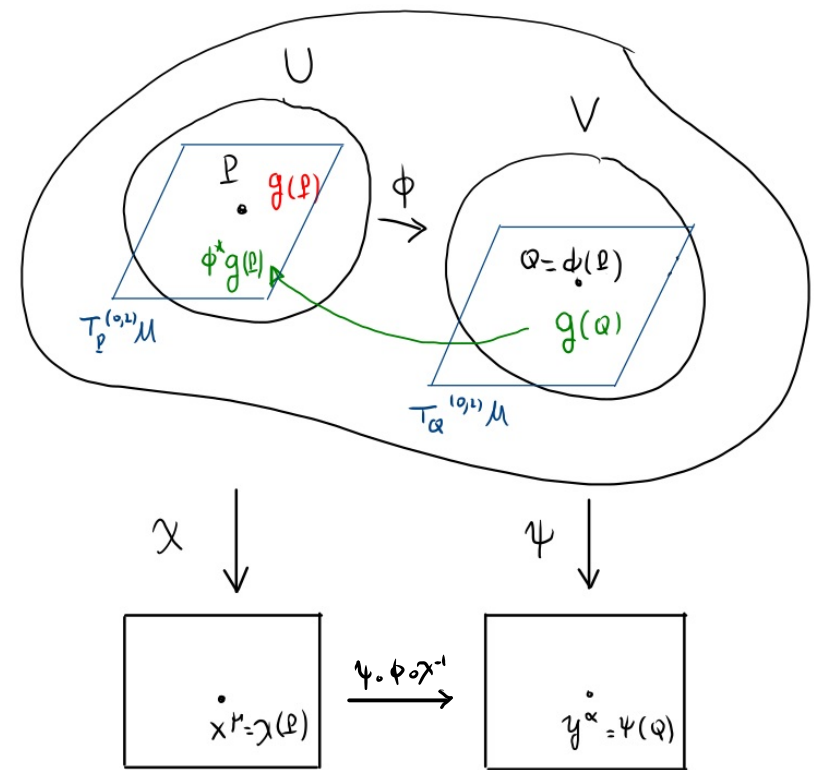
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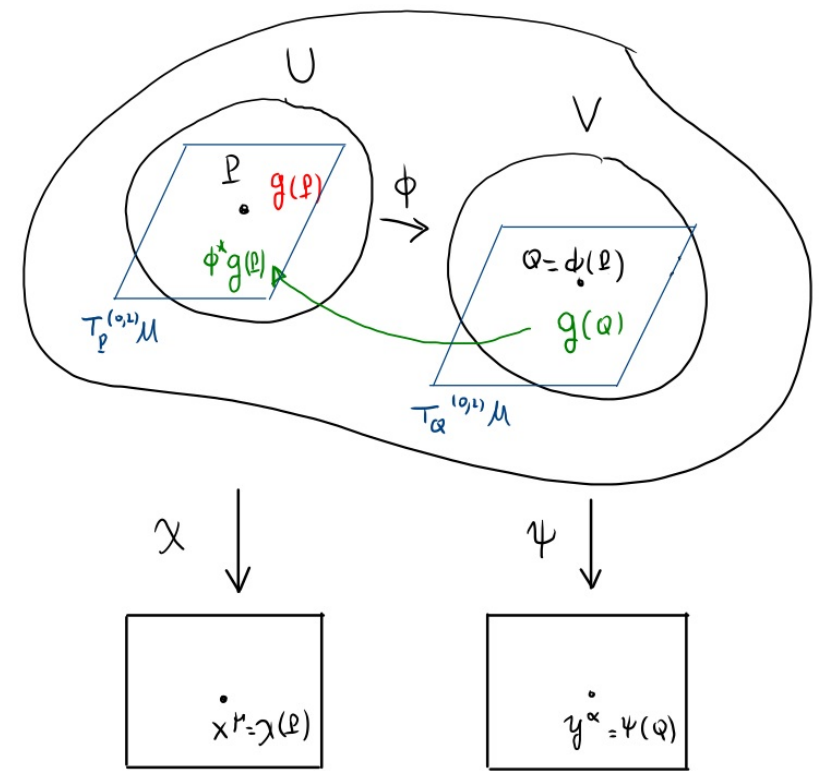
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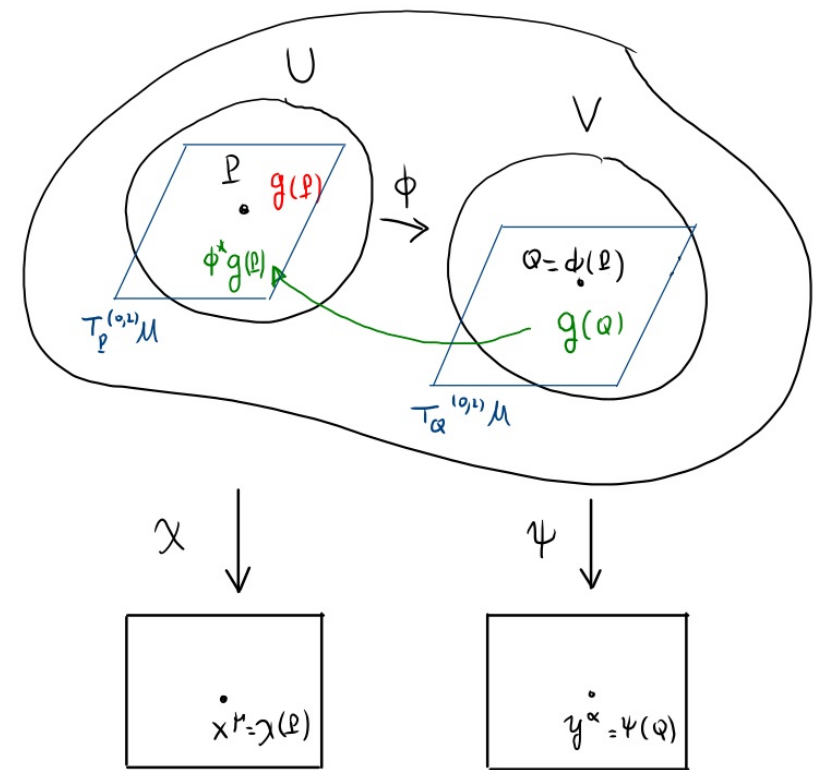

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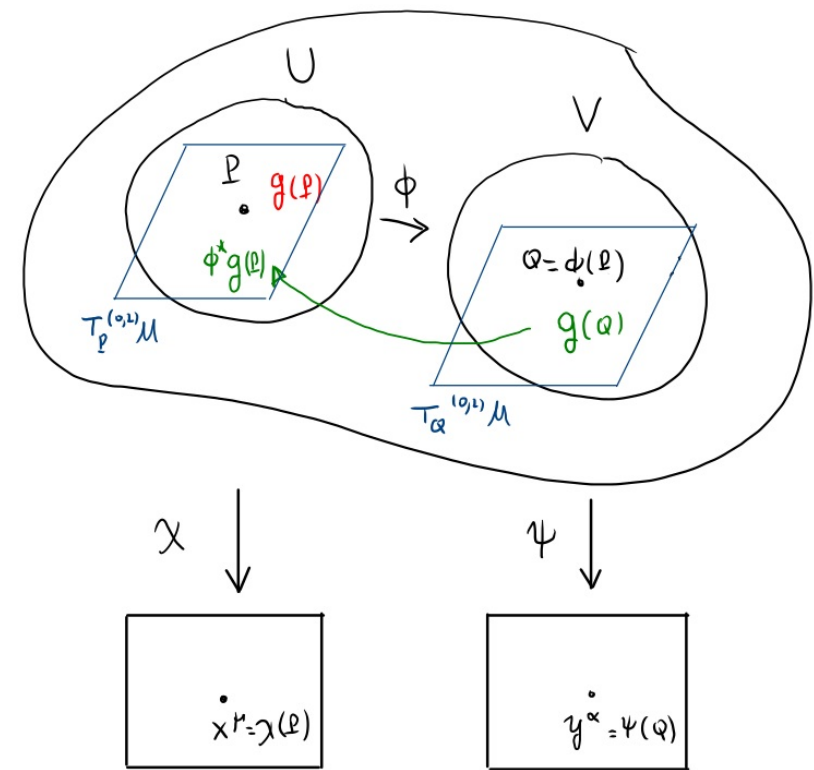
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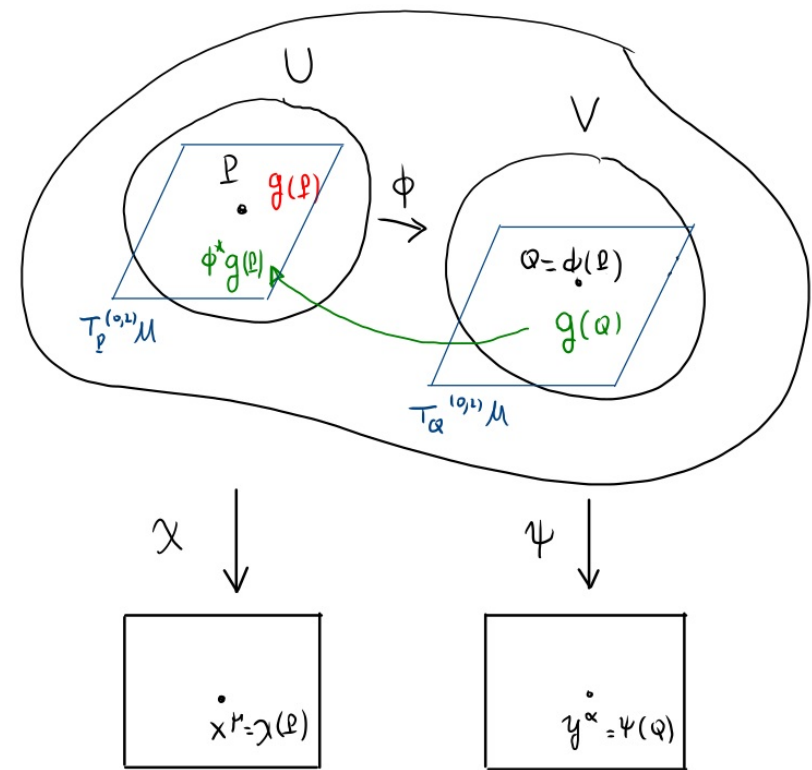
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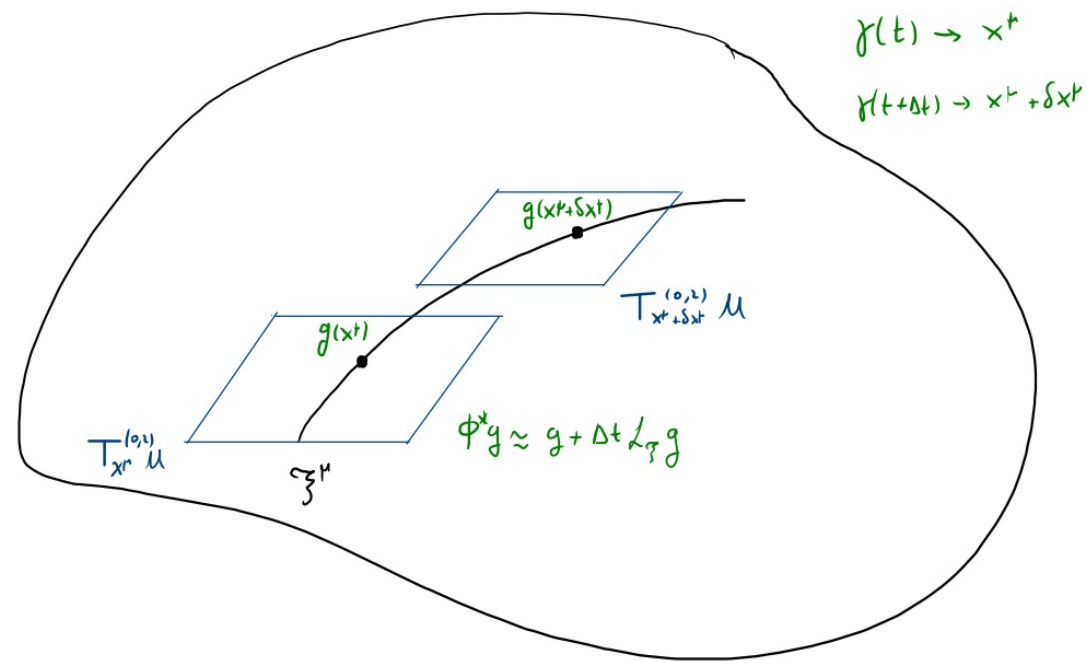
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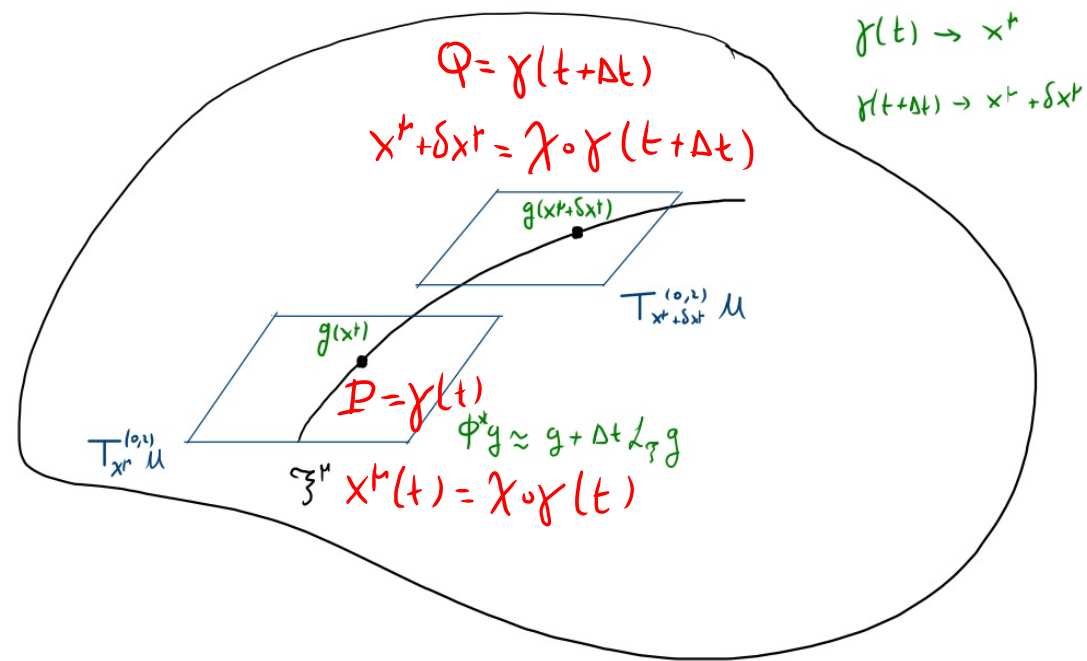
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The curve goes through  $P = \gamma(t)$  and  $Q = \gamma(t + \Delta t)$ ,  $Q = \phi_{\Delta t}(P) \equiv \phi(P)$

$\hookrightarrow$  generated by  $\mathcal{I} = \frac{d}{dt}$



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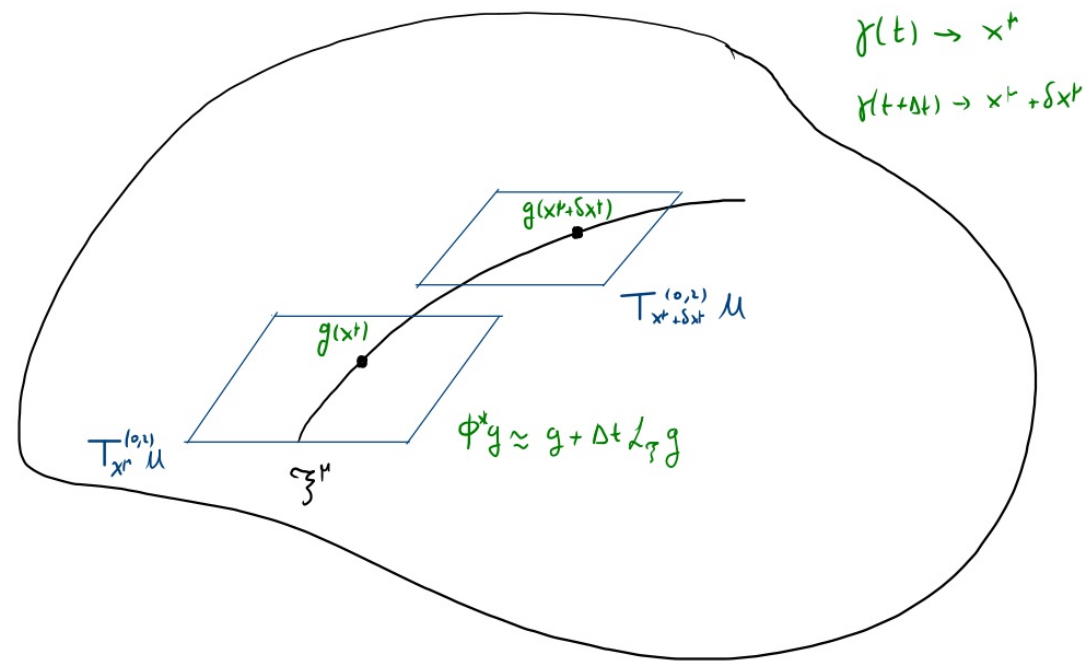
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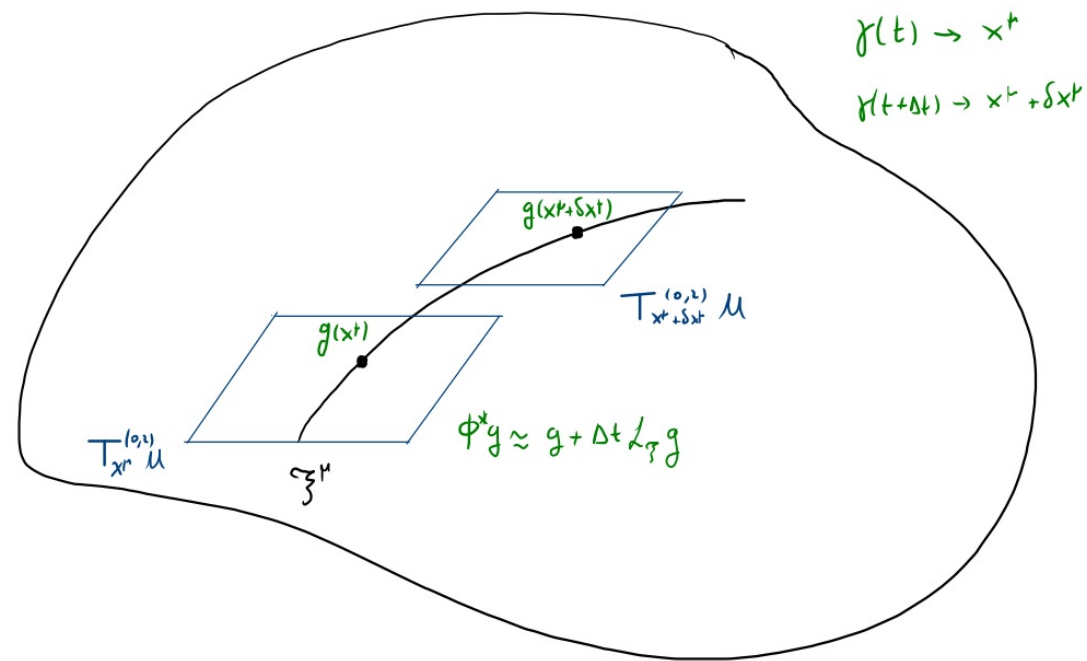
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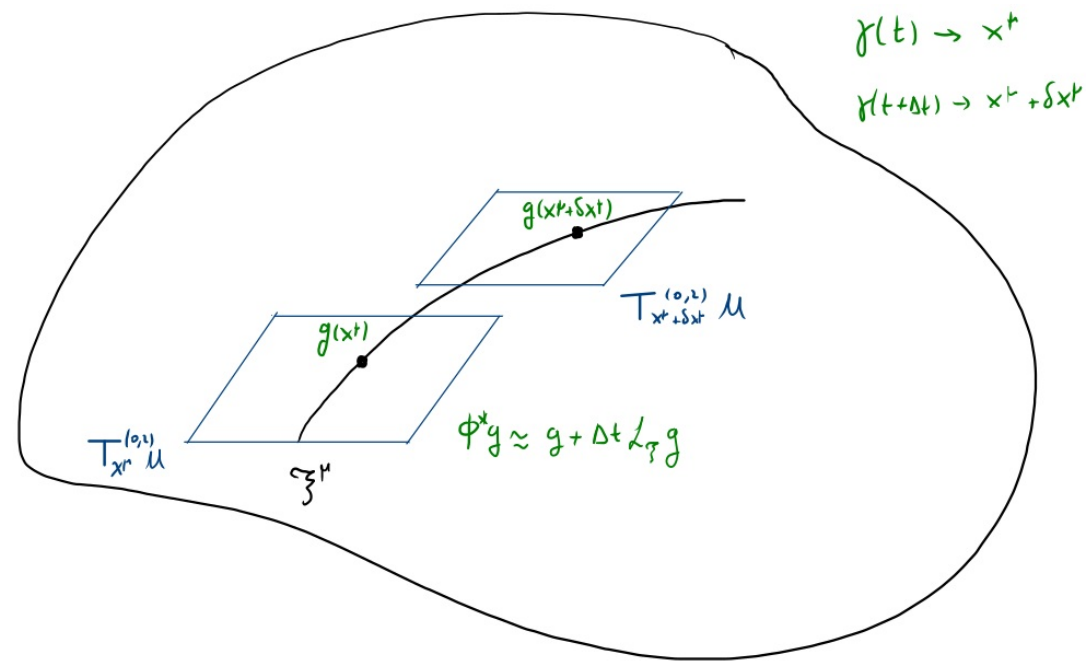
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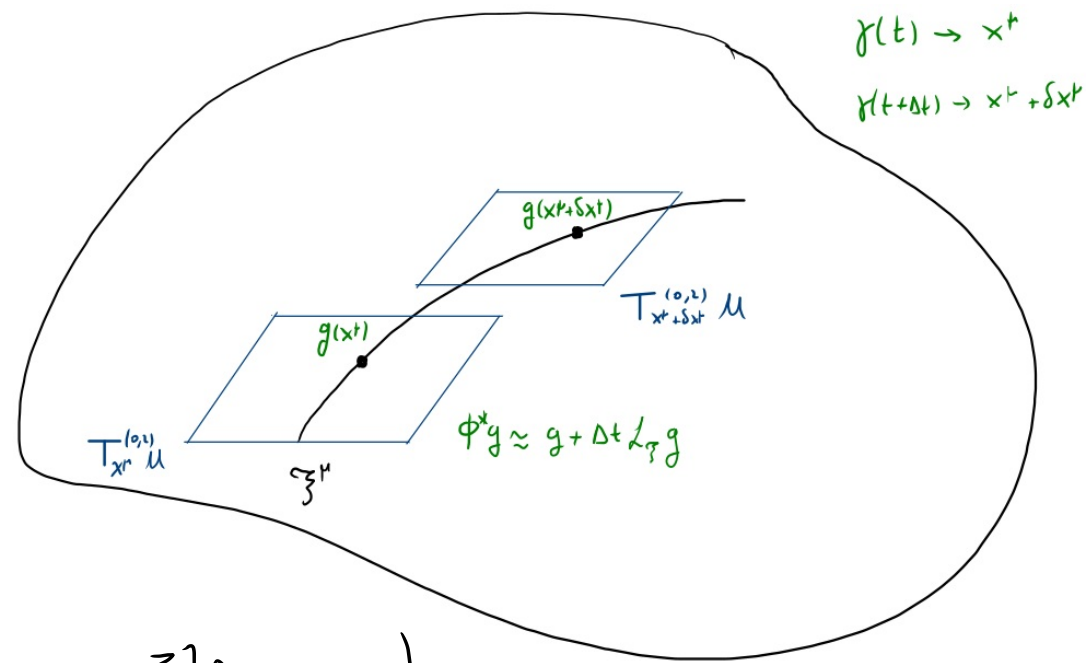
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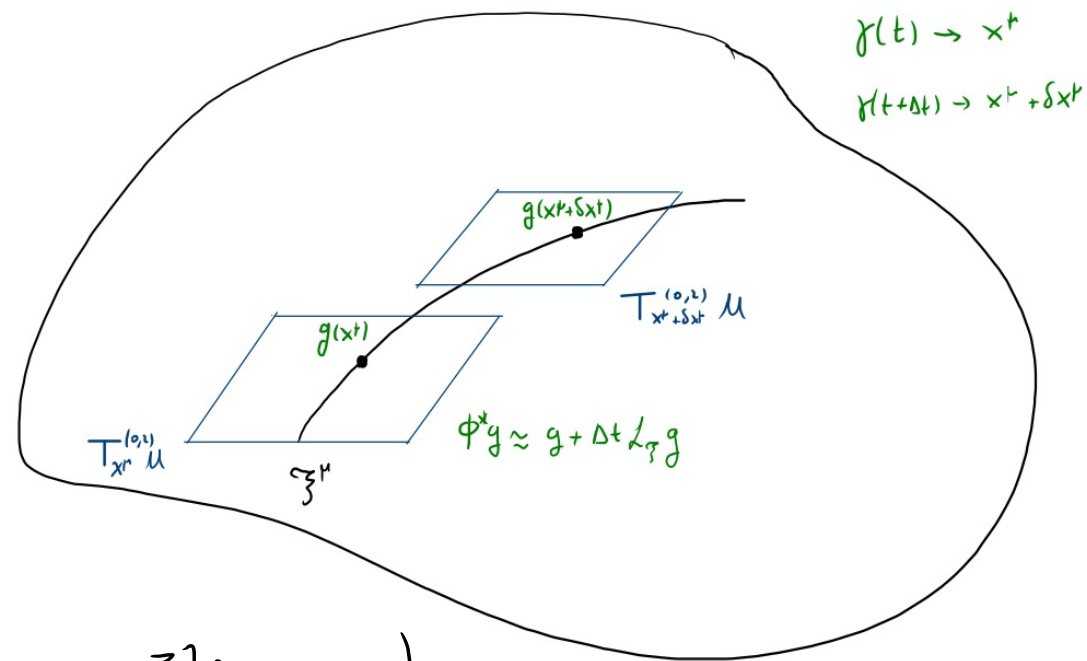
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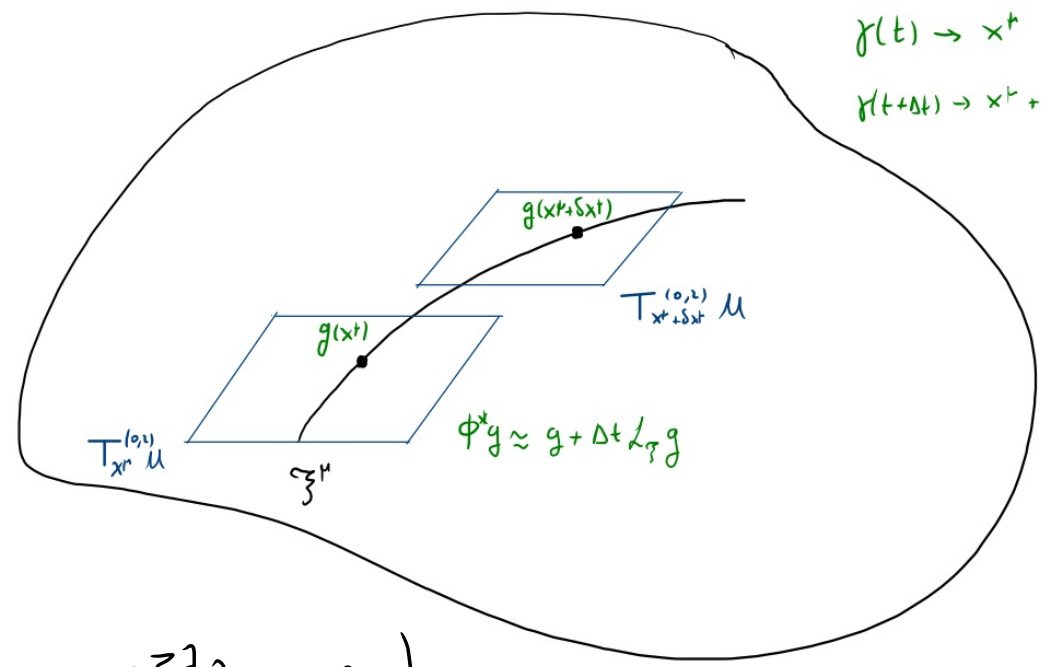
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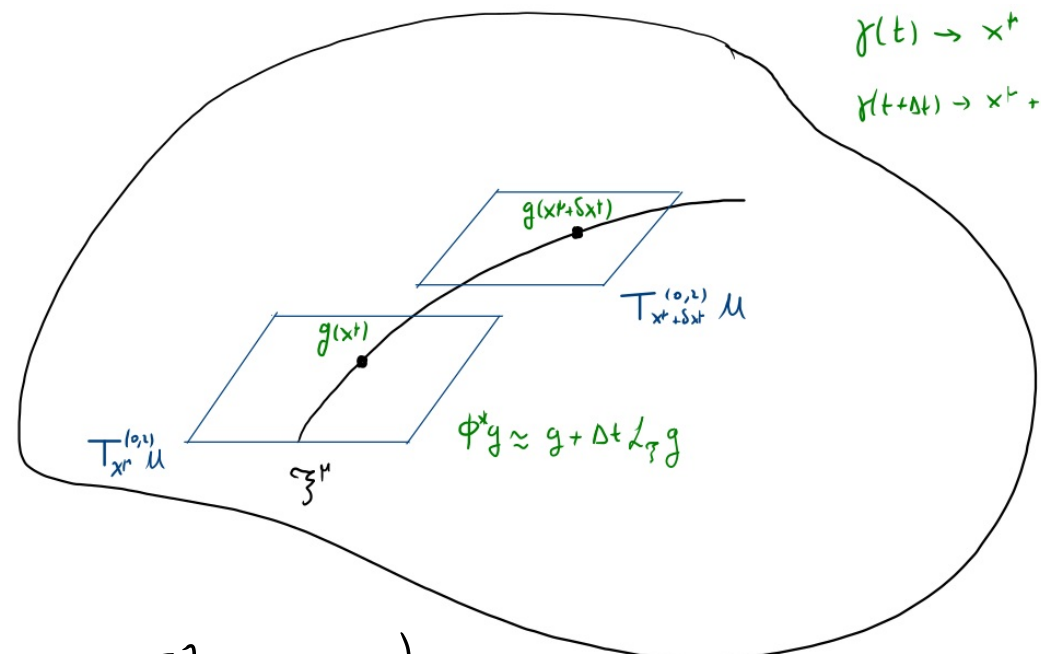
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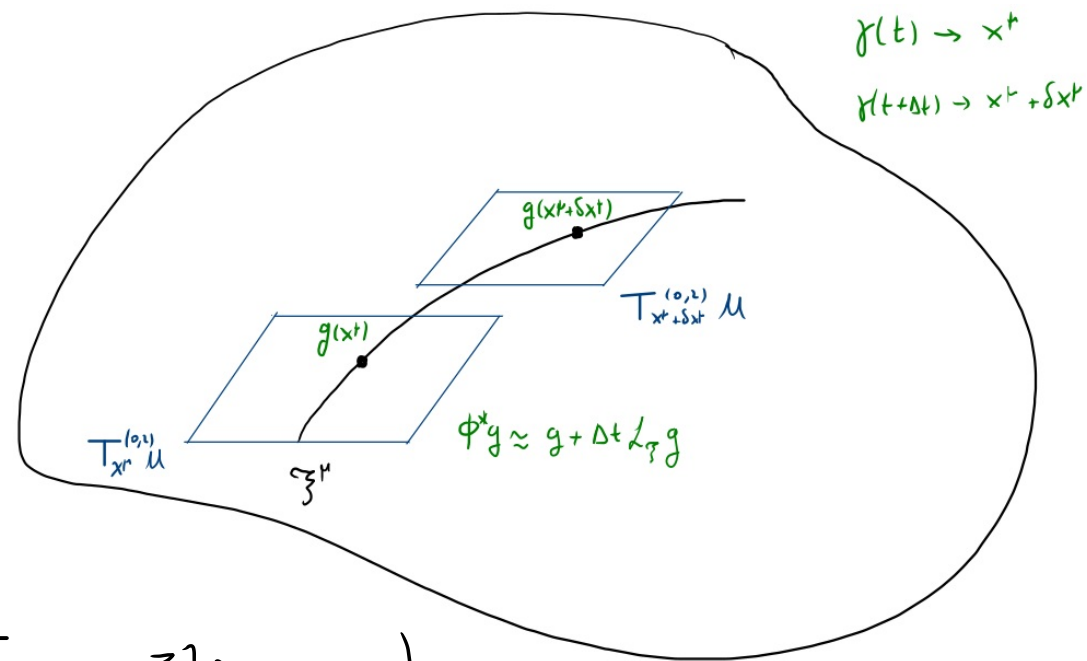


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$$\Rightarrow \mathcal{L}_{\xi} g_{\mu\nu} = 0$$



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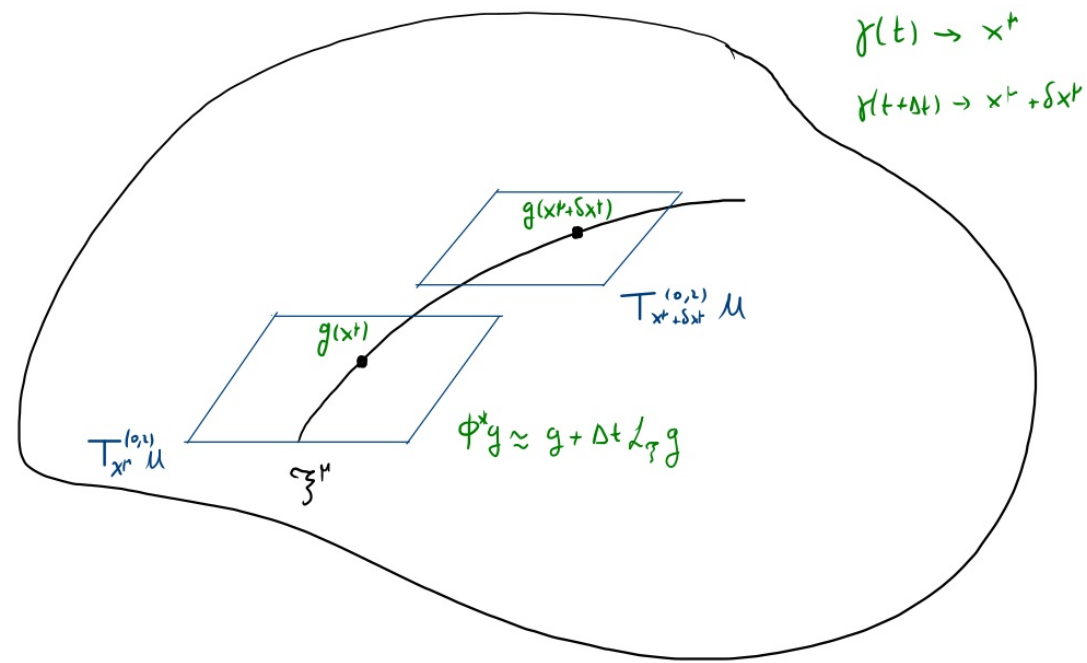
$$\Rightarrow \mathcal{L}_\xi g_{\mu\nu} = 0$$

- No surprise:

$$\mathcal{L}_\xi g(t) = \lim_{\epsilon \rightarrow 0} \frac{\phi_{t+\epsilon}^* g(t) - g(t)}{\epsilon} \Rightarrow \phi^* g = g + \epsilon \mathcal{L}_\xi g + \mathcal{O}(\epsilon^2)$$

- A local condition: differential equations to be solved

- May or may not have solutions. E.g. on compact manifolds with  $R < 0$ , no solutions!



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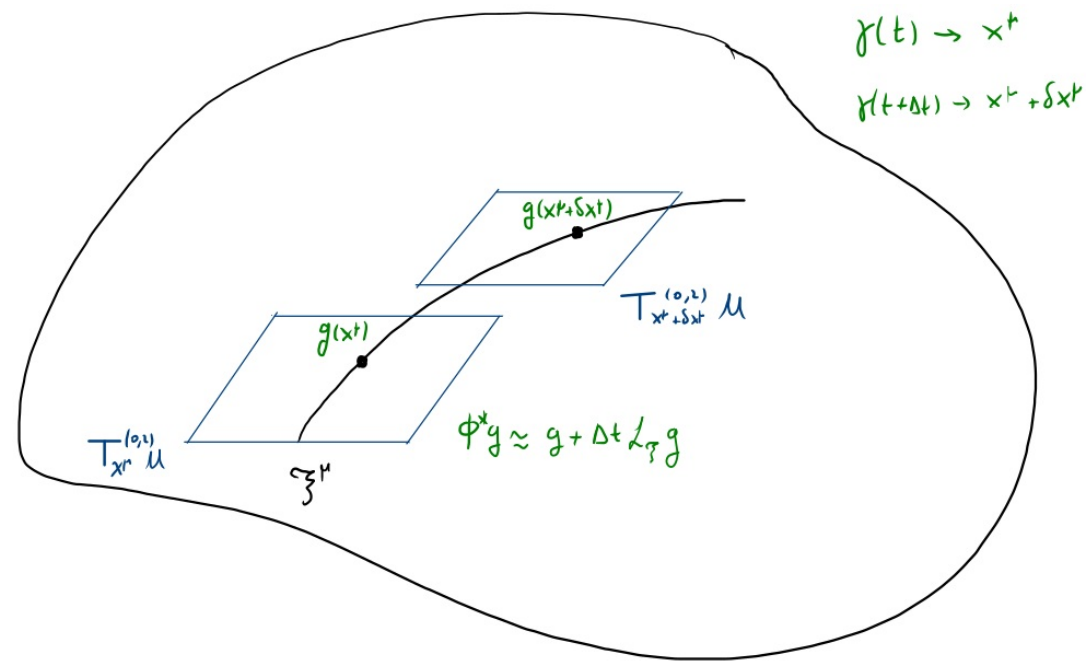
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- May have local solutions, but not global  
 e.g. in a coordinate system



Show that  $\delta_{\xi} g_{\mu\nu} = \nabla_{\mu} \xi_{\nu} + \nabla_{\nu} \xi_{\mu}$

$\nabla$ : Christoffel connection ( $\nabla g = 0, \nabla T = 0$ )

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$$\nabla_\mu \xi_\nu = g_{\nu\lambda} \nabla_\mu \xi^\lambda = g_{\nu\lambda} [\partial_\mu \xi^\lambda + \Gamma^\lambda_{\mu\rho} \xi^\rho]$$

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$\Rightarrow$

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$$\nabla_\mu \xi_\nu + \nabla_\nu \xi_\mu = g_{\nu\lambda} \partial_\mu \xi^\lambda + g_{\mu\lambda} \partial_\nu \xi^\lambda + 2 \cdot \frac{1}{2} \partial_\rho g_{\mu\nu} \xi^\rho$$

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$\Rightarrow$

---

$$\nabla_\mu \xi_\nu + \nabla_\nu \xi_\mu = g_{\nu\lambda} \partial_\mu \xi^\lambda + g_{\mu\lambda} \partial_\nu \xi^\lambda + \partial_\rho g_{\mu\nu} \xi^\rho = \mathcal{L}_\xi g_{\mu\nu}$$

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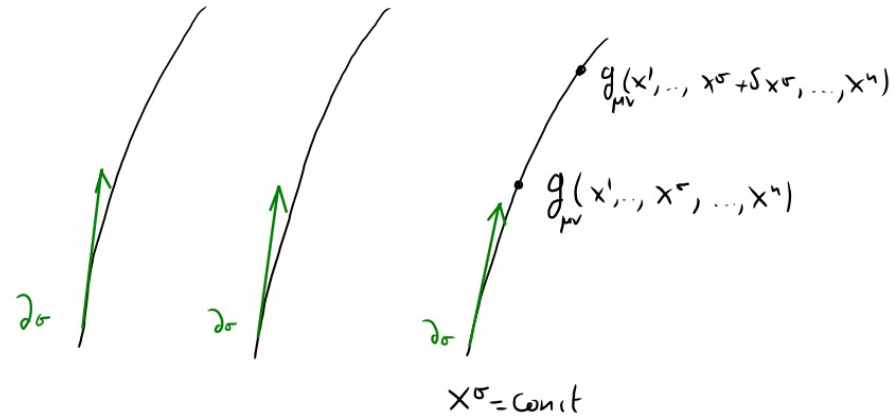
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$$\Rightarrow \mathcal{L}_{[\xi, \chi]} g = [\mathcal{L}_\xi, \mathcal{L}_\chi] g = (\mathcal{L}_\xi \mathcal{L}_\chi g - \mathcal{L}_\chi \mathcal{L}_\xi g) = \mathcal{L}_\xi(\mathcal{L}_\chi g) - \mathcal{L}_\chi(\mathcal{L}_\xi g) = 0$$

# Killing Vector Fields & Coordinate Independence of $g_{\mu\nu}$

If  $\exists$  coordinate system, s.t.  $g_{\mu\nu}(x)$  is independent of  $x^\sigma \Rightarrow \partial_\sigma g_{\mu\nu} = 0$

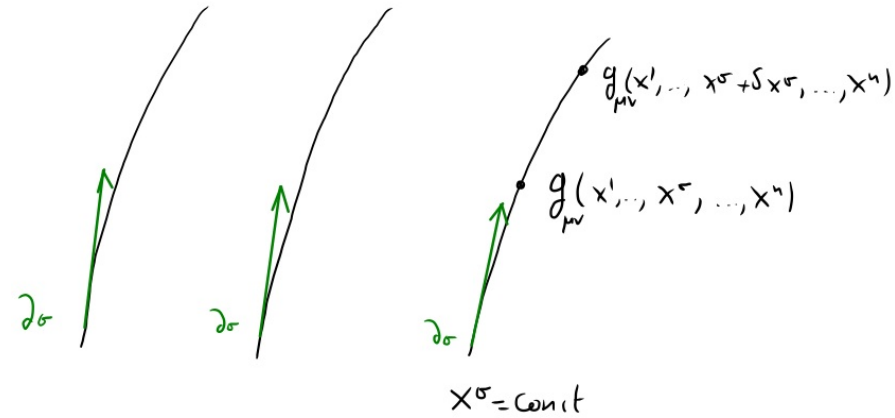


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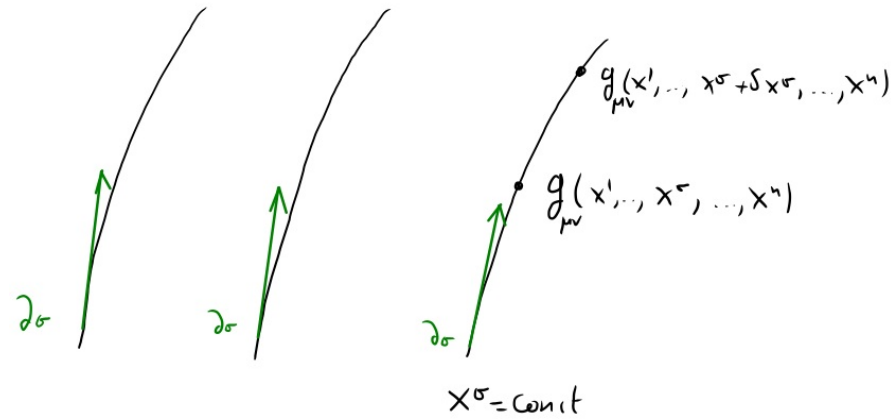


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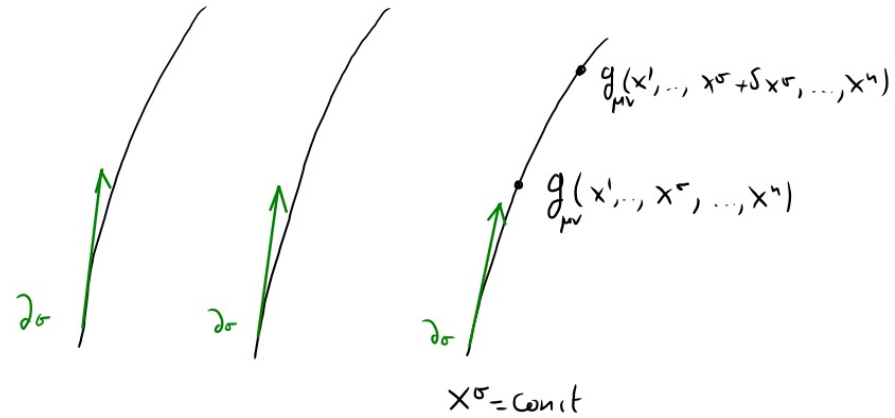


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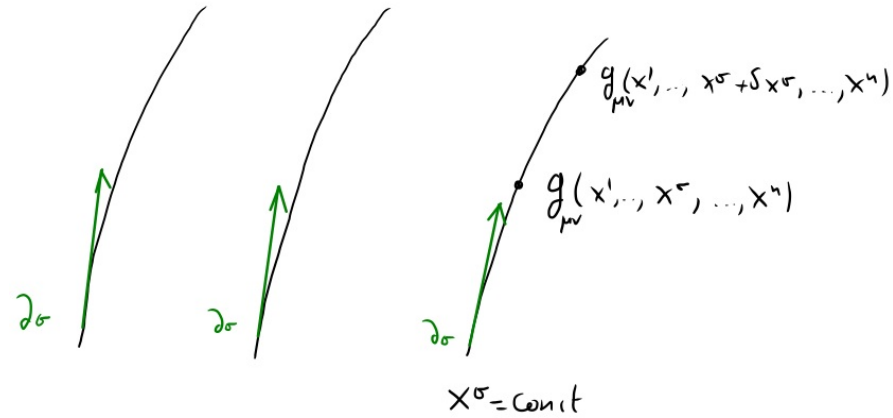


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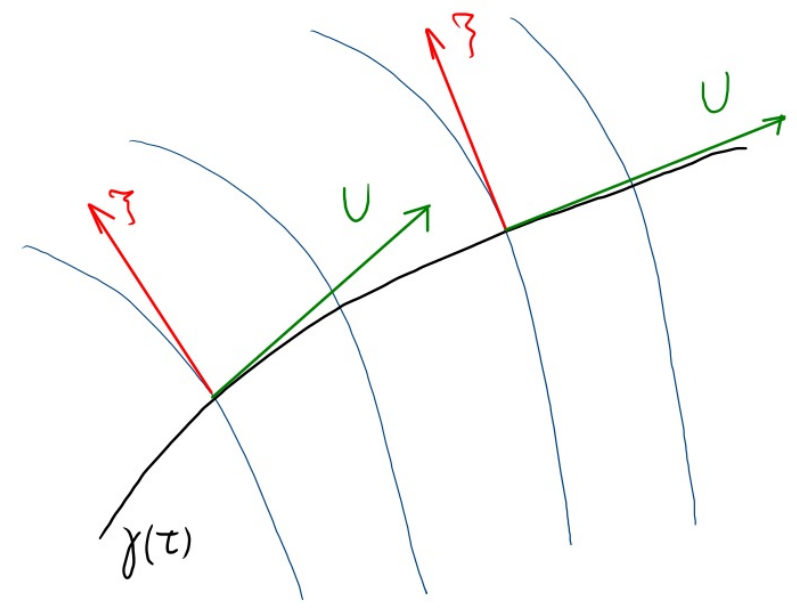
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# Conserved Quantities

- let  $\xi$  be a Killing vector field
- "  $\gamma(\tau)$  " " geodesic with  $\begin{cases} \text{affine parameter } \tau \\ \text{tangent vector } U \end{cases}$

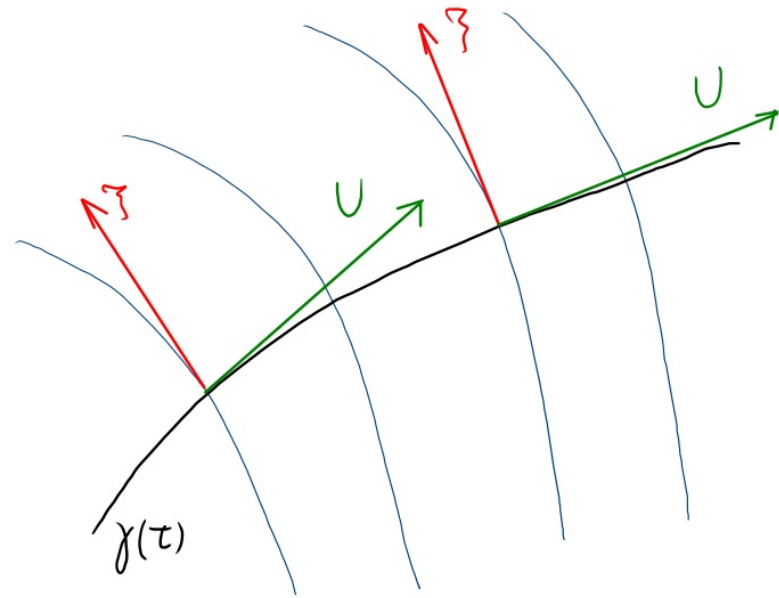




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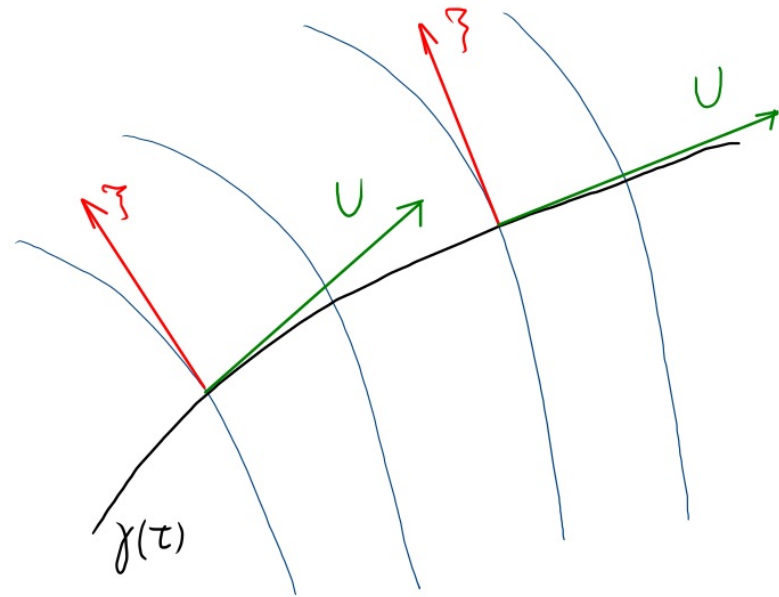


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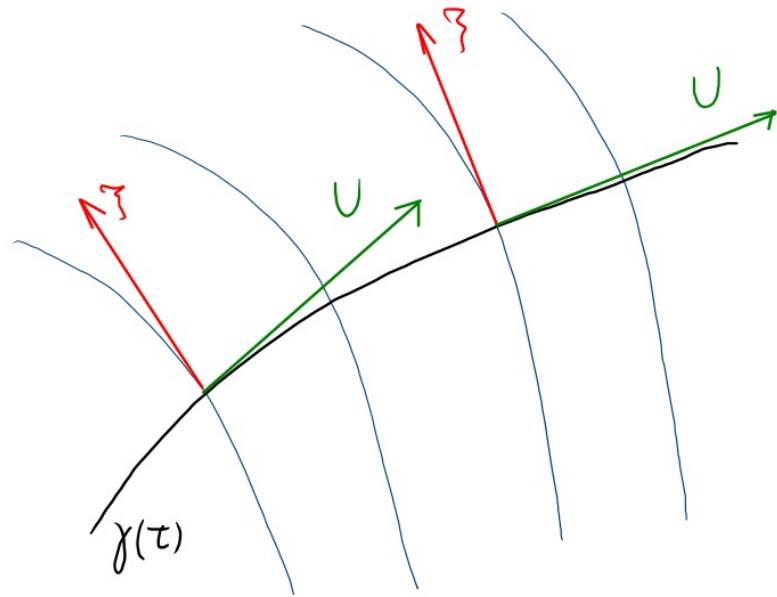
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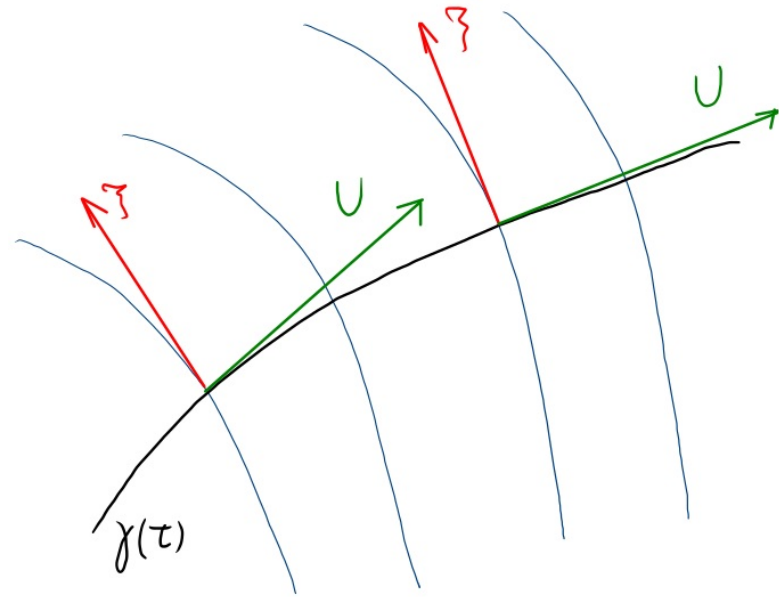
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# Conserved Quantities

Indeed:

$$U^\nu \nabla_\nu (\xi_\mu U^\mu) = U^\nu [\nabla_\nu \xi_\mu U^\mu + \xi_\mu \nabla_\nu U^\mu]$$



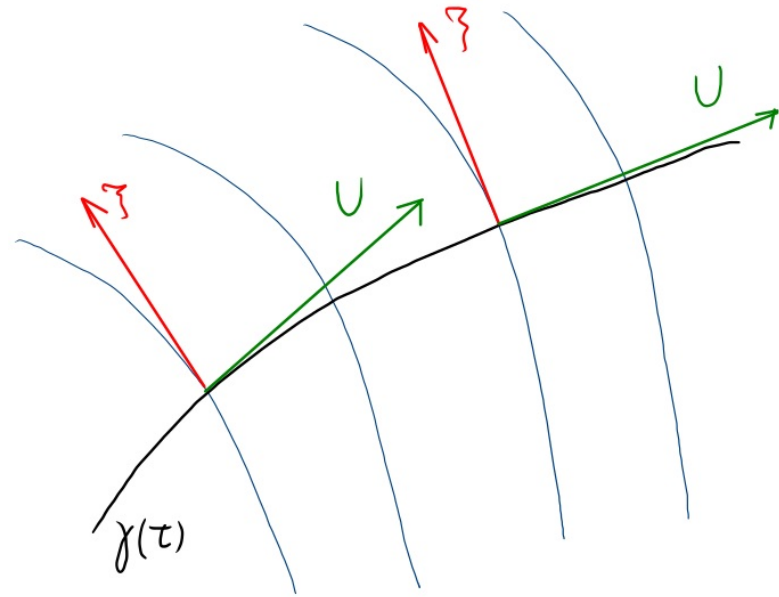
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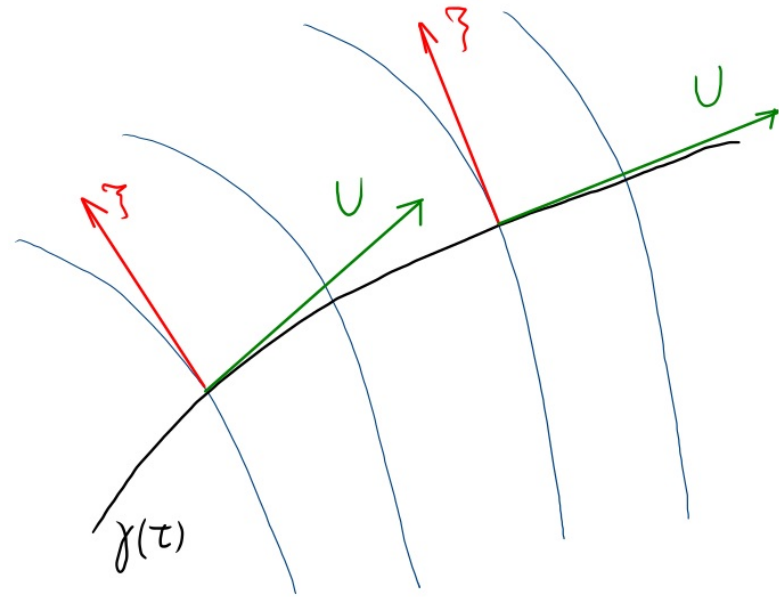
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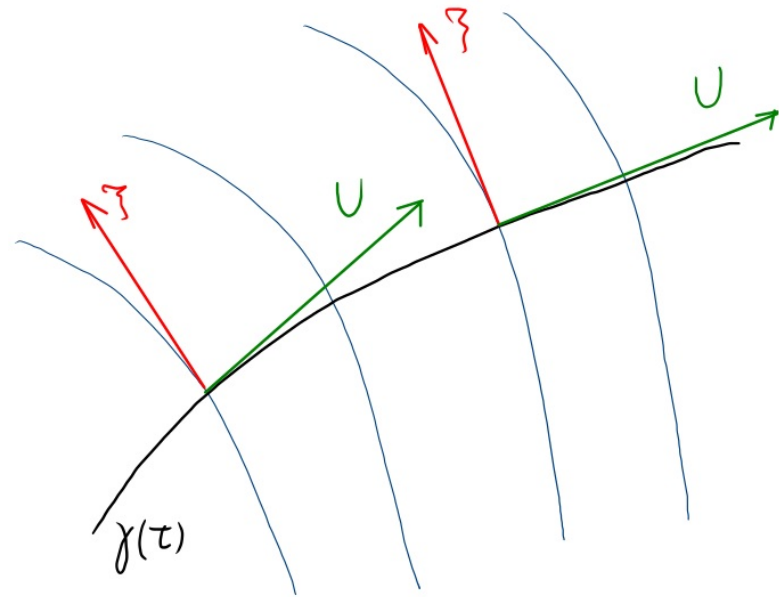
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$$U^\nu U^\mu \nabla_\nu \xi_\mu = U^\nu U^\mu \underbrace{\frac{1}{2} (\nabla_\nu \xi_\mu + \nabla_\mu \xi_\nu)}_{\text{Killing Eq.} \rightarrow 0} = U^\nu U^\mu \cdot 0 = 0$$



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Killing Eq.  
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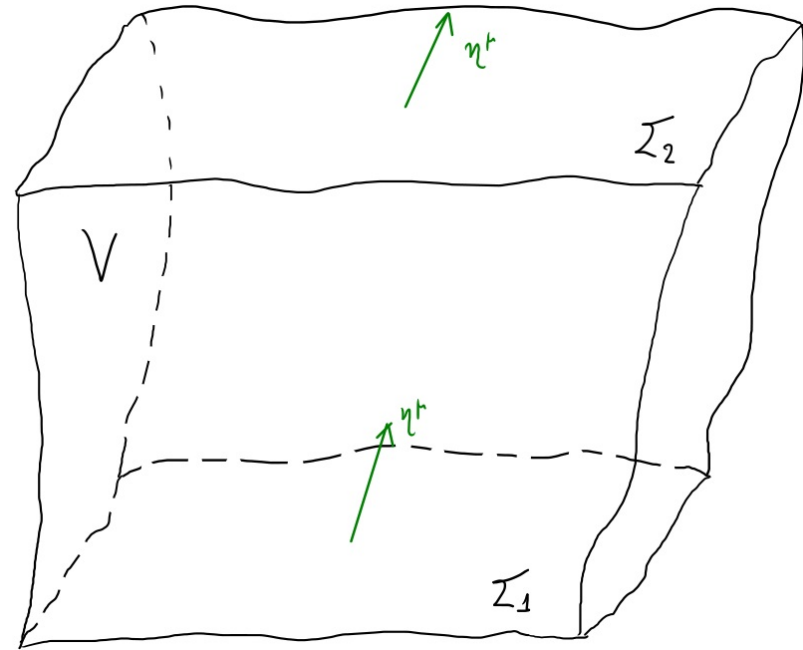
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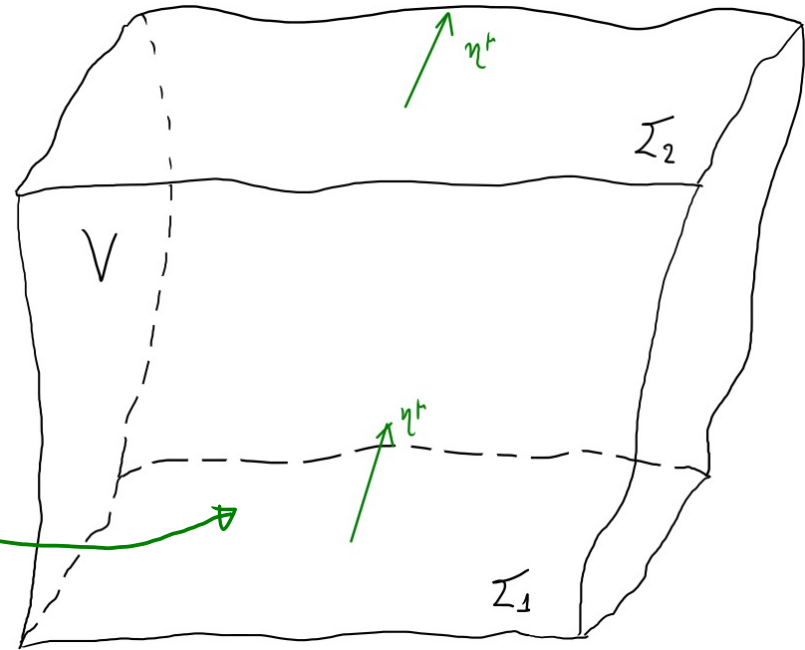
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$\rightarrow$  because we chose  $n^\mu$  to point "inward" in  $V$



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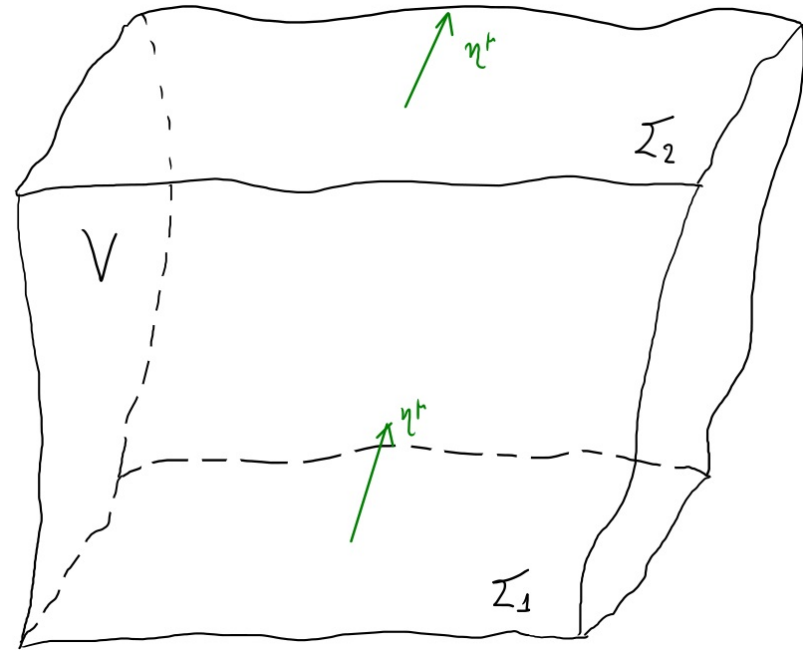
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+  ~~$\int_{\text{spatial infinity}} J_\mu n^\mu$~~   $\rightarrow$  assume  $J_\mu \rightarrow 0$  fast enough





# Conserved Quantities

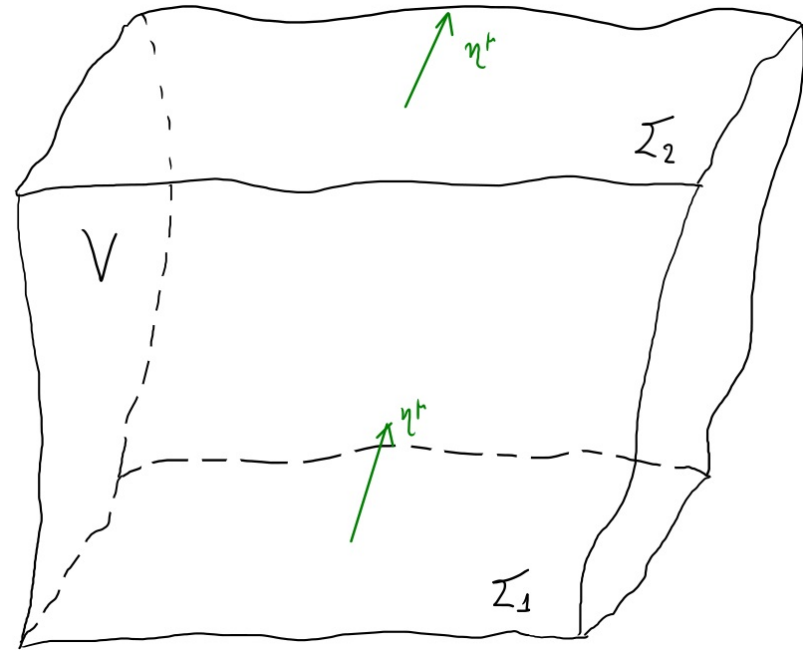
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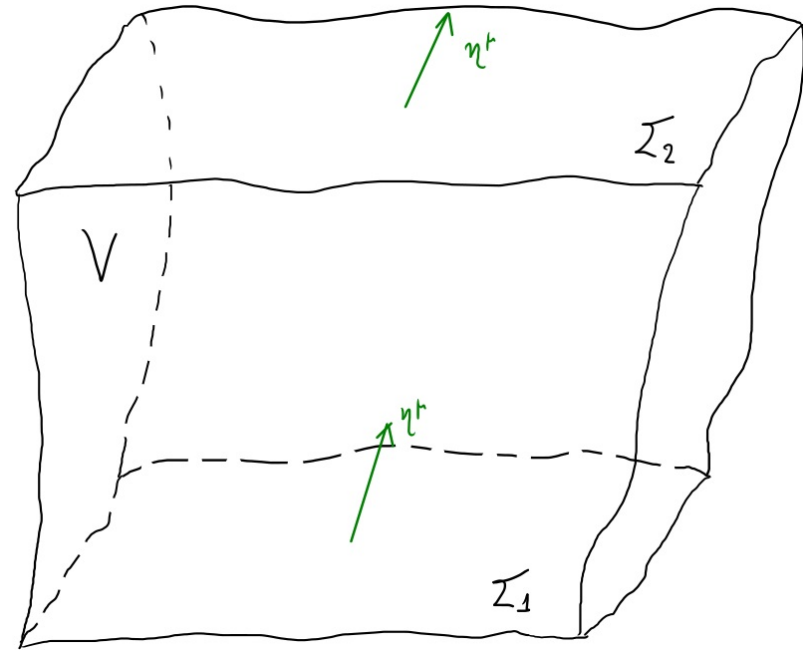
If we choose  $\xi^\mu = n^\mu = (\partial_0)^\mu$ , then

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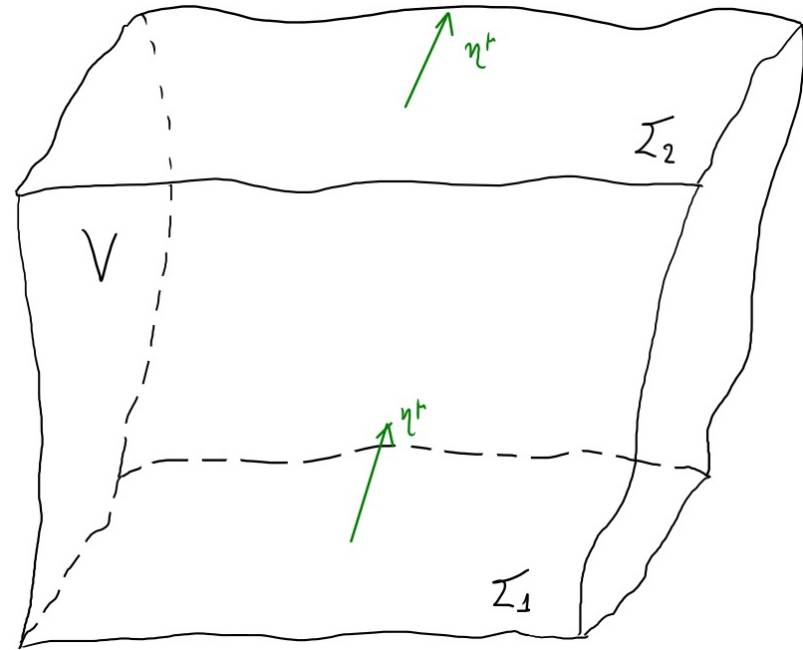
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$\xi$  timelike  $\rightarrow$  time symmetry  $\rightarrow$  energy conservation

$\hookrightarrow$  "static spacetimes"  $\nearrow$



Examples:  $S^2$

$$ds^2 = d\theta^2 + \sin^2\theta d\varphi^2$$

$$g_{\theta\theta} = 1 \quad g_{\varphi\varphi} = \sin^2\theta$$

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$$\nabla_{\lambda}^{\lambda} g_{\mu\nu} + g_{\lambda\nu} \partial_{\mu}^{\lambda} + g_{\mu\lambda} \partial_{\nu}^{\lambda} = 0$$

$(\theta, \theta)$

$$\nabla^{\lambda} \partial_{\lambda} g_{\theta\theta} + g_{\lambda\theta} \partial_{\theta}^{\lambda} + g_{\theta\lambda} \partial_{\theta}^{\lambda} = 0$$

$$g_{\theta\theta} \partial_{\theta}^{\theta} + g_{\theta\theta} \partial_{\theta}^{\theta} = 0$$

$$2 \cdot 1 \cdot \partial_{\theta}^{\theta} = 0 \Rightarrow \partial_{\theta}^{\theta} = 0$$

$(\theta, \varphi)$

$$\nabla^{\lambda} \partial_{\lambda} g_{\theta\varphi} + g_{\lambda\varphi} \partial_{\theta}^{\lambda} + g_{\theta\lambda} \partial_{\varphi}^{\lambda} = 0 \Rightarrow$$

$$g_{\varphi\varphi} \partial_{\theta}^{\varphi} + g_{\theta\theta} \partial_{\varphi}^{\theta} = 0$$

$$\sin^2\theta \partial_{\theta}^{\varphi} + \partial_{\varphi}^{\theta} = 0$$

$(\varphi, \varphi)$

$$\nabla^{\lambda} \partial_{\lambda} g_{\varphi\varphi} + g_{\lambda\varphi} \partial_{\varphi}^{\lambda} + g_{\varphi\lambda} \partial_{\varphi}^{\lambda} = 0$$

Examples:  $S^2$

$$ds^2 = d\theta^2 + \sin^2\theta d\varphi^2$$

$$g_{\theta\theta} = 1 \quad g_{\varphi\varphi} = \sin^2\theta$$

$$\zeta^1 \partial_\lambda g_{\mu\nu} + g_{\lambda\nu} \partial_\mu \zeta^1 + g_{\mu\lambda} \partial_\nu \zeta^1 = 0$$

$(\theta, \theta)$

$$\zeta^1 \partial_\lambda \cancel{g_{\theta\theta}} + g_{\lambda\theta} \partial_\theta \zeta^1 + g_{\theta\lambda} \partial_\theta \zeta^1 = 0$$

$$g_{\theta\theta} \partial_\theta \zeta^0 + g_{\theta\theta} \partial_\theta \zeta^0 = 0$$

$$2 \cdot 1 \cdot \partial_\theta \zeta^0 = 0 \Rightarrow \partial_\theta \zeta^0 = 0$$

$(\theta, \varphi)$

$$\zeta^1 \partial_\lambda \cancel{g_{\theta\varphi}} + g_{\lambda\varphi} \partial_\theta \zeta^1 + g_{\theta\lambda} \partial_\varphi \zeta^1 = 0 \Rightarrow$$

$$g_{\varphi\varphi} \partial_\theta \zeta^1 + g_{\theta\theta} \partial_\varphi \zeta^0 = 0$$

$$\sin^2\theta \partial_\theta \zeta^1 + \partial_\varphi \zeta^0 = 0$$

$(\varphi, \varphi)$

$$\zeta^1 \partial_\lambda g_{\varphi\varphi} + g_{\lambda\varphi} \partial_\varphi \zeta^1 + g_{\varphi\lambda} \partial_\varphi \zeta^1 = 0 \Rightarrow$$

$$\zeta^0 \partial_\theta g_{\varphi\varphi} + g_{\varphi\varphi} \partial_\varphi \zeta^1 + g_{\varphi\varphi} \partial_\varphi \zeta^1 = 0$$

Examples:  $S^2$

$$ds^2 = d\theta^2 + \sin^2\theta d\varphi^2$$

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$(\theta, \theta)$

$$\zeta^\lambda \partial_\lambda \cancel{g_{\theta\theta}} + g_{\lambda\theta} \partial_\theta \zeta^\lambda + g_{\theta\lambda} \partial_\theta \zeta^\lambda = 0$$

$$g_{\theta\theta} \partial_\theta \zeta^\theta + g_{\theta\theta} \partial_\theta \zeta^\theta = 0$$

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$$\zeta^\lambda \partial_\lambda \cancel{g_{\theta\varphi}} + g_{\lambda\varphi} \partial_\theta \zeta^\lambda + g_{\theta\lambda} \partial_\varphi \zeta^\lambda = 0 \Rightarrow$$

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$(\varphi, \varphi)$

$$\zeta^\lambda \partial_\lambda g_{\varphi\varphi} + g_{\lambda\varphi} \partial_\varphi \zeta^\lambda + g_{\varphi\lambda} \partial_\varphi \zeta^\lambda = 0 \Rightarrow$$

$$\zeta^\theta \partial_\theta g_{\varphi\varphi} + g_{\varphi\varphi} \partial_\varphi \zeta^\varphi + g_{\varphi\varphi} \partial_\varphi \zeta^\varphi = 0 \Rightarrow$$

$$\zeta^\theta \partial_\theta (\sin^2\theta) + \sin^2\theta \partial_\varphi \zeta^\varphi + \sin^2\theta \partial_\varphi \zeta^\varphi = 0$$

Examples:  $S^2$

$$ds^2 = d\theta^2 + \sin^2\theta d\varphi^2$$

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$$\zeta^\lambda \partial_\lambda \cancel{g_{\theta\varphi}} + g_{\lambda\varphi} \partial_\theta \zeta^\lambda + g_{\theta\lambda} \partial_\varphi \zeta^\lambda = 0 \Rightarrow$$

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$(\varphi, \varphi)$

$$\zeta^\lambda \partial_\lambda g_{\varphi\varphi} + g_{\lambda\varphi} \partial_\varphi \zeta^\lambda + g_{\varphi\lambda} \partial_\varphi \zeta^\lambda = 0 \Rightarrow$$

$$\zeta^\theta \partial_\theta g_{\varphi\varphi} + g_{\varphi\varphi} \partial_\varphi \zeta^\varphi + g_{\varphi\varphi} \partial_\varphi \zeta^\varphi = 0 \Rightarrow$$

$$\zeta^\theta \partial_\theta (\sin^2\theta) + \sin^2\theta \partial_\varphi \zeta^\varphi + \sin^2\theta \partial_\varphi \zeta^\varphi = 0 \Rightarrow$$

$$\zeta^\theta 2 \sin\theta \cos\theta + 2 \sin^2\theta \partial_\varphi \zeta^\varphi = 0$$

# Examples: $S^2$

$$ds^2 = d\theta^2 + \sin^2\theta d\varphi^2$$

$$g_{\theta\theta} = 1 \quad g_{\varphi\varphi} = \sin^2\theta$$

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$$\zeta^\lambda \partial_\lambda \cancel{g_{\theta\theta}} + g_{\lambda\theta} \partial_\theta \zeta^\lambda + g_{\theta\lambda} \partial_\theta \zeta^\lambda = 0$$

$$g_{\theta\theta} \partial_\theta \zeta^\theta + g_{\theta\theta} \partial_\theta \zeta^\theta = 0$$

$$2 \cdot 1 \cdot \partial_\theta \zeta^\theta = 0 \Rightarrow \partial_\theta \zeta^\theta = 0$$

$(\theta, \varphi)$

$$\zeta^\lambda \partial_\lambda \cancel{g_{\theta\varphi}} + g_{\lambda\varphi} \partial_\theta \zeta^\lambda + g_{\theta\lambda} \partial_\varphi \zeta^\lambda = 0 \Rightarrow$$

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$(\varphi, \varphi)$

$$\zeta^\lambda \partial_\lambda g_{\varphi\varphi} + g_{\lambda\varphi} \partial_\varphi \zeta^\lambda + g_{\varphi\lambda} \partial_\varphi \zeta^\lambda = 0 \Rightarrow$$

$$\zeta^\theta \partial_\theta g_{\varphi\varphi} + g_{\varphi\varphi} \partial_\varphi \zeta^\varphi + g_{\varphi\varphi} \partial_\varphi \zeta^\varphi = 0 \Rightarrow$$

$$\zeta^\theta \partial_\theta (\sin^2\theta) + \sin^2\theta \partial_\varphi \zeta^\varphi + \sin^2\theta \partial_\varphi \zeta^\varphi = 0 \Rightarrow$$

$$\zeta^\theta 2 \cancel{\sin\theta} \cos\theta + 2 \cancel{\sin\theta} \sin\theta \partial_\varphi \zeta^\varphi = 0 \Rightarrow$$

$$\cos\theta \zeta^\theta + \sin\theta \partial_\varphi \zeta^\varphi = 0 \Rightarrow$$

$$\partial_\varphi \zeta^\varphi + \cot\theta \zeta^\theta = 0$$

# Examples: $S^2$

$$\partial_\theta \zeta^0 = 0$$

$$\partial_\varphi \zeta^0 + \sin^2 \theta \partial_\theta \zeta^\varphi = 0$$

$$\partial_\varphi \zeta^\varphi + \cot \theta \zeta^0 = 0$$

$(\theta, \theta)$

$$\zeta^1 \partial_\lambda \cancel{g_{\theta\theta}} + g_{\lambda\theta} \partial_\theta \zeta^\lambda + g_{\theta\lambda} \partial_\theta \zeta^\lambda = 0$$

$$g_{\theta\theta} \partial_\theta \zeta^0 + g_{\theta\theta} \partial_\theta \zeta^0 = 0$$

$$2 \cdot 1 \cdot \partial_\theta \zeta^0 = 0 \Rightarrow \underline{\partial_\theta \zeta^0 = 0}$$

$(\theta, \varphi)$

$$\zeta^1 \partial_\lambda \cancel{g_{\theta\varphi}} + g_{\lambda\varphi} \partial_\theta \zeta^\lambda + g_{\theta\lambda} \partial_\varphi \zeta^\lambda = 0 \Rightarrow$$

$$g_{\varphi\varphi} \partial_\theta \zeta^\varphi + g_{\theta\theta} \partial_\varphi \zeta^0 = 0$$

$$\underline{\sin^2 \theta \partial_\theta \zeta^\varphi + \partial_\varphi \zeta^0 = 0}$$

$(\varphi, \varphi)$

$$\zeta^1 \partial_\lambda g_{\varphi\varphi} + g_{\lambda\varphi} \partial_\varphi \zeta^\lambda + g_{\varphi\lambda} \partial_\varphi \zeta^\lambda = 0 \Rightarrow$$

$$\zeta^0 \partial_\theta g_{\varphi\varphi} + g_{\varphi\varphi} \partial_\varphi \zeta^\varphi + g_{\varphi\varphi} \partial_\varphi \zeta^\varphi = 0 \Rightarrow$$

$$\zeta^0 \partial_\theta (\sin^2 \theta) + \sin^2 \theta \partial_\varphi \zeta^\varphi + \sin^2 \theta \partial_\varphi \zeta^\varphi = 0 \Rightarrow$$

$$\zeta^0 \cancel{2 \sin \theta} \cos \theta + \cancel{2 \sin \theta} \sin \theta \partial_\varphi \zeta^\varphi = 0 \Rightarrow$$

$$\cos \theta \zeta^0 + \sin \theta \partial_\varphi \zeta^\varphi = 0 \Rightarrow$$

$$\underline{\partial_\varphi \zeta^\varphi + \cot \theta \zeta^0 = 0}$$



Examples:  $S^2$

$$\partial_\theta \zeta^\theta = 0$$

$$\partial_\varphi \zeta^\theta + \sin^2 \theta \partial_\theta \zeta^\varphi = 0$$

$$\partial_\varphi \zeta^\varphi + \cot \theta \zeta^\theta = 0$$

Solutions:

$$\zeta^\theta = c_3 \sin(\varphi + c_1)$$

$$\zeta^\varphi = c_3 \cos(\varphi + c_1) \cot \theta + c_2$$

Examples:  $S^2$

$$\partial_\theta \zeta^\theta = 0$$

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$$\zeta^\varphi = c_3 \cos(\varphi + c_1) \cot \theta + c_2$$

3 linearly independent solutions

$(c_1, c_2, c_3)$ :

$$(0, 1, 0) \rightarrow \zeta^{(1)} = (0, 1)$$

$$(0, 0, 1) \rightarrow \zeta^{(2)} = (\sin \varphi, \cos \varphi \cot \theta)$$

$$\left(\frac{\pi}{2}, 0, 1\right) \rightarrow \zeta^{(3)} = (\cos \varphi, -\sin \varphi \cot \theta)$$

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Note:  $S^2$  is 2-dim

has 3 linearly independent  $\zeta^{(i)}$   $i=1, 2, 3$

$$\lambda_1 \zeta^{(1)} + \lambda_2 \zeta^{(2)} + \lambda_3 \zeta^{(3)} = 0 \Rightarrow \lambda_1 = \lambda_2 = \lambda_3 = 0$$

$\lambda_1, \lambda_2, \lambda_3 \in \mathbb{R}$  not functions

linear independence of basis:

$$f^1 \partial_1 + f^2 \partial_2 = 0 \Rightarrow f^1 = f^2 = 0$$

at each point, so  $f^1, f^2$  become functions  
if considered at all points

# Examples: $S^2$

$$\partial_\theta \zeta^\theta = 0$$

$$\partial_\varphi \zeta^\theta + \sin^2 \theta \partial_\theta \zeta^\varphi = 0$$

$$\partial_\varphi \zeta^\varphi + \cot \theta \zeta^\theta = 0$$

Solutions:

$$\zeta^\theta = c_3 \sin(\varphi + c_1)$$

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\*  $\zeta^{(1)}, \zeta^{(2)}, \zeta^{(3)}$  generate  $SO(3)$

rotations on sphere

# Examples: $S^2$

$$\partial_\theta \zeta^\theta = 0$$

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Solutions:

$$\zeta^\theta = c_3 \sin(\varphi + c_1)$$

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\*  $\zeta^{(1)}, \zeta^{(2)}, \zeta^{(3)}$  generate  $SO(3)$

rotations on sphere

---

Consider geodesic along equator:  $U = \partial_\varphi = (0, 1)$

$$U_\mu \zeta^\mu = g_{\mu\nu} U^\mu \zeta^\nu = g_{\varphi\varphi} U^\varphi \zeta^\varphi = \sin^2 \theta \zeta^\varphi$$

For  $\zeta^{(1)}$ :  $\sin^2 \theta$  is conserved

$\zeta^{(2)}$ :  $\sin^2 \theta \cot \theta \cot \theta$  is conserved

$\zeta^{(3)}$ : ...

Examples:  $\mathbb{R}^2$

$$ds^2 = dx^2 + dy^2$$

$$\cancel{\xi^\mu \partial_\mu g_{\mu\nu}} + g_{\mu\nu} \partial_\mu \xi^\nu + g_{\mu\nu} \partial_\nu \xi^\mu = 0$$

---

(x, x):

$$g_{1x} \partial_x \xi^1 + g_{x1} \partial_x \xi^1 = 0 \Rightarrow$$

$$2g_{xx} \partial_x \xi^x = 0 \Rightarrow \partial_x \xi^x = 0$$

Examples:  $\mathbb{R}^2$

$$ds^2 = dx^2 + dy^2$$

$$\cancel{\xi^\lambda \partial_\lambda g_{\mu\nu}} + g_{\mu\nu} \partial_\mu \xi^\lambda + g_{\mu\lambda} \partial_\nu \xi^\lambda = 0$$

---

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$$2g_{xx} \partial_x \xi^x = 0 \Rightarrow \partial_x \xi^x = 0$$

---

$(x, y)$ :

$$g_{xy} \partial_x \xi^\lambda + g_{x\lambda} \partial_y \xi^\lambda = 0 \Rightarrow$$

$$g_{yz} \partial_x \xi^z + g_{xz} \partial_y \xi^z = 0 \Rightarrow \partial_x \xi^y = -\partial_y \xi^x$$

# Examples: $\mathbb{R}^2$

$$ds^2 = dx^2 + dy^2$$

$$\cancel{\xi^\mu \partial_\mu g_{\mu\nu}} + g_{\mu\nu} \partial_\mu \xi^\nu + g_{\mu\nu} \partial_\nu \xi^\mu = 0$$

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---

$(x, y)$ :

$$g_{xy} \partial_x \xi^y + g_{xy} \partial_y \xi^x = 0 \Rightarrow$$

$$g_{yx} \partial_x \xi^y + g_{yx} \partial_y \xi^x = 0 \Rightarrow \partial_x \xi^y = -\partial_y \xi^x$$

---

$(y, y)$ :

$$g_{yy} \partial_y \xi^y + g_{yy} \partial_y \xi^y = 0 \Rightarrow g_{yy} \partial_y \xi^y + g_{yy} \partial_y \xi^y = 0$$

$$\Rightarrow \partial_y \xi^y = 0$$



# Examples: $\mathbb{R}^2$

$$ds^2 = dx^2 + dy^2$$

$$\cancel{\xi^\mu \partial_\mu g_{\mu\nu}} + g_{\mu\nu} \partial_\mu \xi^\nu + g_{\mu\nu} \partial_\nu \xi^\mu = 0$$

$(x, x)$ :

$$g_{xx} \partial_x \xi^x + g_{xx} \partial_x \xi^x = 0 \Rightarrow \quad (1)$$

$$2g_{xx} \partial_x \xi^x = 0 \Rightarrow \partial_x \xi^x = 0$$

$(x, y)$ :

$$g_{xy} \partial_x \xi^y + g_{xy} \partial_y \xi^x = 0 \Rightarrow \quad (2)$$

$$g_{yy} \partial_x \xi^y + g_{xx} \partial_y \xi^x = 0 \Rightarrow \partial_x \xi^y = -\partial_y \xi^x$$

$(y, y)$ :

$$g_{yy} \partial_y \xi^y + g_{yy} \partial_y \xi^y = 0 \Rightarrow g_{yy} \partial_y \xi^y + g_{yy} \partial_y \xi^y = 0$$

$$\Rightarrow \partial_y \xi^y = 0 \quad (3)$$

$$(1), (3) \Rightarrow \xi^x = f(y) \quad \xi^y = g(x)$$

$$(2) \Rightarrow f'(y) = -g'(x) = c$$

# Examples: $\mathbb{R}^2$

$$ds^2 = dx^2 + dy^2$$

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$(x, y)$ :

$$g_{xy} \partial_x \xi^y + g_{xy} \partial_y \xi^x = 0 \Rightarrow \quad (2)$$

$$g_{yx} \partial_x \xi^x + g_{yx} \partial_y \xi^y = 0 \Rightarrow \partial_x \xi^y = -\partial_y \xi^x$$

$(y, y)$ :

$$g_{yy} \partial_y \xi^y + g_{yy} \partial_y \xi^y = 0 \Rightarrow g_{yy} \partial_y \xi^y + g_{yy} \partial_y \xi^y = 0$$

$$\Rightarrow \partial_y \xi^y = 0 \quad (3)$$

(1), (3)  $\Rightarrow \xi^x = f(y) \quad \xi^y = g(x)$

(2)  $\Rightarrow f'(y) = -g'(x) = c_1 \Rightarrow$

$$\left. \begin{array}{l} f(y) = c_1 y + c_2 \\ g(x) = -c_1 x + c_3 \end{array} \right\} \Rightarrow \begin{array}{l} \xi^x = c_1 y + c_2 \\ \xi^y = -c_1 x + c_3 \end{array}$$

# Examples: $\mathbb{R}^2$

$$ds^2 = dx^2 + dy^2$$

$$\cancel{\xi^\mu \partial_\mu g_{\nu\lambda}} + g_{\mu\nu} \partial_\mu \xi^\lambda + g_{\mu\lambda} \partial_\nu \xi^\mu = 0$$

(x, x):

$$g_{1x} \partial_x \xi^1 + g_{x1} \partial_x \xi^1 = 0 \Rightarrow (1)$$

$$2g_{xx} \partial_x \xi^x = 0 \Rightarrow \partial_x \xi^x = 0$$

(x, y):

$$g_{1y} \partial_x \xi^1 + g_{x1} \partial_y \xi^1 = 0 \Rightarrow (2)$$

$$g_{y2} \partial_x \xi^2 + g_{xx} \partial_y \xi^x = 0 \Rightarrow \partial_x \xi^2 = -\partial_y \xi^x$$

(y, y):

$$g_{1y} \partial_y \xi^1 + g_{y1} \partial_y \xi^1 = 0 \Rightarrow g_{yy} \partial_y \xi^2 + g_{yy} \partial_y \xi^2 = 0$$

$$\Rightarrow \partial_y \xi^2 = 0 \quad (3)$$

$$(1), (3) \Rightarrow \xi^x = f(y) \quad \xi^y = g(x)$$

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$$\left. \begin{array}{l} f(y) = c_1 y + c_2 \\ g(x) = -c_1 x + c_3 \end{array} \right\} \Rightarrow \begin{array}{l} \xi^x = c_1 y + c_2 \\ \xi^y = -c_1 x + c_3 \end{array}$$

$$(c_1, c_2, c_3)$$

$$(0, 1, 0)$$

$$(0, 0, 1)$$

$$(-1, 0, 0)$$

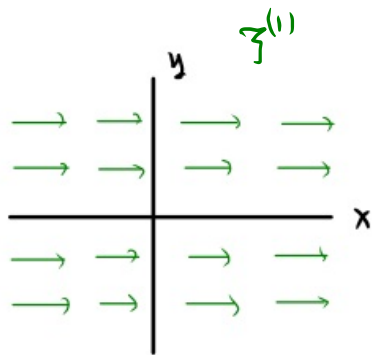
$$\xi^{(1)} = (1, 0)$$

$$\xi^{(2)} = (0, 1)$$

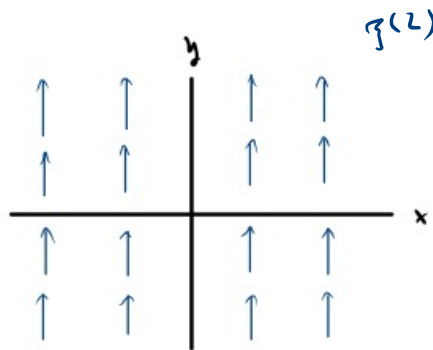
$$\xi^{(3)} = (-y, x) = (-\rho \sin\varphi, \rho \cos\varphi) = \rho e_\varphi = \partial_\varphi$$

# Examples: $\mathbb{R}^2$

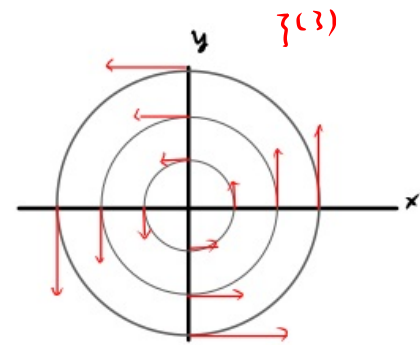
$\zeta^{(1)}$ : x-translations



$\zeta^{(2)}$ : y-translations



$\zeta^{(3)}$ : rotations around (0,0)



$$(1), (3) \Rightarrow \zeta^x = f(y) \quad \zeta^y = g(x)$$

$$(2) \Rightarrow \left. \begin{aligned} f'(y) = -g'(x) = c_1 \\ f(y) = c_1 y + c_2 \\ g(x) = -c_1 x + c_3 \end{aligned} \right\} \Rightarrow \begin{aligned} \zeta^x &= c_1 y + c_2 \\ \zeta^y &= -c_1 x + c_3 \end{aligned}$$

$$(c_1, c_2, c_3)$$

$$(0, 1, 0)$$

$$(0, 0, 1)$$

$$(-1, 0, 0)$$

$$\zeta^{(1)} = (1, 0)$$

$$\zeta^{(2)} = (0, 1)$$

$$\zeta^{(3)} = (-y, x) = (-\rho \sin\varphi, \rho \cos\varphi) = \rho e_\varphi = \rho \partial_\varphi$$

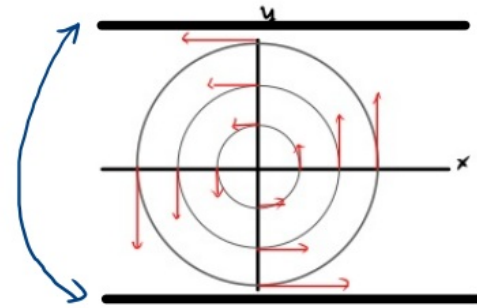
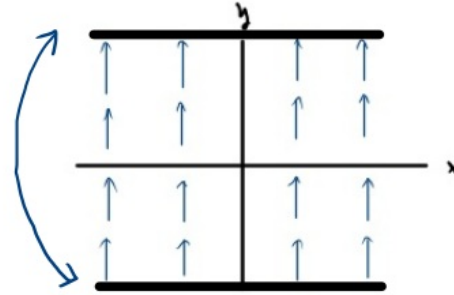
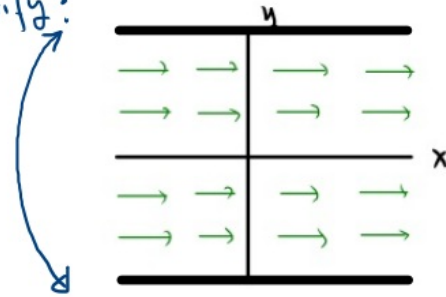
# Examples: $S^1 \times \mathbb{R}$ (cylinder)

$\xi^{(1)}$ :  $x$ -translations

$\xi^{(2)}$ :  $y$ -translations

$\xi^{(3)}$ : rotations around  $(0,0)$

identify:



\* The Killing equations don't change: same solutions in  $(x,y)$  coordinate system

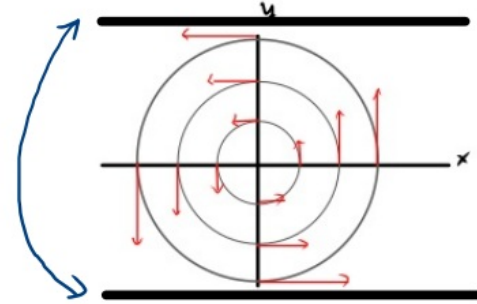
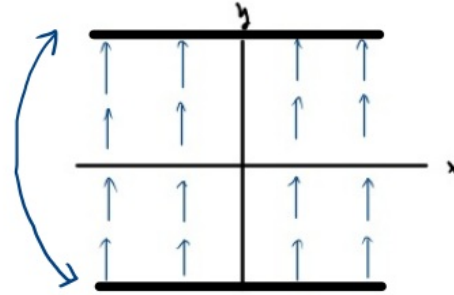
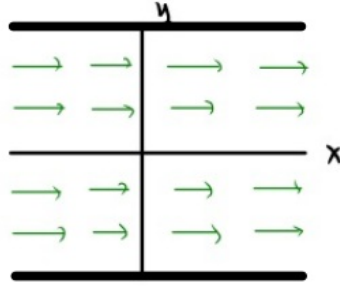
# Examples: $S^1 \times \mathbb{R}$ (cylinder)

$\xi^{(1)}$ :  $x$ -translations

$\xi^{(2)}$ :  $y$ -translations

$\xi^{(3)}$ : rotation around  $(0,0)$

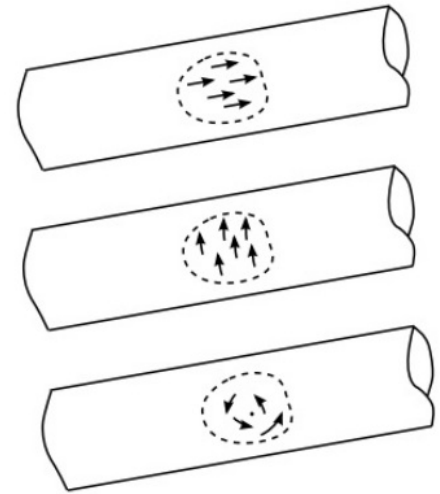
identify:



\* The Killing equations don't change: same solutions in  $(x,y)$  coordinate system  
 \*  $(x,y)$  coordinate system does not cover whole cylinder

- $\xi^{(1)}$  globally defined
- $\xi^{(2)}$  " "
- $\xi^{(3)}$  only locally defined

(notice that  $\lim_{y \rightarrow \pi^-} \xi^{(3)} \neq \lim_{y \rightarrow -\pi^+} \xi^{(3)}$ )



Example: The Schwarzschild metric

$$ds^2 = -\left(1 - \frac{2M}{r}\right) dt^2 + \left(1 - \frac{2M}{r}\right)^{-1} dr^2 + r^2 (d\theta^2 + \sin^2\theta d\varphi^2)$$

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 $g_{\mu\nu}$   $t$ -independent  $\leadsto g_{\mu\nu}$  static }  $\rightarrow$  energy conservation

$R^\mu$ : generates  $\varphi$ -translations  $\leadsto$  rotations  
 $g_{\mu\nu}$  rotationally symmetric }  $\rightarrow$  angular conservation momentum

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For massive particle  $p^\mu = mU^\mu \rightarrow$  energy/angular momentum per unit mass ( $\lambda = \tau$ )

For massless: choose  $\lambda$  s.t.  $p^\mu = \frac{dx^\mu}{d\lambda}$



Exercise: Show that for a k.v.f.  $\xi$   $\nabla_\mu \nabla_\nu \xi_\lambda = R_{\mu\nu\rho}^{\lambda} \xi^\rho$

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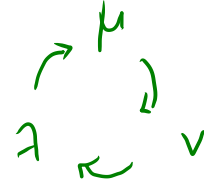
$$\nabla_\mu \nabla_\nu \xi_\lambda - \nabla_\nu \nabla_\mu \xi_\lambda = -R^\rho_{\lambda\mu\nu} \xi_\rho$$

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$$(1) + (2) - (3) \Rightarrow$$

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$$\hookrightarrow \text{use } \nabla_\mu \xi_\nu + \nabla_\nu \xi_\mu = 0$$

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