

Curvature and the geodesic equations

Copy/paste the following cell in a notebook and edit the data between the red lines. Then evaluate it to see the results.

Details on the code and how it works can be found at the end of the notebook.

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In[ ]:= Clear[coord, metric, inversemetric, affine, riemann, lriemann, uriemann,
        ricci, scalar, einstein, weyl, geodesic, R, G, τ, i, j, k, l, s];
Clear[r, θ, φ, t, χ, a, m, M];

(*-----*)
(* This is what you need to set: *)
coord = {V, U, θ, φ};
n      = Length[coord];
metric = {
  { - $\frac{32 M^3}{r[V, U]} e^{-\frac{r[V, U]}{2 M}}$ , 0, 0, 0},
  { 0,  $\frac{32 M^3}{r[V, U]} e^{-\frac{r[V, U]}{2 M}}$ , 0, 0},
  { 0, 0, r[V, U]^2, 0},
  { 0, 0, 0, r[V, U]^2 Sin[θ]^2 }
};

(*-----*)

inversemetric = FullSimplify[Inverse[metric]];
Print["-----"];
Print["The Manifold has dimension   n= ",
      n, "\nCoordinate system:      ", coord];
Print["-----"];
Print["gμν=", metric // MatrixForm];
Print["gμν=", inversemetric // MatrixForm];
affine := affine = FullSimplify[Table[
  (1/2) * Sum[
    (*  $g^{is} (\partial_k g_{sj} + \partial_j g_{sk} - \partial_s g_{jk})$  *)
    (inversemetric[[i, s]] *
     (D[metric[[s, j], coord[[k]]] +
      D[metric[[s, k], coord[[j]]] - D[metric[[j, k], coord[[s]]],
      {s, 1, n}],
     {i, 1, n}, {j, 1, n}, {k, 1, n}]]];
(*The non zero Christoffel symbols are computed and selected below: *)
listaffine := Table[
  If[

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    UnsameQ[affine[[i, j, k]], 0],
    {Subscript[Superscript[Γ, i - 1], j - 1, k - 1], affine[[i, j, k]]
    },
    {i, 1, n}, {j, 1, n}, {k, 1, j}}];
Print["-----"];
Print["Christoffel Symbols:"];
Print[TableForm[
    Partition[DeleteCases[Flatten[listaffine], Null], 2], TableSpacing → {2, 2}]];
riemann := riemann = FullSimplify[Table[
    (*  $R^i_{jkl} = \partial_k \Gamma^i_{lj} - \partial_l \Gamma^i_{kj} +$ 
    D[ affine[[i, l, j]], coord[[k]] ] - D[affine[[i, k, j]], coord[[l]] ] +
    (*  $\Gamma^i_{ks} \Gamma^s_{lj} - \Gamma^i_{ls} \Gamma^s_{kj}$  *)
    Sum[affine[[i, k, s]] affine[[s, l, j]] - affine[[i, l, s]] affine[[s, k, j]],
    {s, 1, n}],
    {i, 1, n}, {j, 1, n}, {k, 1, n}, {l, 1, n}]];
listriemann := Table[
    If[
        UnsameQ[riemann[[i, j, k, l]], 0],
        {Subscript[Superscript[R, i - 1], j - 1, k - 1, l - 1], riemann[[i, j, k, l]]
        },
        {i, 1, n}, {j, 1, n}, {k, 1, n}, {l, 1, k - 1}}];
Print["-----"];
Print["Riemann Tensor:"];
Print[TableForm[
    Partition[DeleteCases[Flatten[listriemann], Null], 2], TableSpacing → {2, 2}]];
lriemann := lriemann = FullSimplify[Table[
    Sum[metric[[i, ii]] riemann[[ii, j, k, l]], {ii, 1, n}],
    {i, 1, n}, {j, 1, n}, {k, 1, n}, {l, 1, n}]];
listlriemann := Table[
    If[
        UnsameQ[lriemann[[i, j, k, l]], 0],
        {Subscript[R, i - 1, j - 1, k - 1, l - 1], lriemann[[i, j, k, l]]
        }, {i, 1, n}, {j, 1, i - 1}, {k, 1, n}, {l, 1, k - 1}}];
Print["-----"];
Print["Contravariant Riemann Tensor:"];
Print[TableForm[
    Partition[DeleteCases[Flatten[listlriemann], Null], 2], TableSpacing → {2, 2}]];
uriemann := uriemann = FullSimplify[Table[
    Sum[
        inversemetric[[j, jj]] inversemetric[[k, kk]] inversemetric[[l, ll]]
        riemann[[i, jj, kk, ll]], {jj, 1, n}, {kk, 1, n}, {ll, 1, n}
    ],
    {i, 1, n}
];

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    {i, 1, n}, {j, 1, n}, {k, 1, n}, {l, 1, n}]];
listuriemann := Table[
  If[
    UnsameQ[uriemann[[i, j, k, l]], 0],
    {Superscript[Superscript[Superscript[Superscript[R, i - 1], j - 1], k - 1], l - 1],
      uriemann[[i, j, k, l]]
    }, {i, 1, n}, {j, 1, i - 1}, {k, 1, n}, {l, 1, k - 1}];
Print["-----"];
Print["Covariant Riemann Tensor:"];
Print[TableForm[
  Partition[DeleteCases[Flatten[listuriemann], Null], 2], TableSpacing -> {2, 2}]];
r2 = FullSimplify[Sum[lriemann[[i, j, k, l]]uriemann[[i, j, k, l]],
  {i, 1, n}, {j, 1, n}, {k, 1, n}, {l, 1, n}]];
Print["-----"];
Print["R2= ", r2];
ricci := ricci = FullSimplify[Table[
  Sum[
    riemann[[i, j, i, l]],
    {i, 1, n}
  ], {j, 1, n}, {l, 1, n}]];
listricci := Table[
  If[
    UnsameQ[ricci[[j, l]], 0],
    {Subscript[R, j - 1, l - 1], ricci[[j, l]]
    }, {j, 1, n}, {l, 1, j}];
Print["-----"];
Print["Ricci Tensor:"];
Print[TableForm[
  Partition[DeleteCases[Flatten[listricci], Null], 2], TableSpacing -> {2, 2}]];
scalar = FullSimplify[Sum[inversemetric[[i, j]]ricci[[i, j]], {i, 1, n}, {j, 1, n}]];
Print["-----"];
Print["Curvature Scalar:"];
Print["R= ", scalar];
einstein := einstein = FullSimplify[ricci - (1/2) scalar * metric];
listeinstein := Table[
  If[
    UnsameQ[einstein[[j, l]], 0],
    {Subscript[G, j - 1, l - 1], einstein[[j, l]]
    }, {j, 1, n}, {l, 1, j}];
Print["-----"];
Print["Einstein Tensor:"];
Print[TableForm[
  Partition[DeleteCases[Flatten[list Einstein], Null], 2], TableSpacing -> {2, 2}]];

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weyl := weyl = FullSimplify[Table[
  If[n > 3,
    Riemann[i, j, k, l]
    -  $\frac{1}{n-2}$  (metric[i, k] ricci[l, j] - metric[i, l] ricci[k, j] -
      metric[j, k] ricci[l, i] + metric[j, l] ricci[k, i])
    +  $\frac{1}{(n-1)(n-2)}$  (metric[i, k] metric[l, j] - metric[i, l] metric[k, j]) scalar
    (*else, if n ≤ 3 return 0:*), 0],
  {i, 1, n}, {j, 1, n}, {k, 1, n}, {l, 1, n}]];
listweyl := Table[
  If[
    UnsameQ[weyl[i, j, k, l], 0],
    {Subscript[C, i-1, j-1, k-1, l-1], weyl[i, j, k, l]}
  ], {i, 1, n}, {j, 1, i-1}, {k, 1, n}, {l, 1, k-1}];
Print["-----"];
Print["Weyl Tensor:"];
Print[TableForm[
  Partition[DeleteCases[Flatten[listweyl], Null], 2], TableSpacing → {2, 2}];
geodesic := geodesic =
  Simplify[Table[-Sum[affine[i, j, k] u[j] u[k], {j, 1, n}, {k, 1, n}], {i, 1, n}]];
subst = Table[u[i] → Subscript[coord[i], τ], {i, 1, n}];
nlistgeodesic :=
  Table[{Subscript[coord[i], τ], "+", -geodesic[i] /. subst, "= 0"}, {i, 1, n}];
Print["-----"];
Print["Geodesic Equations:"];
Print[TableForm[nlistgeodesic, TableSpacing → {2}]];

```

The Manifold has dimension $n = 4$
 Coordinate system: $\{V, U, \theta, \phi\}$

$$g_{\mu\nu} = \begin{pmatrix} -\frac{32e^{-\frac{r[V,U]}{2M}} M^3}{r[V,U]} & 0 & 0 & 0 \\ 0 & \frac{32e^{-\frac{r[V,U]}{2M}} M^3}{r[V,U]} & 0 & 0 \\ 0 & 0 & r[V, U]^2 & 0 \\ 0 & 0 & 0 & r[V, U]^2 \sin[\theta]^2 \end{pmatrix}$$

$$g^{\mu\nu} = \begin{pmatrix} -\frac{e^{\frac{r[V,U]}{2M}} r[V,U]}{32 M^3} & 0 & 0 & 0 \\ 0 & \frac{e^{\frac{r[V,U]}{2M}} r[V,U]}{32 M^3} & 0 & 0 \\ 0 & 0 & \frac{1}{r[V,U]^2} & 0 \\ 0 & 0 & 0 & \frac{\text{Csc}[\theta]^2}{r[V,U]^2} \end{pmatrix}$$

Christoffel Symbols:

$$\Gamma^0_{0,0} = -\frac{(2M+r[V,U]) r^{(1,0)}[V,U]}{4M r[V,U]}$$

$$\Gamma^0_{1,0} = -\frac{(2M+r[V,U]) r^{(0,1)}[V,U]}{4M r[V,U]}$$

$$\Gamma^0_{1,1} = -\frac{(2M+r[V,U]) r^{(1,0)}[V,U]}{4M r[V,U]}$$

$$\Gamma^0_{2,2} = \frac{e^{\frac{r[V,U]}{2M}} r[V,U]^2 r^{(1,0)}[V,U]}{32 M^3}$$

$$\Gamma^0_{3,3} = \frac{e^{\frac{r[V,U]}{2M}} r[V,U]^2 \text{Sin}[\theta]^2 r^{(1,0)}[V,U]}{32 M^3}$$

$$\Gamma^1_{0,0} = -\frac{(2M+r[V,U]) r^{(0,1)}[V,U]}{4M r[V,U]}$$

$$\Gamma^1_{1,0} = -\frac{(2M+r[V,U]) r^{(1,0)}[V,U]}{4M r[V,U]}$$

$$\Gamma^1_{1,1} = -\frac{(2M+r[V,U]) r^{(0,1)}[V,U]}{4M r[V,U]}$$

$$\Gamma^1_{2,2} = -\frac{e^{\frac{r[V,U]}{2M}} r[V,U]^2 r^{(0,1)}[V,U]}{32 M^3}$$

$$\Gamma^1_{3,3} = -\frac{e^{\frac{r[V,U]}{2M}} r[V,U]^2 \text{Sin}[\theta]^2 r^{(0,1)}[V,U]}{32 M^3}$$

$$\Gamma^2_{2,0} = \frac{r^{(1,0)}[V,U]}{r[V,U]}$$

$$\Gamma^2_{2,1} = \frac{r^{(0,1)}[V,U]}{r[V,U]}$$

$$\Gamma^2_{3,3} = -\text{Cos}[\theta] \text{Sin}[\theta]$$

$$\Gamma^3_{3,0} = \frac{r^{(1,0)}[V,U]}{r[V,U]}$$

$$\Gamma^3_{3,1} = \frac{r^{(0,1)}[V,U]}{r[V,U]}$$

$$\Gamma^3_{3,2} = \text{Cot}[\theta]$$

Riemann Tensor:

$$\begin{aligned}
R^0_{1,1,0} &= \frac{2 M r^{(0,1)}[V, U]^2 - 2 M r^{(1,0)}[V, U]^2 + 2 M r[V, U] (-r^{(0,2)}[V, U] + r^{(2,0)}[V, U]) + r[V, U]^2 (-r^{(0,2)}[V, U] + r^{(2,0)}[V, U])}{4 M r[V, U]^2} \\
R^0_{2,2,0} &= -\frac{\frac{r[V, U]}{e^{2M}} r[V, U] ((2 M + r[V, U]) (r^{(0,1)}[V, U]^2 + r^{(1,0)}[V, U]^2) + 4 M r[V, U] r^{(2,0)}[V, U])}{128 M^4} \\
R^0_{2,2,1} &= -\frac{\frac{r[V, U]}{e^{2M}} r[V, U] ((2 M + r[V, U]) r^{(0,1)}[V, U] r^{(1,0)}[V, U] + 2 M r[V, U] r^{(1,1)}[V, U])}{64 M^4} \\
R^0_{3,3,0} &= -\frac{\frac{r[V, U]}{e^{2M}} r[V, U] \text{Sin}[\theta]^2 ((2 M + r[V, U]) (r^{(0,1)}[V, U]^2 + r^{(1,0)}[V, U]^2) + 4 M r[V, U] r^{(2,0)}[V, U])}{128 M^4} \\
R^0_{3,3,1} &= -\frac{\frac{r[V, U]}{e^{2M}} r[V, U] \text{Sin}[\theta]^2 ((2 M + r[V, U]) r^{(0,1)}[V, U] r^{(1,0)}[V, U] + 2 M r[V, U] r^{(1,1)}[V, U])}{64 M^4} \\
R^1_{0,1,0} &= \frac{2 M r^{(0,1)}[V, U]^2 - 2 M r^{(1,0)}[V, U]^2 + 2 M r[V, U] (-r^{(0,2)}[V, U] + r^{(2,0)}[V, U]) + r[V, U]^2 (-r^{(0,2)}[V, U] + r^{(2,0)}[V, U])}{4 M r[V, U]^2} \\
R^1_{2,2,0} &= \frac{\frac{r[V, U]}{e^{2M}} r[V, U] ((2 M + r[V, U]) r^{(0,1)}[V, U] r^{(1,0)}[V, U] + 2 M r[V, U] r^{(1,1)}[V, U])}{64 M^4} \\
R^1_{2,2,1} &= \frac{\frac{r[V, U]}{e^{2M}} r[V, U] ((2 M + r[V, U]) r^{(0,1)}[V, U]^2 + 4 M r[V, U] r^{(0,2)}[V, U] + (2 M + r[V, U]) r^{(1,0)}[V, U]^2)}{128 M^4} \\
R^1_{3,3,0} &= \frac{\frac{r[V, U]}{e^{2M}} r[V, U] \text{Sin}[\theta]^2 ((2 M + r[V, U]) r^{(0,1)}[V, U] r^{(1,0)}[V, U] + 2 M r[V, U] r^{(1,1)}[V, U])}{64 M^4} \\
R^1_{3,3,1} &= \frac{\frac{r[V, U]}{e^{2M}} r[V, U] \text{Sin}[\theta]^2 ((2 M + r[V, U]) r^{(0,1)}[V, U]^2 + 4 M r[V, U] r^{(0,2)}[V, U] + (2 M + r[V, U]) r^{(1,0)}[V, U]^2)}{128 M^4} \\
R^2_{0,2,0} &= -\frac{(2 M + r[V, U]) (r^{(0,1)}[V, U]^2 + r^{(1,0)}[V, U]^2) + 4 M r[V, U] r^{(2,0)}[V, U]}{4 M r[V, U]^2} \\
R^2_{0,2,1} &= -\frac{\frac{(2 M + r[V, U]) r^{(0,1)}[V, U] r^{(1,0)}[V, U]}{M} + 2 r[V, U] r^{(1,1)}[V, U]}{2 r[V, U]^2} \\
R^2_{1,2,0} &= -\frac{\frac{(2 M + r[V, U]) r^{(0,1)}[V, U] r^{(1,0)}[V, U]}{M} + 2 r[V, U] r^{(1,1)}[V, U]}{2 r[V, U]^2} \\
R^2_{1,2,1} &= -\frac{(2 M + r[V, U]) r^{(0,1)}[V, U]^2 + 4 M r[V, U] r^{(0,2)}[V, U] + (2 M + r[V, U]) r^{(1,0)}[V, U]^2}{4 M r[V, U]^2} \\
R^2_{3,3,2} &= \frac{1}{32} \text{Sin}[\theta]^2 \left(-32 + \frac{\frac{r[V, U]}{e^{2M}} r[V, U] (r^{(0,1)}[V, U]^2 - r^{(1,0)}[V, U]^2)}{M^3} \right) \\
R^3_{0,3,0} &= -\frac{(2 M + r[V, U]) (r^{(0,1)}[V, U]^2 + r^{(1,0)}[V, U]^2) + 4 M r[V, U] r^{(2,0)}[V, U]}{4 M r[V, U]^2} \\
R^3_{0,3,1} &= -\frac{\frac{(2 M + r[V, U]) r^{(0,1)}[V, U] r^{(1,0)}[V, U]}{M} + 2 r[V, U] r^{(1,1)}[V, U]}{2 r[V, U]^2} \\
R^3_{1,3,0} &= -\frac{\frac{(2 M + r[V, U]) r^{(0,1)}[V, U] r^{(1,0)}[V, U]}{M} + 2 r[V, U] r^{(1,1)}[V, U]}{2 r[V, U]^2} \\
R^3_{1,3,1} &= -\frac{(2 M + r[V, U]) r^{(0,1)}[V, U]^2 + 4 M r[V, U] r^{(0,2)}[V, U] + (2 M + r[V, U]) r^{(1,0)}[V, U]^2}{4 M r[V, U]^2} \\
R^3_{2,3,2} &= 1 - \frac{\frac{r[V, U]}{e^{2M}} r[V, U] (r^{(0,1)}[V, U]^2 - r^{(1,0)}[V, U]^2)}{32 M^3}
\end{aligned}$$

Contravariant Riemann Tensor:

$$\begin{aligned}
R_{1,0,1,0} &= \frac{8 e^{-\frac{r[V,U]}{2M}} M^2 (2M r^{(0,1)}[V,U]^2 - 2M r^{(1,0)}[V,U]^2 + 2M r[V,U] (-r^{(0,2)}[V,U] + r^{(2,0)}[V,U]) + r[V,U]^2 (-r^{(0,2)}[V,U] + r^{(2,0)}[V,U]))}{r[V,U]^3} \\
R_{2,0,2,0} &= -\frac{(2M+r[V,U]) (r^{(0,1)}[V,U]^2 + r^{(1,0)}[V,U]^2)}{4M} - r[V,U] r^{(2,0)}[V,U] \\
R_{2,0,2,1} &= -\frac{(2M+r[V,U]) r^{(0,1)}[V,U] r^{(1,0)}[V,U]}{2M} - r[V,U] r^{(1,1)}[V,U] \\
R_{2,1,2,0} &= -\frac{(2M+r[V,U]) r^{(0,1)}[V,U] r^{(1,0)}[V,U]}{2M} - r[V,U] r^{(1,1)}[V,U] \\
R_{2,1,2,1} &= -\frac{(2M+r[V,U]) r^{(0,1)}[V,U]^2 + 4M r[V,U] r^{(0,2)}[V,U] + (2M+r[V,U]) r^{(1,0)}[V,U]^2}{4M} \\
R_{3,0,3,0} &= -\frac{\text{Sin}[\theta]^2 ((2M+r[V,U]) (r^{(0,1)}[V,U]^2 + r^{(1,0)}[V,U]^2) + 4M r[V,U] r^{(2,0)}[V,U])}{4M} \\
R_{3,0,3,1} &= -\frac{1}{2} \text{Sin}[\theta]^2 \left(\frac{(2M+r[V,U]) r^{(0,1)}[V,U] r^{(1,0)}[V,U]}{M} + 2 r[V,U] r^{(1,1)}[V,U] \right) \\
R_{3,1,3,0} &= -\frac{1}{2} \text{Sin}[\theta]^2 \left(\frac{(2M+r[V,U]) r^{(0,1)}[V,U] r^{(1,0)}[V,U]}{M} + 2 r[V,U] r^{(1,1)}[V,U] \right) \\
R_{3,1,3,1} &= -\frac{\text{Sin}[\theta]^2 ((2M+r[V,U]) r^{(0,1)}[V,U]^2 + 4M r[V,U] r^{(0,2)}[V,U] + (2M+r[V,U]) r^{(1,0)}[V,U]^2)}{4M} \\
R_{3,2,3,2} &= r[V,U]^2 \text{Sin}[\theta]^2 \left(1 - \frac{e^{-\frac{r[V,U]}{2M}} r[V,U] (r^{(0,1)}[V,U]^2 - r^{(1,0)}[V,U]^2)}{32M^3} \right)
\end{aligned}$$

Covariant Riemann Tensor:

$$\begin{aligned}
R^{1010} &= \frac{e^{-\frac{3r[V,U]}{2M}} r[V,U] (2M r^{(0,1)}[V,U]^2 - 2M r^{(1,0)}[V,U]^2 + 2M r[V,U] (-r^{(0,2)}[V,U] + r^{(2,0)}[V,U]) + r[V,U]^2 (-r^{(0,2)}[V,U] + r^{(2,0)}[V,U]))}{131072M^{10}} \\
R^{2020} &= -\frac{e^{-\frac{r[V,U]}{M}} ((2M+r[V,U]) (r^{(0,1)}[V,U]^2 + r^{(1,0)}[V,U]^2) + 4M r[V,U] r^{(2,0)}[V,U])}{4096M^7 r[V,U]^2} \\
R^{2021} &= \frac{e^{-\frac{r[V,U]}{M}} ((2M+r[V,U]) r^{(0,1)}[V,U] r^{(1,0)}[V,U] + 2M r[V,U] r^{(1,1)}[V,U])}{2048M^7 r[V,U]^2} \\
R^{2120} &= \frac{e^{-\frac{r[V,U]}{M}} ((2M+r[V,U]) r^{(0,1)}[V,U] r^{(1,0)}[V,U] + 2M r[V,U] r^{(1,1)}[V,U])}{2048M^7 r[V,U]^2} \\
R^{2121} &= -\frac{e^{-\frac{r[V,U]}{M}} ((2M+r[V,U]) r^{(0,1)}[V,U]^2 + 4M r[V,U] r^{(0,2)}[V,U] + (2M+r[V,U]) r^{(1,0)}[V,U]^2)}{4096M^7 r[V,U]^2} \\
R^{3030} &= -\frac{e^{-\frac{r[V,U]}{M}} \text{Csc}[\theta]^2 ((2M+r[V,U]) (r^{(0,1)}[V,U]^2 + r^{(1,0)}[V,U]^2) + 4M r[V,U] r^{(2,0)}[V,U])}{4096M^7 r[V,U]^2} \\
R^{3031} &= \frac{e^{-\frac{r[V,U]}{M}} \text{Csc}[\theta]^2 ((2M+r[V,U]) r^{(0,1)}[V,U] r^{(1,0)}[V,U] + 2M r[V,U] r^{(1,1)}[V,U])}{2048M^7 r[V,U]^2} \\
R^{3130} &= \frac{e^{-\frac{r[V,U]}{M}} \text{Csc}[\theta]^2 ((2M+r[V,U]) r^{(0,1)}[V,U] r^{(1,0)}[V,U] + 2M r[V,U] r^{(1,1)}[V,U])}{2048M^7 r[V,U]^2} \\
R^{3131} &= -\frac{e^{-\frac{r[V,U]}{M}} \text{Csc}[\theta]^2 ((2M+r[V,U]) r^{(0,1)}[V,U]^2 + 4M r[V,U] r^{(0,2)}[V,U] + (2M+r[V,U]) r^{(1,0)}[V,U]^2)}{4096M^7 r[V,U]^2} \\
R^{3232} &= \frac{\text{Csc}[\theta]^2 \left(1 - \frac{e^{-\frac{r[V,U]}{2M}} r[V,U] (r^{(0,1)}[V,U]^2 - r^{(1,0)}[V,U]^2)}{32M^3} \right)}{r[V,U]^6}
\end{aligned}$$

$$R^2 = \frac{4}{r[V, U]^4} + \frac{e^{\frac{r[V, U]}{2M}} (-r^{(0,1)}[V, U]^2 + r^{(1,0)}[V, U]^2)}{4M^3 r[V, U]^3} + \frac{1}{4096M^8 r[V, U]^2}$$

$$e^{\frac{r[V, U]}{M}} \left(4(9M^2 + 4M r[V, U] + r[V, U]^2) r^{(0,1)}[V, U]^4 + 36M^2 r^{(1,0)}[V, U]^4 - 64M r[V, U] (2M + r[V, U]) r^{(0,1)}[V, U] r^{(1,0)}[V, U] r^{(1,1)}[V, U] + 4M r[V, U]^3 (r^{(0,2)}[V, U] - r^{(2,0)}[V, U])^2 + r[V, U]^4 (r^{(0,2)}[V, U] - r^{(2,0)}[V, U])^2 + 8M r[V, U] r^{(1,0)}[V, U]^2 (5M r^{(0,2)}[V, U] + 2r^{(1,0)}[V, U]^2 + 3M r^{(2,0)}[V, U]) + 4r^{(0,1)}[V, U]^2 (-18M^2 r^{(1,0)}[V, U]^2 + 2M r[V, U] (3M r^{(0,2)}[V, U] - 4r^{(1,0)}[V, U]^2 + 5M r^{(2,0)}[V, U]) + r[V, U]^2 (3M r^{(0,2)}[V, U] - 2r^{(1,0)}[V, U]^2 + 5M r^{(2,0)}[V, U])) + 4r[V, U]^2 (9M^2 r^{(0,2)}[V, U]^2 + r^{(1,0)}[V, U]^4 + 3M r^{(1,0)}[V, U]^2 r^{(2,0)}[V, U] + M r^{(0,2)}[V, U] (5r^{(1,0)}[V, U]^2 - 2M r^{(2,0)}[V, U]) + M^2 (-16r^{(1,1)}[V, U]^2 + 9r^{(2,0)}[V, U]^2)) \right)$$

Ricci Tensor:

$$R_{0,0} = \frac{-2(M+r[V, U]) r^{(0,1)}[V, U]^2 - 6M r^{(1,0)}[V, U]^2 + r[V, U]^2 (-r^{(0,2)}[V, U] + r^{(2,0)}[V, U]) - 2r[V, U] (M r^{(0,2)}[V, U] + r^{(1,0)}[V, U]^2 + 3M r^{(2,0)}[V, U])}{4M r[V, U]^2}$$

$$R_{1,0} = -\frac{\frac{(2M+r[V, U]) r^{(0,1)}[V, U] r^{(1,0)}[V, U]}{M} + 2r[V, U] r^{(1,1)}[V, U]}{r[V, U]^2}$$

$$R_{1,1} = \frac{-2(3M+r[V, U]) r^{(0,1)}[V, U]^2 - 2M r^{(1,0)}[V, U]^2 + r[V, U]^2 (r^{(0,2)}[V, U] - r^{(2,0)}[V, U]) - 2r[V, U] (3M r^{(0,2)}[V, U] + r^{(1,0)}[V, U]^2 + M r^{(2,0)}[V, U])}{4M r[V, U]^2}$$

$$R_{2,2} = 1 - \frac{e^{\frac{r[V, U]}{2M}} r[V, U] (r^{(0,1)}[V, U]^2 - r^{(1,0)}[V, U]^2 + r[V, U] (r^{(0,2)}[V, U] - r^{(2,0)}[V, U]))}{32M^3}$$

$$R_{3,3} = \text{Sin}[\theta]^2 - \frac{e^{\frac{r[V, U]}{2M}} r[V, U] \text{Sin}[\theta]^2 (r^{(0,1)}[V, U]^2 - r^{(1,0)}[V, U]^2 + r[V, U] (r^{(0,2)}[V, U] - r^{(2,0)}[V, U]))}{32M^3}$$

Curvature Scalar:

$$R = \frac{128 + \frac{e^{\frac{r[V, U]}{2M}} r[V, U] (-6M r^{(0,1)}[V, U]^2 + 6M r^{(1,0)}[V, U]^2 + r[V, U]^2 (r^{(0,2)}[V, U] - r^{(2,0)}[V, U]) + 6M r[V, U] (-r^{(0,2)}[V, U] + r^{(2,0)}[V, U]))}{M^4}}{64 r[V, U]^2}$$

Einstein Tensor:

$$G_{0,0} = -\frac{-64e^{\frac{r[V, U]}{2M}} M^3 + \frac{r[V, U] ((4M+r[V, U]) r^{(0,1)}[V, U]^2 + r[V, U] (4M r^{(0,2)}[V, U] + r^{(1,0)}[V, U]^2))}{M}}{2r[V, U]^3}$$

$$G_{1,0} = -\frac{\frac{(2M+r[V, U]) r^{(0,1)}[V, U] r^{(1,0)}[V, U]}{M} + 2r[V, U] r^{(1,1)}[V, U]}{r[V, U]^2}$$

$$G_{1,1} = -\frac{64e^{\frac{r[V, U]}{2M}} M^3 + 4r[V, U] r^{(1,0)}[V, U]^2 + \frac{r[V, U]^2 (r^{(0,1)}[V, U]^2 + r^{(1,0)}[V, U]^2 + 4M r^{(2,0)}[V, U])}{M}}{2r[V, U]^3}$$

$$G_{2,2} = \frac{e^{\frac{r[V, U]}{2M}} r[V, U] (2M r^{(0,1)}[V, U]^2 - 2M r^{(1,0)}[V, U]^2 + 2M r[V, U] (r^{(0,2)}[V, U] - r^{(2,0)}[V, U]) + r[V, U]^2 (-r^{(0,2)}[V, U] + r^{(2,0)}[V, U]))}{128M^4}$$

$$G_{3,3} = \frac{e^{\frac{r[V, U]}{2M}} r[V, U] \text{Sin}[\theta]^2 (2M r^{(0,1)}[V, U]^2 - 2M r^{(1,0)}[V, U]^2 + 2M r[V, U] (r^{(0,2)}[V, U] - r^{(2,0)}[V, U]) + r[V, U]^2 (-r^{(0,2)}[V, U] + r^{(2,0)}[V, U]))}{128M^4}$$

Weyl Tensor:

$$C_{1,0,1,0} = \frac{e^{-\frac{r[V,U]}{M}} \left(-1024 M^6 - 8 e^{\frac{r[V,U]}{2M}} M^2 r[V,U] (-6 M r^{(0,1)}[V,U]^2 + 6 M r[V,U] r^{(0,2)}[V,U] + r[V,U]^2 r^{(0,2)}[V,U] + 6 M r^{(1,0)}[V,U]^2 - r[V,U] (6 M + r[V,U]) r^{(2,0)}[V,U] \right)}{3 r[V,U]^4}$$

$$C_{2,0,2,0} = \frac{1}{24} \left(\frac{128 e^{-\frac{r[V,U]}{2M}} M^3}{r[V,U]} - 6 r^{(0,1)}[V,U]^2 + 6 r^{(1,0)}[V,U]^2 + \frac{r[V,U] (6 M + r[V,U]) (r^{(0,2)}[V,U] - r^{(2,0)}[V,U])}{M} \right)$$

$$C_{2,1,2,1} = \frac{1}{24} \left(-\frac{128 e^{-\frac{r[V,U]}{2M}} M^3}{r[V,U]} + 6 (r^{(0,1)}[V,U]^2 - r^{(1,0)}[V,U]^2) - \frac{r[V,U] (6 M + r[V,U]) (r^{(0,2)}[V,U] - r^{(2,0)}[V,U])}{M} \right)$$

$$C_{3,0,3,0} = \frac{1}{24} \sin[\theta]^2 \left(\frac{128 e^{-\frac{r[V,U]}{2M}} M^3}{r[V,U]} - 6 r^{(0,1)}[V,U]^2 + 6 r^{(1,0)}[V,U]^2 + \frac{r[V,U] (6 M + r[V,U]) (r^{(0,2)}[V,U] - r^{(2,0)}[V,U])}{M} \right)$$

$$C_{3,1,3,1} = \frac{1}{24} \sin[\theta]^2 \left(-\frac{128 e^{-\frac{r[V,U]}{2M}} M^3}{r[V,U]} + 6 (r^{(0,1)}[V,U]^2 - r^{(1,0)}[V,U]^2) - \frac{r[V,U] (6 M + r[V,U]) (r^{(0,2)}[V,U] - r^{(2,0)}[V,U])}{M} \right)$$

$$C_{3,2,3,2} = \frac{r[V,U]^2 \sin[\theta]^2 \left(128 M^4 + e^{\frac{r[V,U]}{2M}} r[V,U] (-6 M r^{(0,1)}[V,U]^2 + 6 M r[V,U] r^{(0,2)}[V,U] + r[V,U]^2 r^{(0,2)}[V,U] + 6 M r^{(1,0)}[V,U]^2 - r[V,U] (6 M + r[V,U]) r^{(2,0)}[V,U]) \right)}{384 M^4}$$

Geodesic Equations:

$$V_{\tau\tau} + \frac{16 M^2 (2 M + r[V,U]) U_\tau V_\tau r^{(0,1)}[V,U] + \left(16 M^3 (U_\tau^2 + V_\tau^2) + 8 M^2 r[V,U] (U_\tau^2 + V_\tau^2) - e^{\frac{r[V,U]}{2M}} r[V,U]^3 (\theta_\tau^2 + \sin^2[\theta] \phi_\tau^2) \right) r^{(1,0)}[V,U]}{32 M^3 r[V,U]} = 0$$

$$U_{\tau\tau} + \frac{\left(16 M^3 (U_\tau^2 + V_\tau^2) + 8 M^2 r[V,U] (U_\tau^2 + V_\tau^2) + e^{\frac{r[V,U]}{2M}} r[V,U]^3 (\theta_\tau^2 + \sin^2[\theta] \phi_\tau^2) \right) r^{(0,1)}[V,U] + 16 M^2 (2 M + r[V,U]) U_\tau V_\tau r^{(1,0)}[V,U]}{32 M^3 r[V,U]} = 0$$

$$\theta_{\tau\tau} + \frac{-\cos[\theta] \sin[\theta] \phi_\tau^2 + \frac{2 \theta_\tau (U_\tau r^{(0,1)}[V,U] + V_\tau r^{(1,0)}[V,U])}{r[V,U]}}{r[V,U]} = 0$$

$$\phi_{\tau\tau} + \frac{2 \phi_\tau (\cot[\theta] r[V,U] \theta_\tau + U_\tau r^{(0,1)}[V,U] + V_\tau r^{(1,0)}[V,U])}{r[V,U]} = 0$$

Postscript

The code in this notebook is based on James Hartle's Mathematica programs written as companions to his book "Gravity: An Introduction to Einstein's General Relativity", available from the Book's site: <http://web.physics.ucsb.edu/~gravitybook/mathematica.html>

The original program was written by *Leonard Parker, University of Wisconsin, Milwaukee* (see the Acknowledgement section in the end of this notebook). The code in this notebook is a modification of the original program, adapted for the needs of the course "General Relativity and Cosmology" offered at the National Technical University of Athens, by Konstantinos Anagnostopoulos (<http://physics.ntua.gr/konstant>). The site of the course for the Spring 2023 can be found at <http://physics.ntua.gr/konstant/GR>.

This is the *Mathematica* notebook *Curvature and the Einstein Equation* available from the book website. From a given metric $g_{\alpha\beta}$, it computes the components of the following: the inverse metric, $g^{\lambda\sigma}$, the Christoffel symbols or affine connection,

$$\Gamma^\lambda_{\mu\nu} = \frac{1}{2} g^{\lambda\sigma} (\partial_\mu g_{\sigma\nu} + \partial_\nu g_{\sigma\mu} - \partial_\sigma g_{\mu\nu}),$$

(∂_α stands for the partial derivative $\partial/\partial x^\alpha$), the Riemann tensor,

$$R^\lambda{}_{\mu\nu\sigma} = \partial_\nu \Gamma^\lambda{}_{\mu\sigma} - \partial_\sigma \Gamma^\lambda{}_{\mu\nu} + \Gamma^\lambda{}_{\eta\nu} \Gamma^\eta{}_{\mu\sigma} - \Gamma^\lambda{}_{\eta\sigma} \Gamma^\eta{}_{\mu\nu},$$

the Ricci tensor

$$R_{\mu\nu} = R^\lambda{}_{\mu\lambda\nu},$$

the scalar curvature,

$$R = g^{\mu\nu} R_{\mu\nu},$$

and the Einstein tensor,

$$G_{\mu\nu} = R_{\mu\nu} - \frac{1}{2} g_{\mu\nu} R.$$

You must input the covariant components of the metric tensor $g_{\mu\nu}$ by editing the relevant input line in this *Mathematica* notebook. You may also wish to change the names of the coordinates. Only the nonzero components of the above quantities are displayed as the output. All the components computed are in the *coordinate basis* in which the metric was specified.