

- The Metric
- Causal Structure

The metric is an additional structure on a manifold

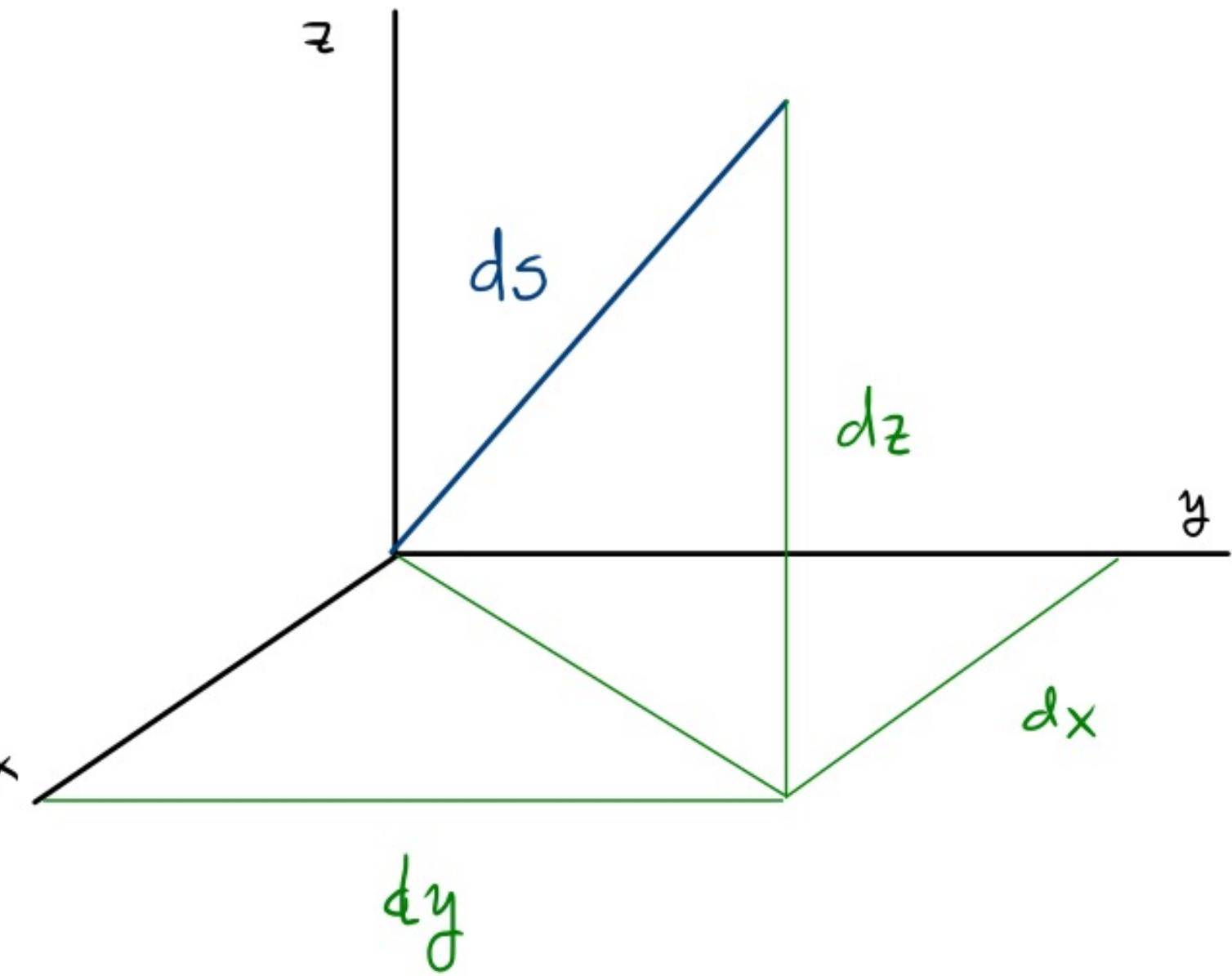
It provides:

- locally inertial frames - where physics is easy...
- causality: future, past, max "speed of light"
- geometric, observer independent { path length  
proper time
- parallel transport, geodesics: { locally "straightest" curves  
longest times
- geodesics: paths of the free!
- curvature = gravitation

• Line element: infinitesimal length

- Euclidean  $\mathbb{R}^3$ :

$$ds^2 = dx^2 + dy^2 + dz^2$$



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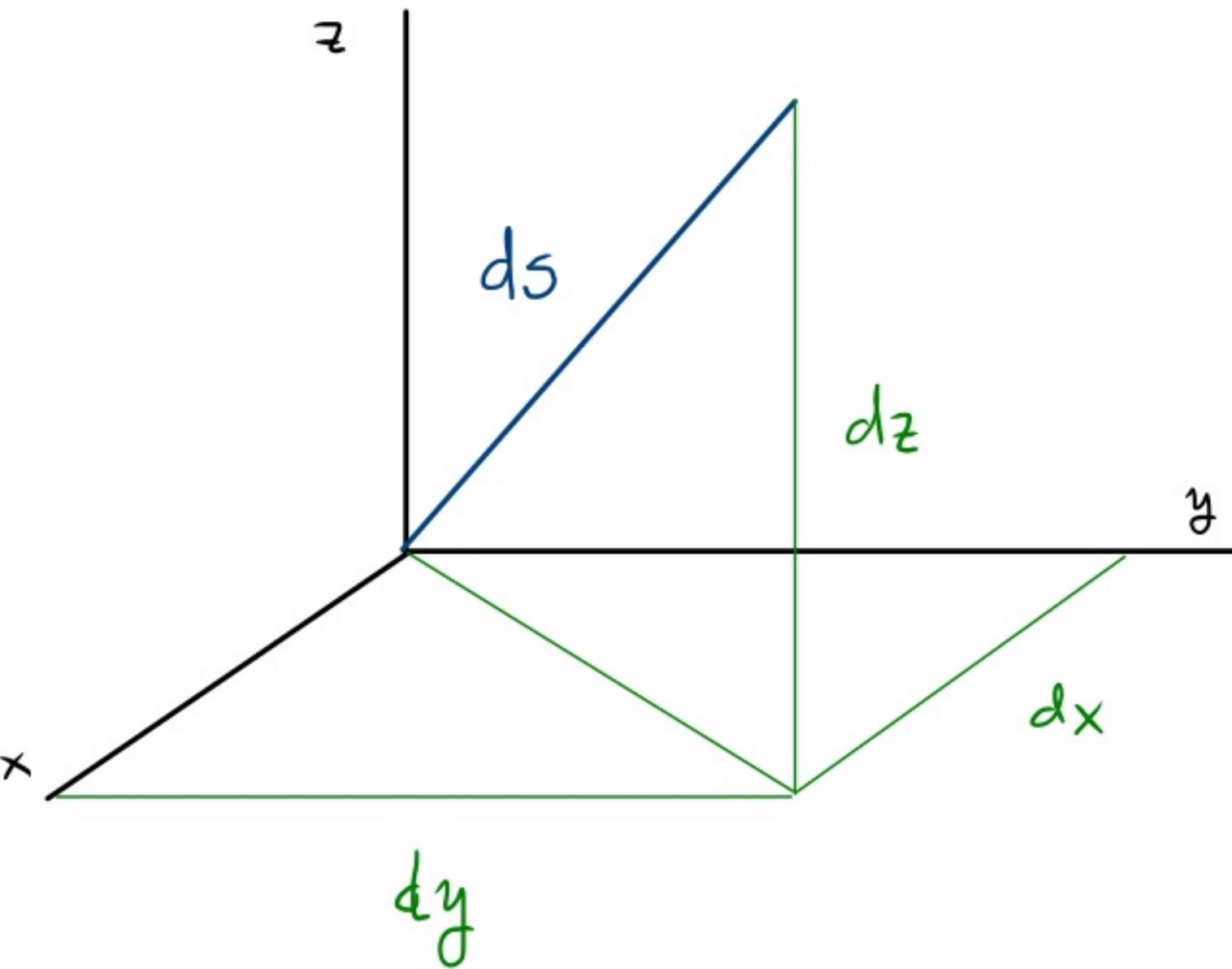
$$ds^2 = dx^2 + dy^2 + dz^2$$

But also:

$$ds^2 = dr^2 + r^2 d\theta^2 + r^2 \sin^2\theta d\varphi^2$$

$$= d\rho^2 + \rho^2 d\varphi^2 + dz^2$$

= ...



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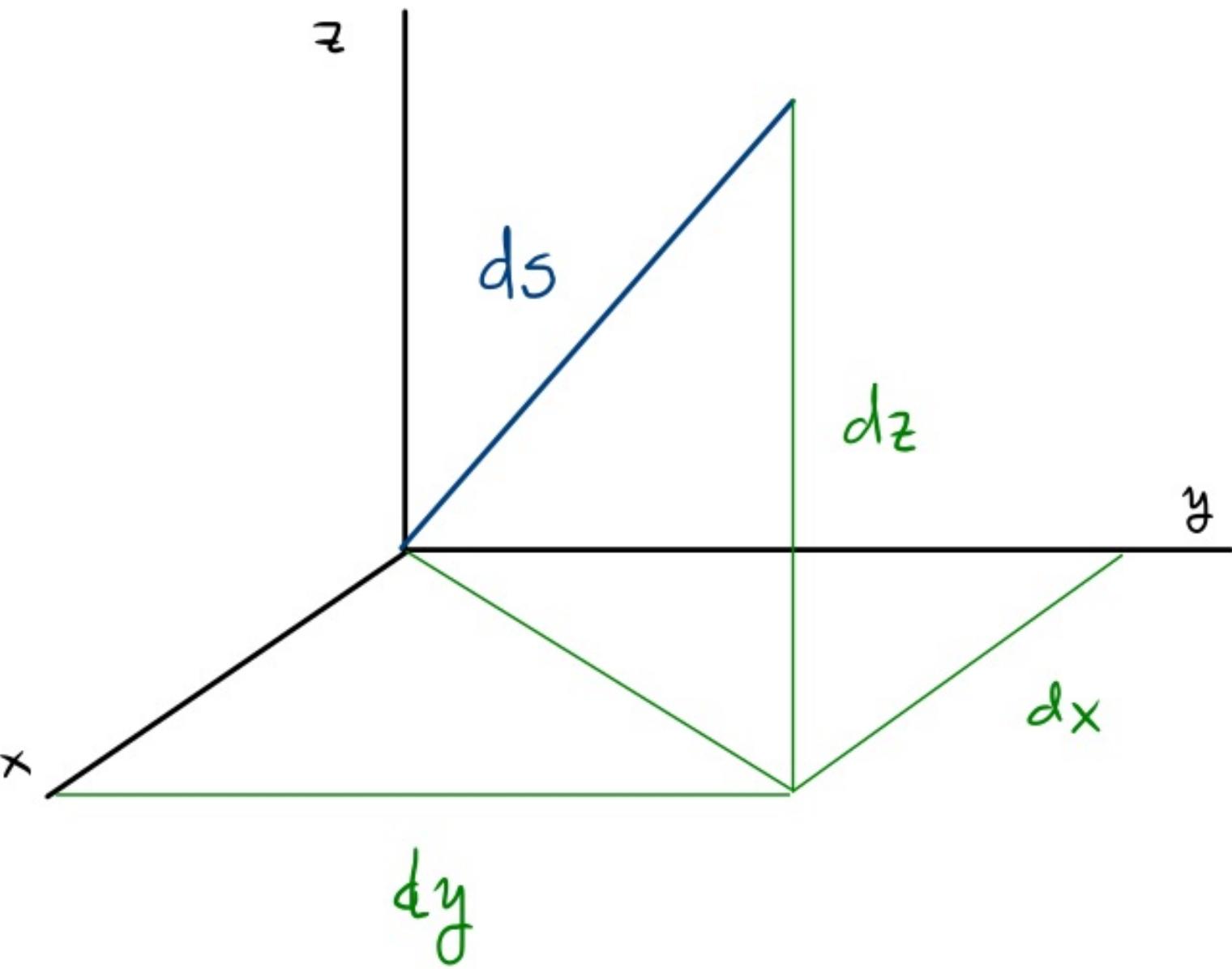
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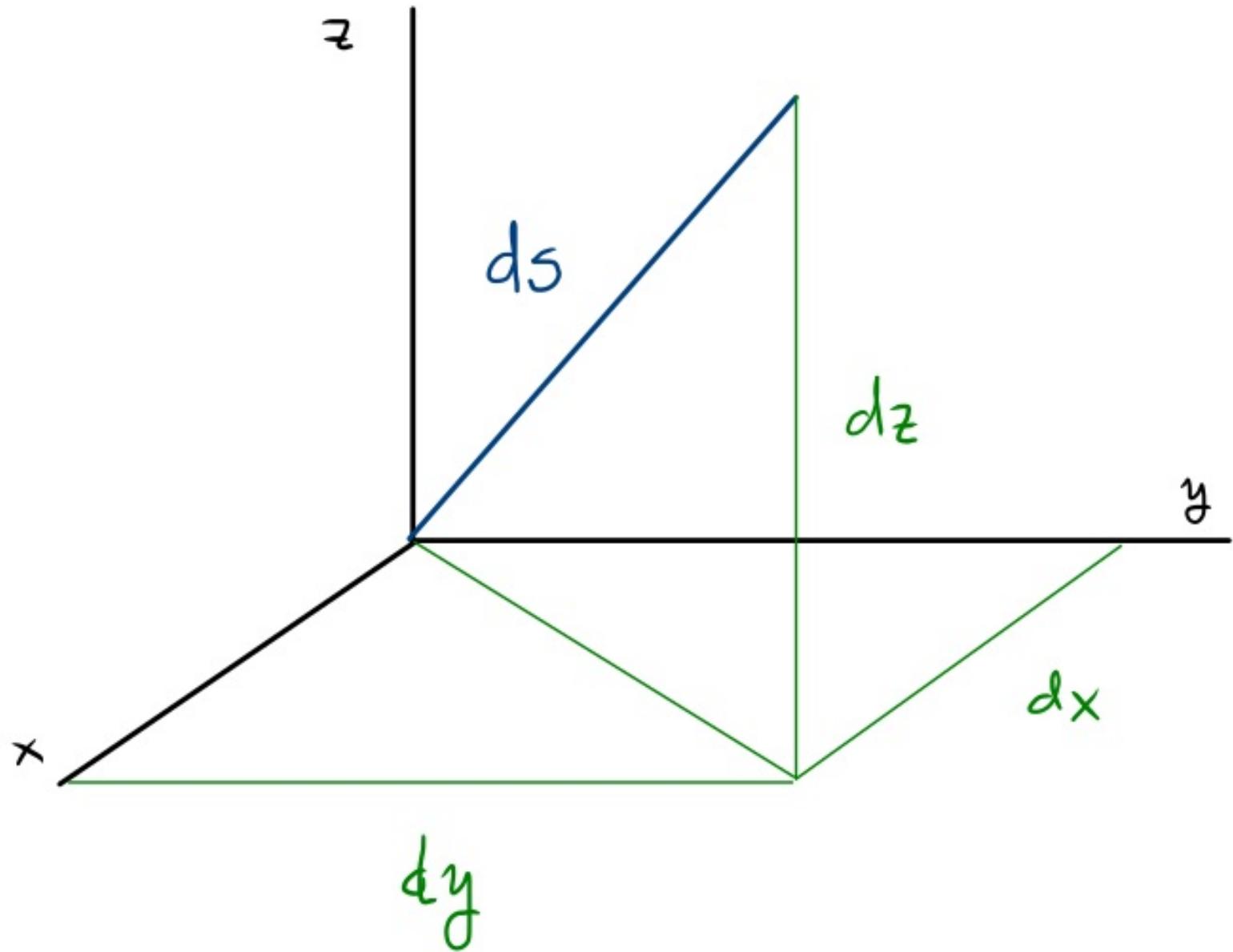
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symmetric

$g_{\mu\nu}$ : a  $(0,2)$  symmetric tensor



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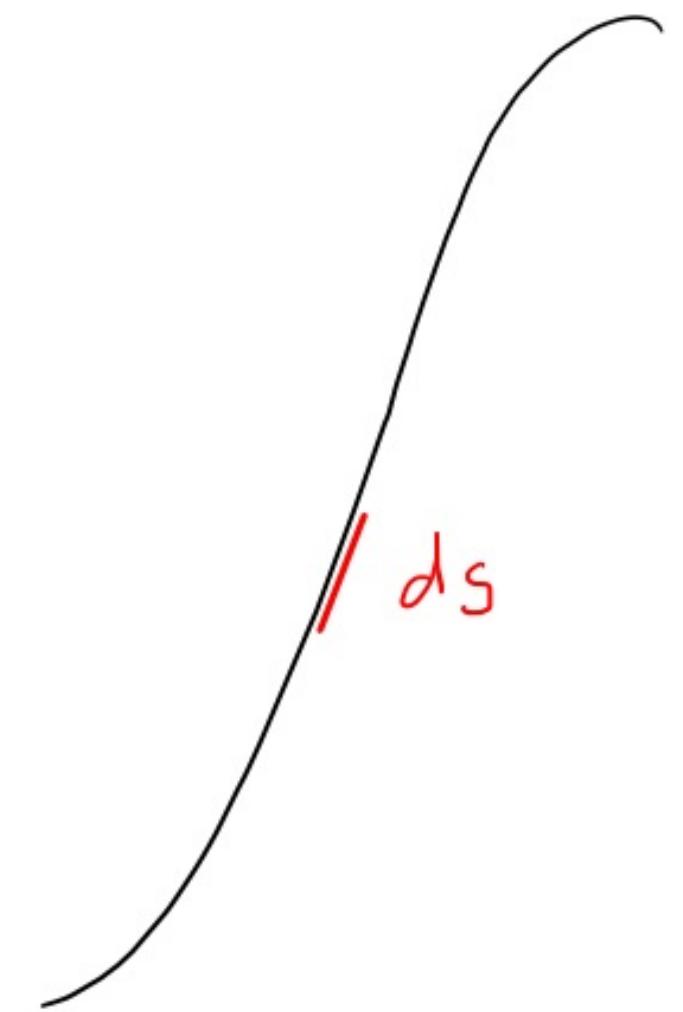
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- Length of a finite curve:

$$s = \int ds = \int (dx^2 + dy^2 + dz^2)^{1/2} = \int dt \left\{ \left( \frac{dx}{dt} \right)^2 + \left( \frac{dy}{dt} \right)^2 + \left( \frac{dz}{dt} \right)^2 \right\}^{1/2}$$

↳ line integral on curve  $\gamma(t)$

$x(t), y(t), z(t)$   
must be given



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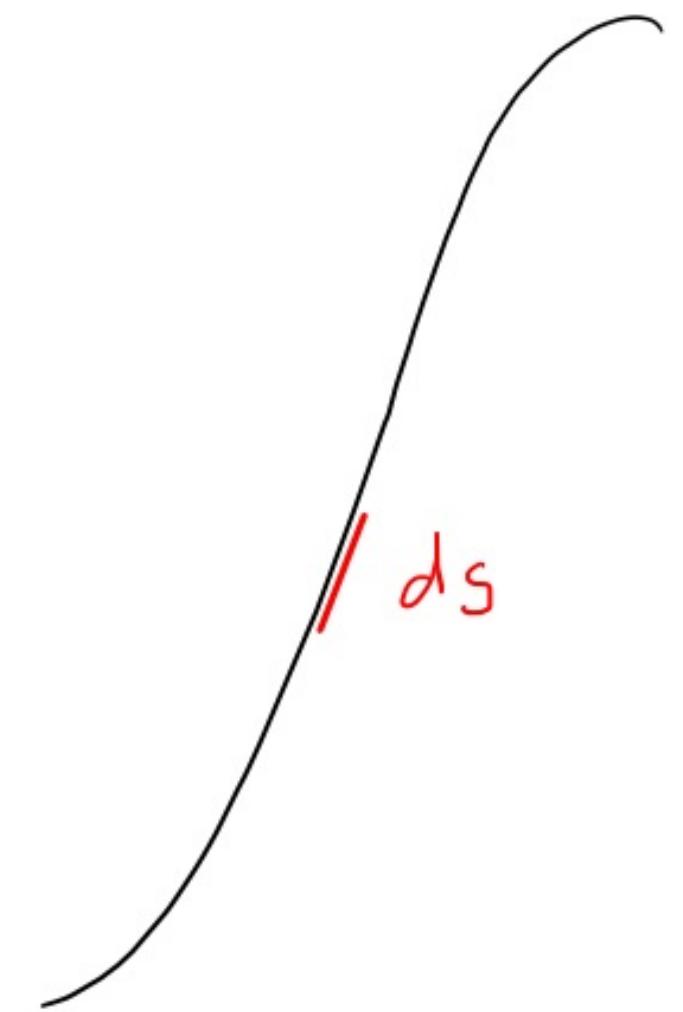
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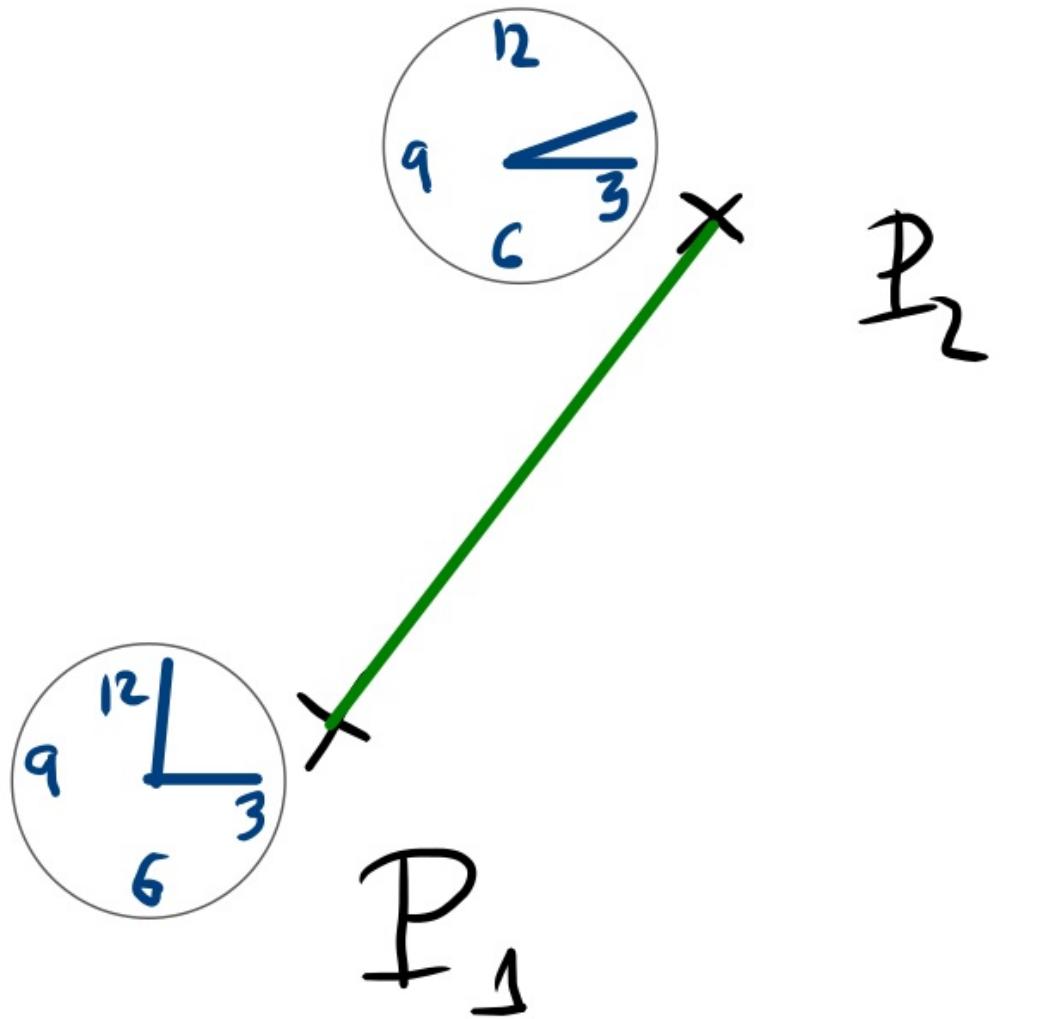
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$$= \int \{ g_{\mu\nu} dx^\mu dx^\nu \}^{1/2} = \int dt \left\{ g_{\mu\nu} \frac{dx^\mu}{dt} \frac{dx^\nu}{dt} \right\}^{1/2}$$



- Line element: infinitesimal length
- Minkowski metric on  $\mathbb{R}^4$ : spacetime of events!
 
$$ds^2 = -dt^2 + dx^2 + dy^2 + dz^2$$

$$= (\text{spacetime distance of events})^2$$
- worldline of observer: chooses coordinates w.r.t. which she stays @ same place:
 
$$dx = dy = dz = 0$$

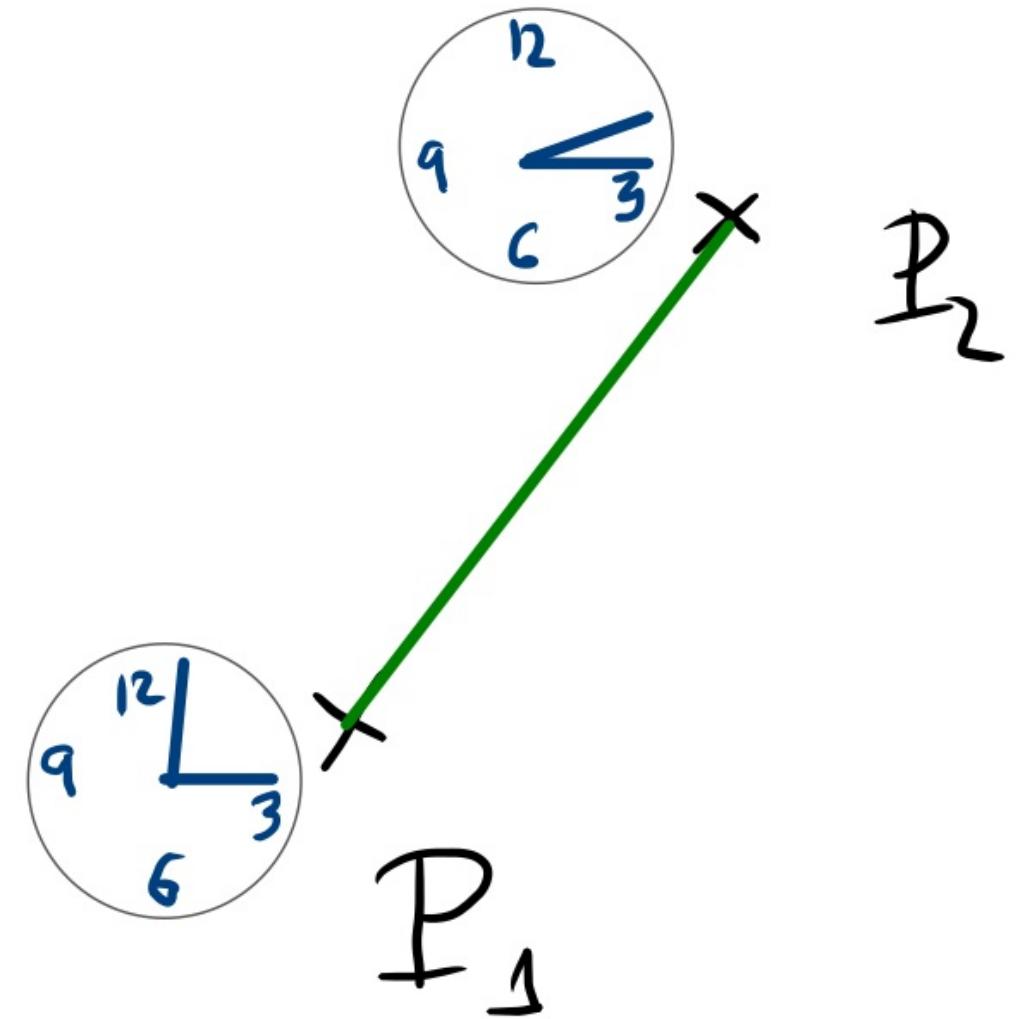


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$$\Rightarrow ds^2 = -d\tau^2$$

her clock is ticking @  $d\tau$ -rate  
her proper time

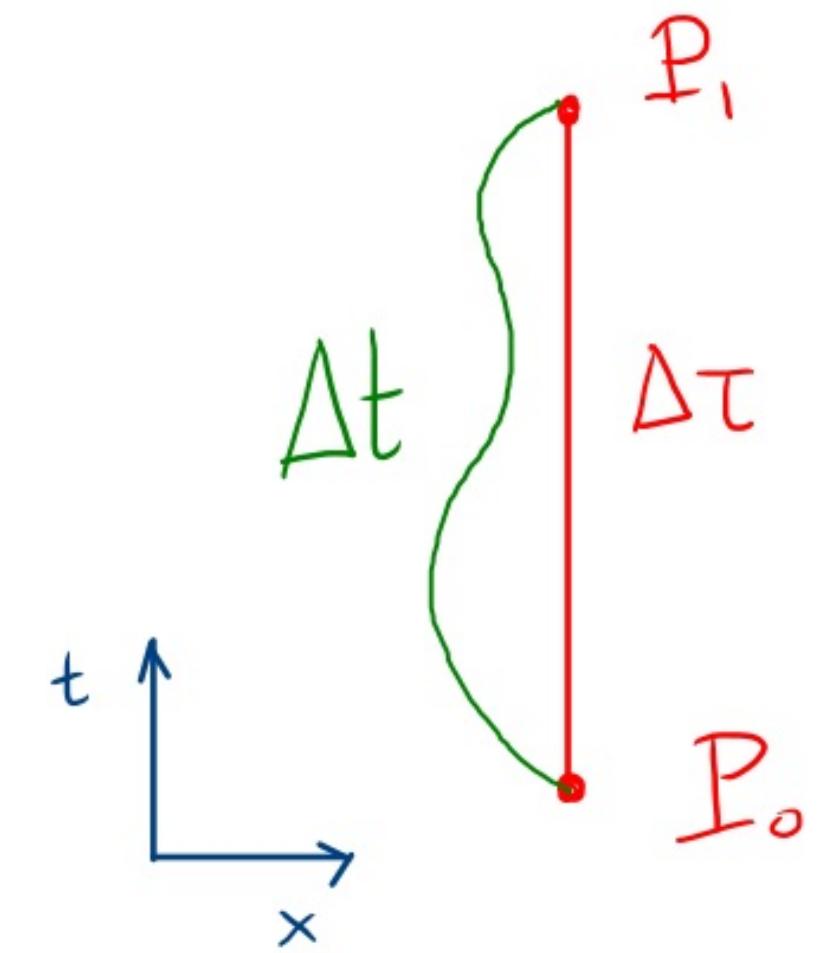


## Proper time:

- a geometric concept, independent of coordinates
- it is the longest time between two events ("twin paradox")

→ the free age faster than anyone else meeting @ same events

(the price of laziness...)



(Disclaimer: this simple picture may become more complicated in the case of large curvature and/or strange topology for events that are far from each other. Far compared to the scale of length introduced by the radius of curvature. Consult with your family's physicist.)

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## • Space:

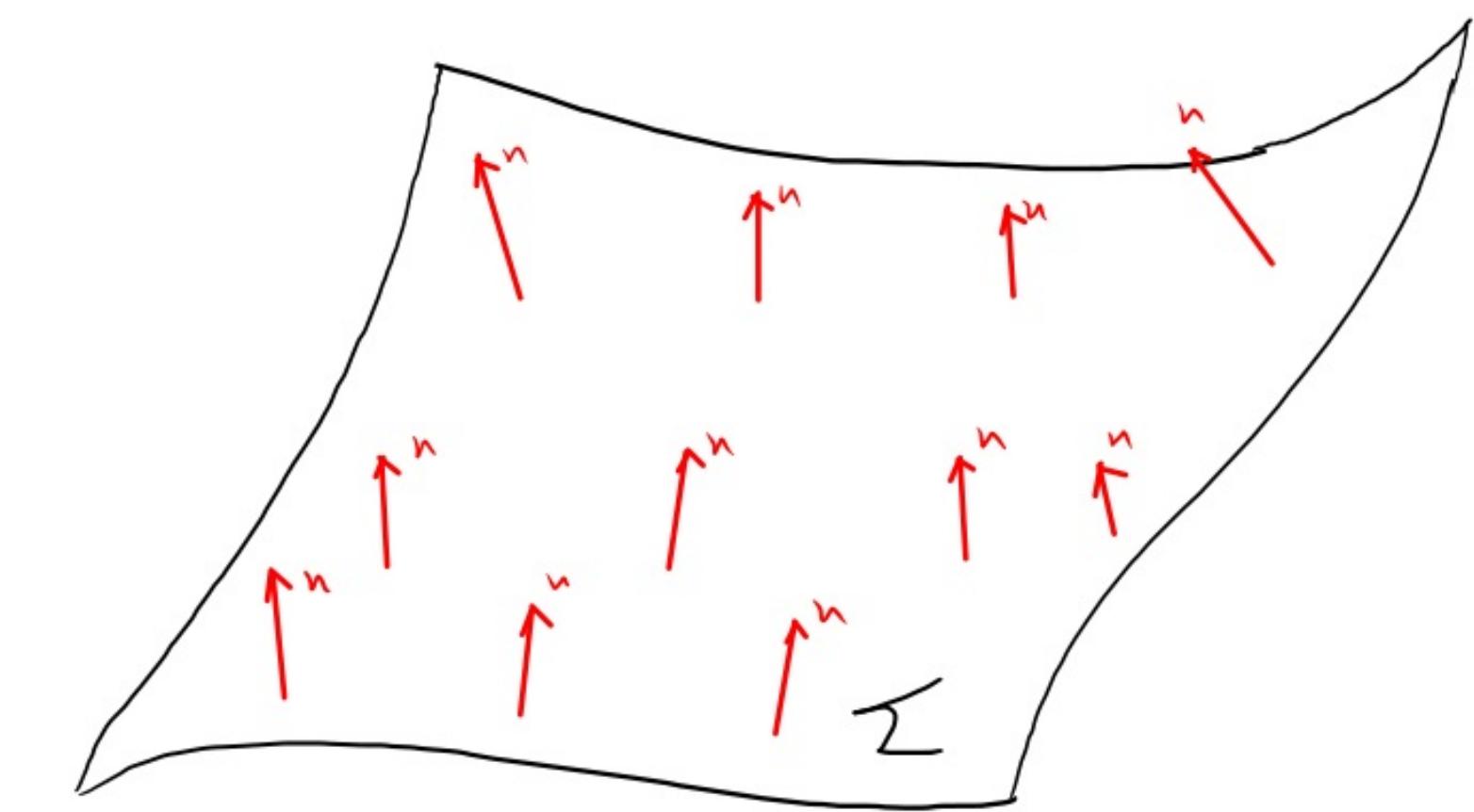
Defined by events for which  $dt = 0$

- the "simultaneous events"

- observer dependent

- a hypersurface w/metric  $d\Sigma^2 = dx^2 + dy^2 + dz^2 = g_{ij} dx^i dx^j \quad i,j=1,2,3$

- in GR, any "spacelike" surface can be "space". There may not be a natural way to choose one, or a global "constant" time defined on it.



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- \*  $g$  defines an inner product in  $T\mathcal{M}$ :  $V \cdot U = g(V,U)$
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- \* Theorem: every manifold has a Riemannian metric (comes from local diffeomorphicity to  $\mathbb{R}^n$ )

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\* There are many metrics on a manifold!

We choose the one to do geometry with...

Nature makes a dynamical choice: In GR, solution to Einstein Eqs.

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\* (iii)  $\Leftrightarrow$  the matrix  $(g_{\mu\nu})$  is invertible

$$\Leftrightarrow \det g \neq 0 \quad (\text{exercise, or see video...})$$

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\* we denote  $g^{-1}$  by  $g^{\mu\nu}$ , so that  $g^{\mu\rho} g_{\rho\nu} = \delta^\mu_\nu$

$\hookrightarrow$  also a symmetric tensor

## Index Raising/Lowering

A metric (and its inverse) gives rise to an isomorphism between  $T_e M$  and  $T_e^* M$

- If  $V \in T_e M$ , then  $g(V, \cdot) \in T_e^* M$

↳ a linear map from  $T_p M \rightarrow \mathbb{R}$

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for simplicity  $\tilde{V}_\mu \rightarrow V_\mu$

& we call the operation "index lowering"

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index  
raising

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- Similar maps between tensors of any rank. E.g.

$$F_{\mu}{}^{\rho} = g_{\mu\lambda} F^{\lambda\rho} \quad R_{\mu\nu\lambda\rho} = g_{\mu\sigma} R^{\sigma}{}_{\nu\lambda\rho} \quad A^{\mu\nu\rho} = g^{\mu\alpha} g^{\nu\beta} g^{\rho\gamma} A_{\alpha\beta\gamma}$$

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- Therefore index raising/lowering is 1-1, onto, "duality"  $\tilde{\bullet} = \bullet$   
between  $T_p^{(l,k)} M$  for  $l+k = \text{fixed}$

---

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  - \* the choice of a different metric results in different dual tensors
- Dual tensors do not depend on choice of basis/coordinates

Remember the duality between bases defined by  $e^\alpha(e_\beta) = \delta^\alpha_\beta$ ? This duality is basis-dependent and does not give a dual tensor independent of the choice of basis.

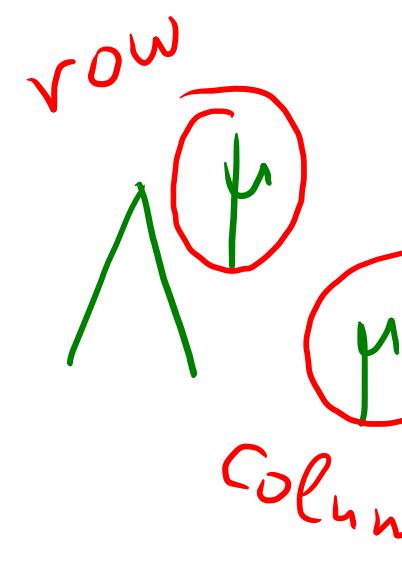
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$$\Lambda^\mu{}_\mu' = \frac{\partial x^\mu}{\partial x^{\mu'}}$$

*row*  


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row

column

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For any change of basis  $e_{\mu'} = \Lambda^\mu{}_{\mu'} e_\mu$

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where  $g_d = \text{diag}(g_0, g_1, \dots, g_{n-1}) = \begin{pmatrix} g_0 & 0 & \dots & 0 \\ 0 & g_1 & \dots & 0 \\ \vdots & 0 & \dots & 0 \\ 0 & 0 & \dots & g_{n-1} \end{pmatrix}$

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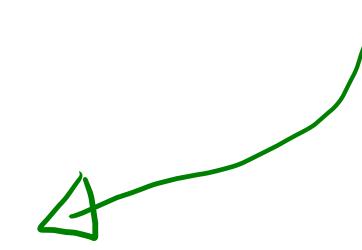
$$\begin{aligned} \text{Indeed: } g(\tilde{e}_\mu, \tilde{e}_\nu) &= g(\Lambda^{\mu'}_\mu e_{\mu'}, \Lambda^{\nu'}_\nu e_{\nu'}) = \Lambda^{\mu'}_\mu \Lambda^{\nu'}_\nu g(e_{\mu'}, e_{\nu'}) \\ &= \Lambda^{\mu'}_\mu \eta_{\mu' \nu'} \Lambda^{\nu'}_\nu = (\Lambda^T)_\mu^{\mu'} \eta_{\mu' \nu'} \Lambda^{\nu'}_\nu \\ &= (\Lambda^T \eta \Lambda)_{\mu \nu} \\ &= \eta_{\mu \nu} \end{aligned}$$

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If  $s$  is the signature of the metric, and

$s=0$  : the metric is Euclidean ,  $\Lambda \in O(n)$  orthogonal group  
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$s=1$  : the metric is Minkowskian  $\Lambda \in O(1, n-1)$   
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$O(1, n-1)$  : Lorentz group  
 $\Lambda$  a Lorentz xfm

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~ coordinate bases may consist of orthogonal vectors,  
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e.g.  $(\hat{r}, \hat{\theta}, \hat{\varphi})$  orthonormal

$(\partial_r, \partial_\theta, \partial_\varphi)$  are not!

$$g(\partial_r, \partial_r) = 1 \quad g(\partial_\theta, \partial_\theta) = r^2 \quad g(\partial_\varphi, \partial_\varphi) = r^2 \sin^2 \theta$$

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the coordinate basis at  $P$  is orthonormal

local Lorentz frame  
locally inertial coordinates

\* effects of curvature negligible in a small enough laboratory  
- physics is simple locally

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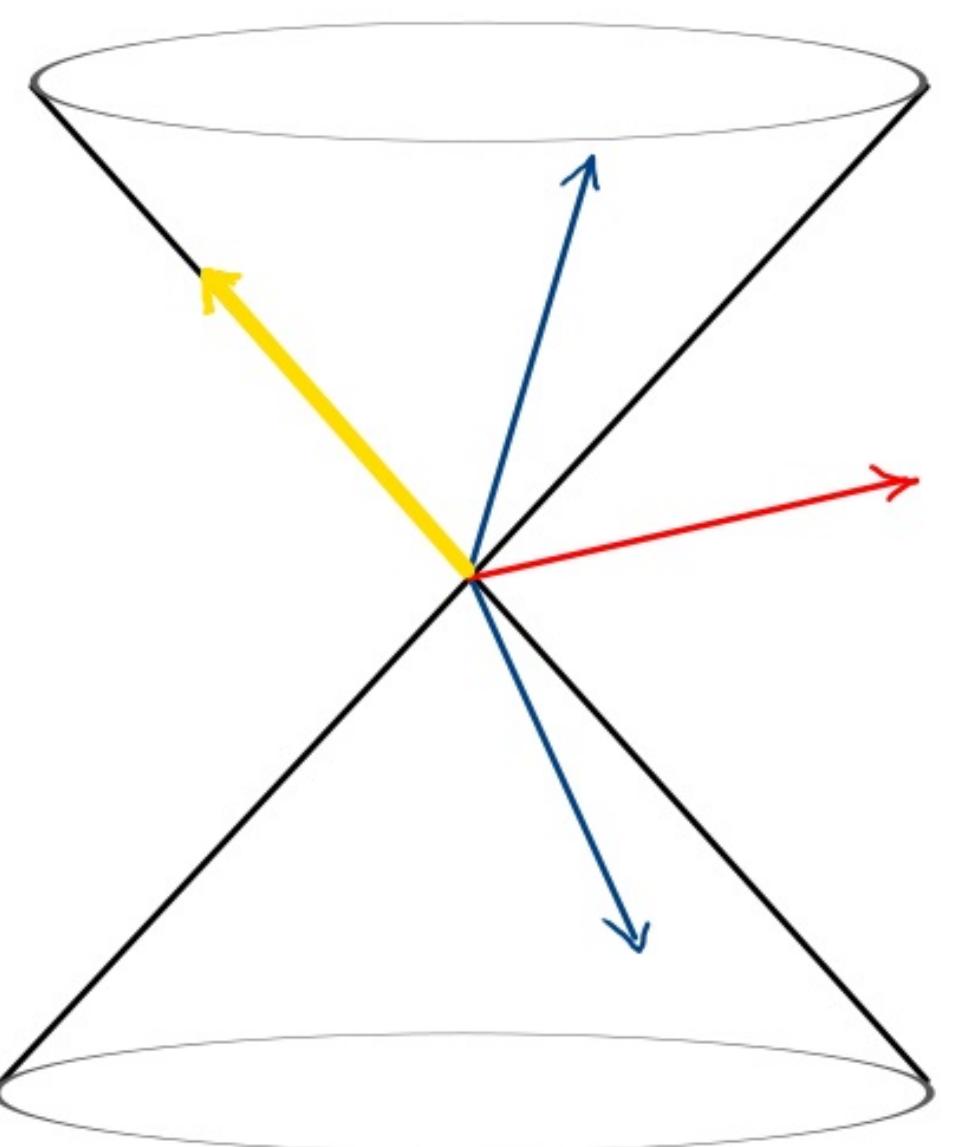
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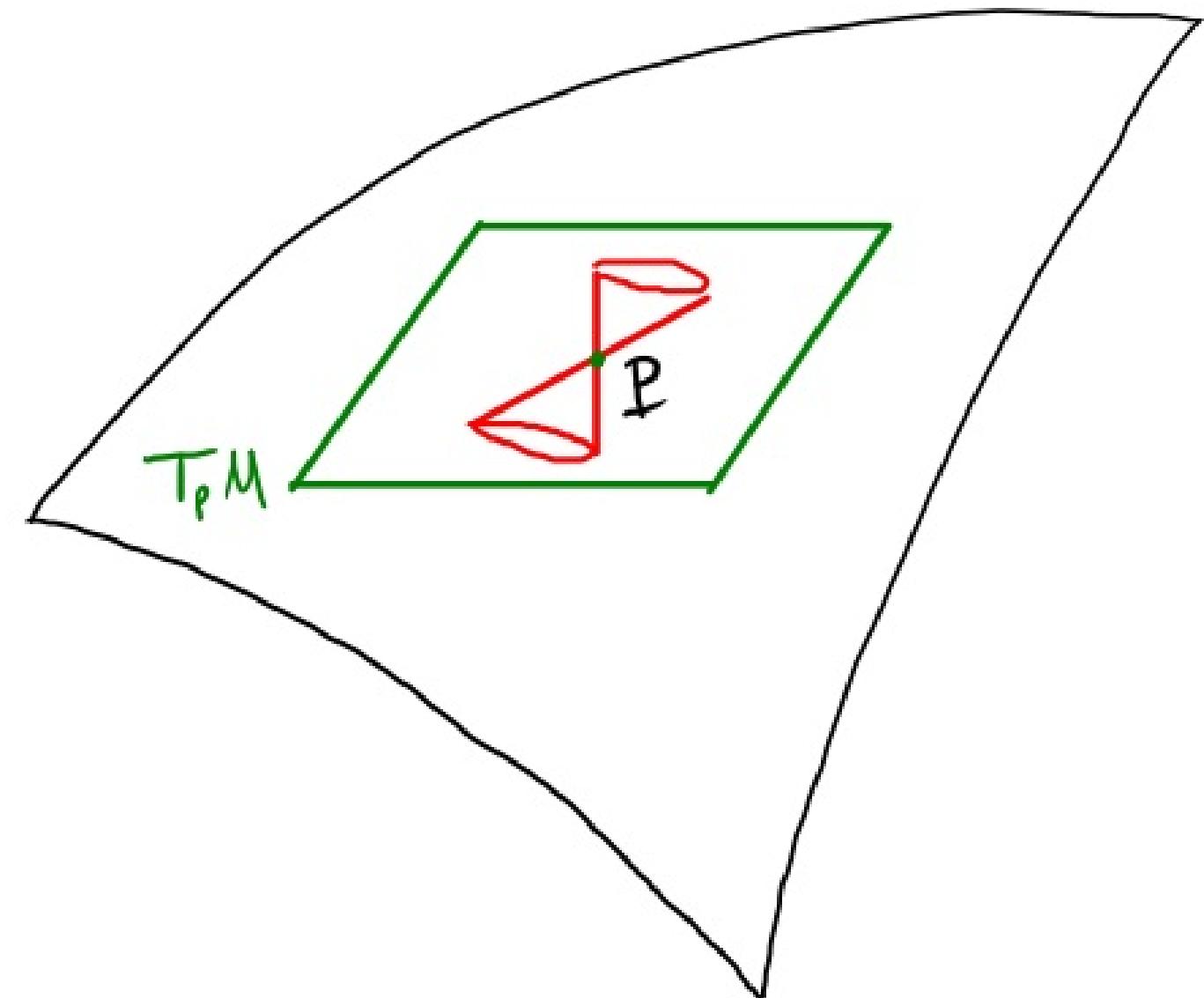
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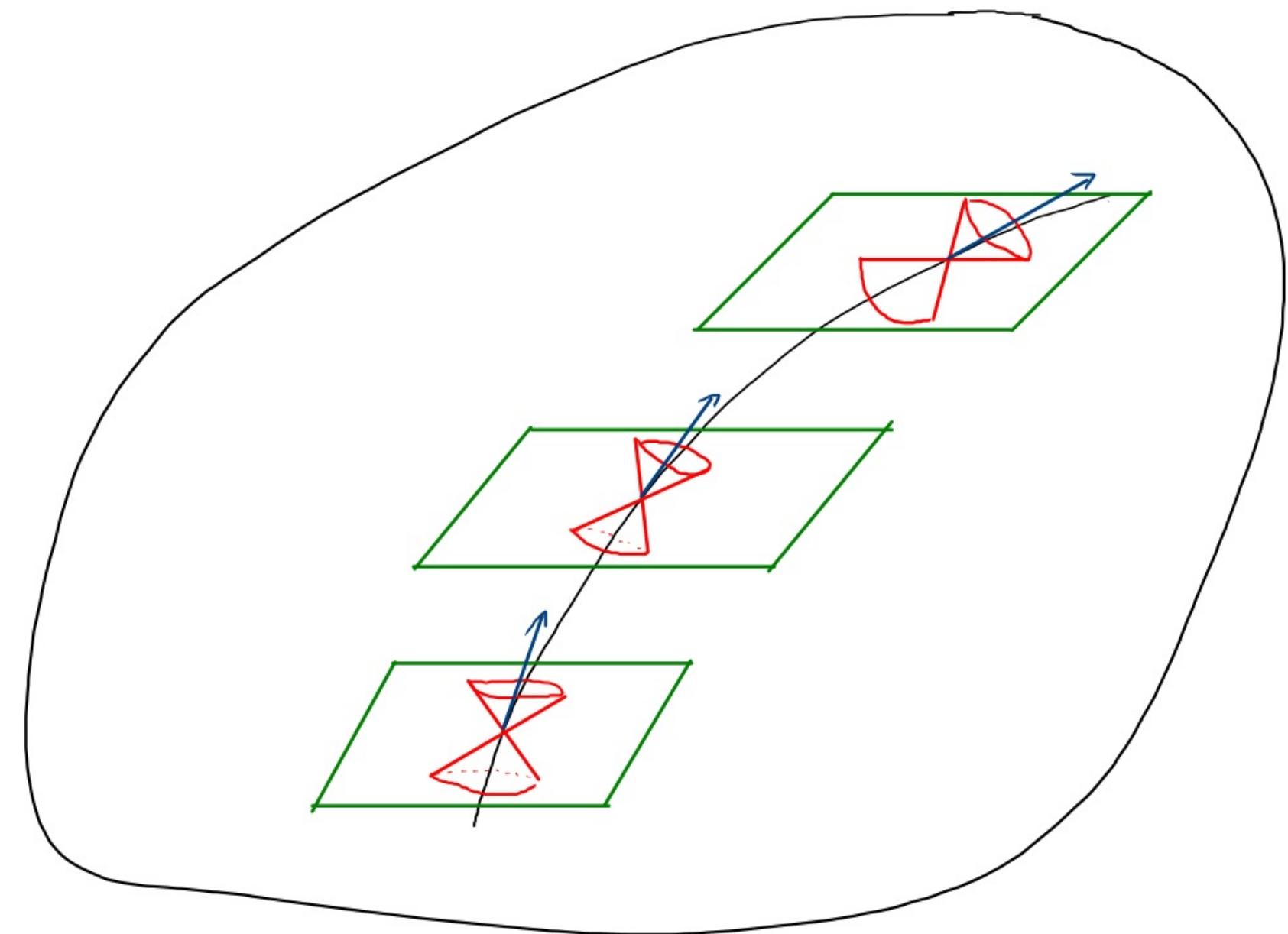
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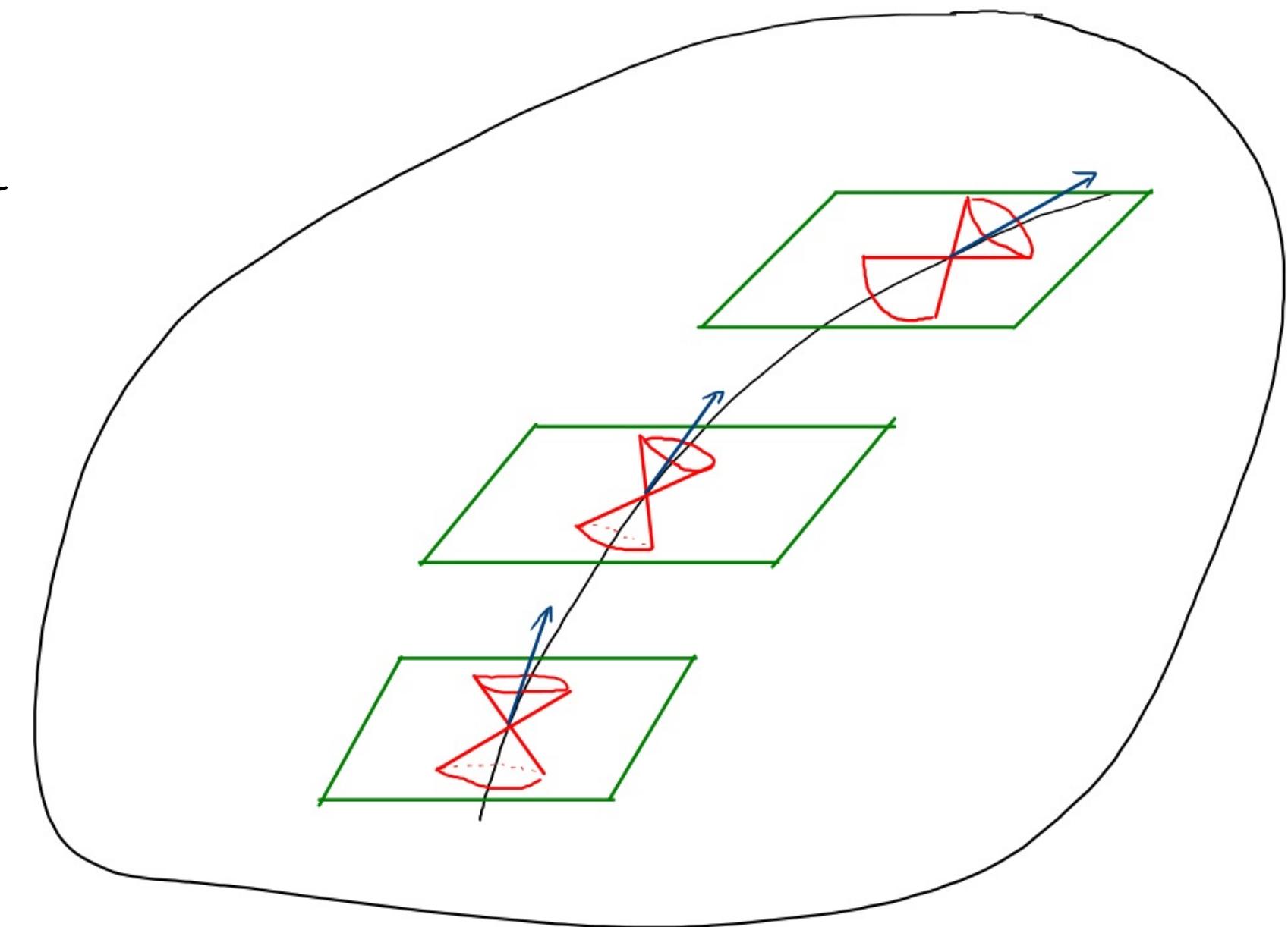


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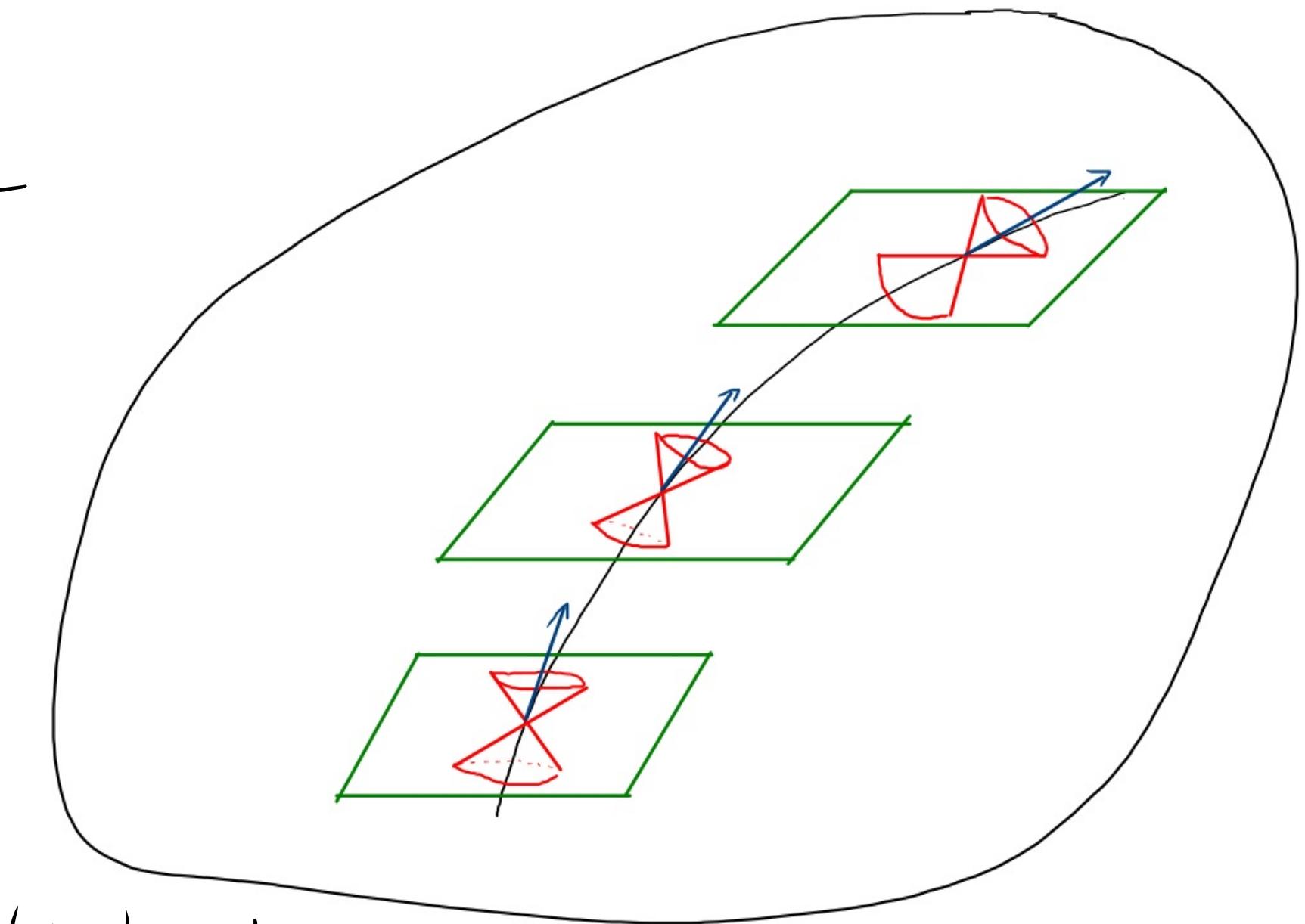


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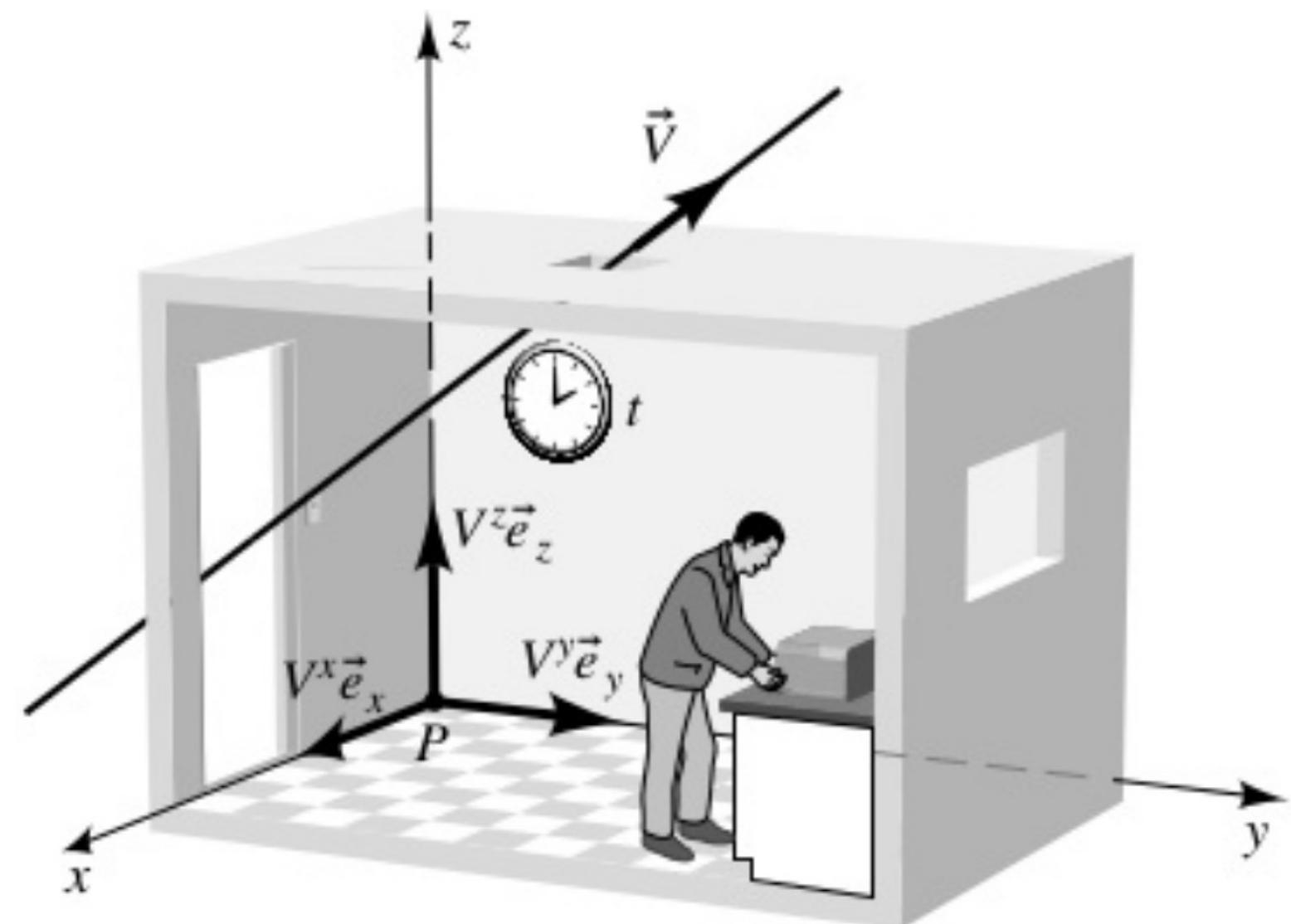
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- there are no worldlines with tangent vectors that change category



# Local Frames

Orthonormal bases define an "observer"



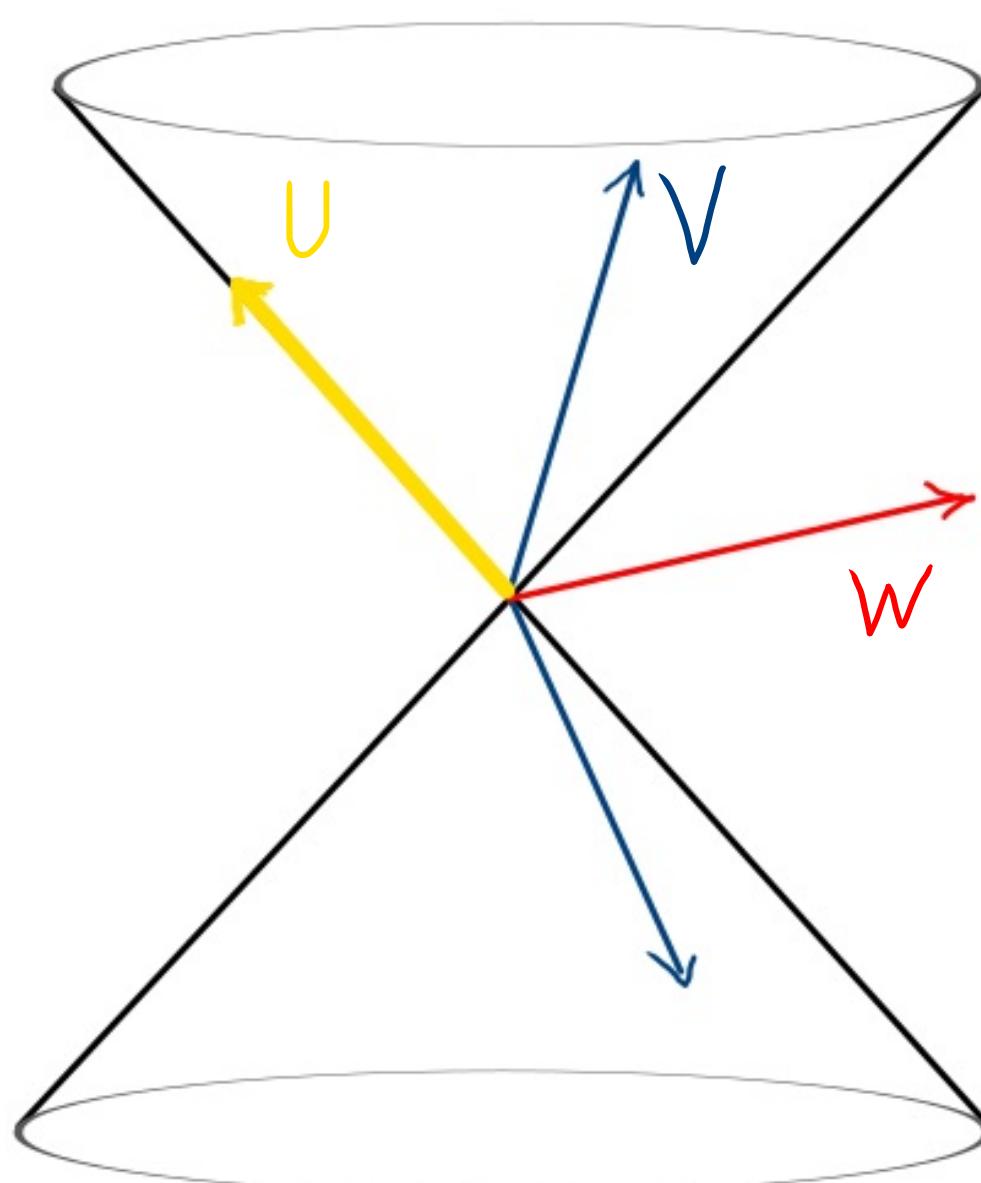
Hartle, Fig 7.6

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Orthonormal bases define an "observer"

four-velocity of observer  $u = e_0$

local cartesian axes  $\{e_1, e_2, e_3\}$

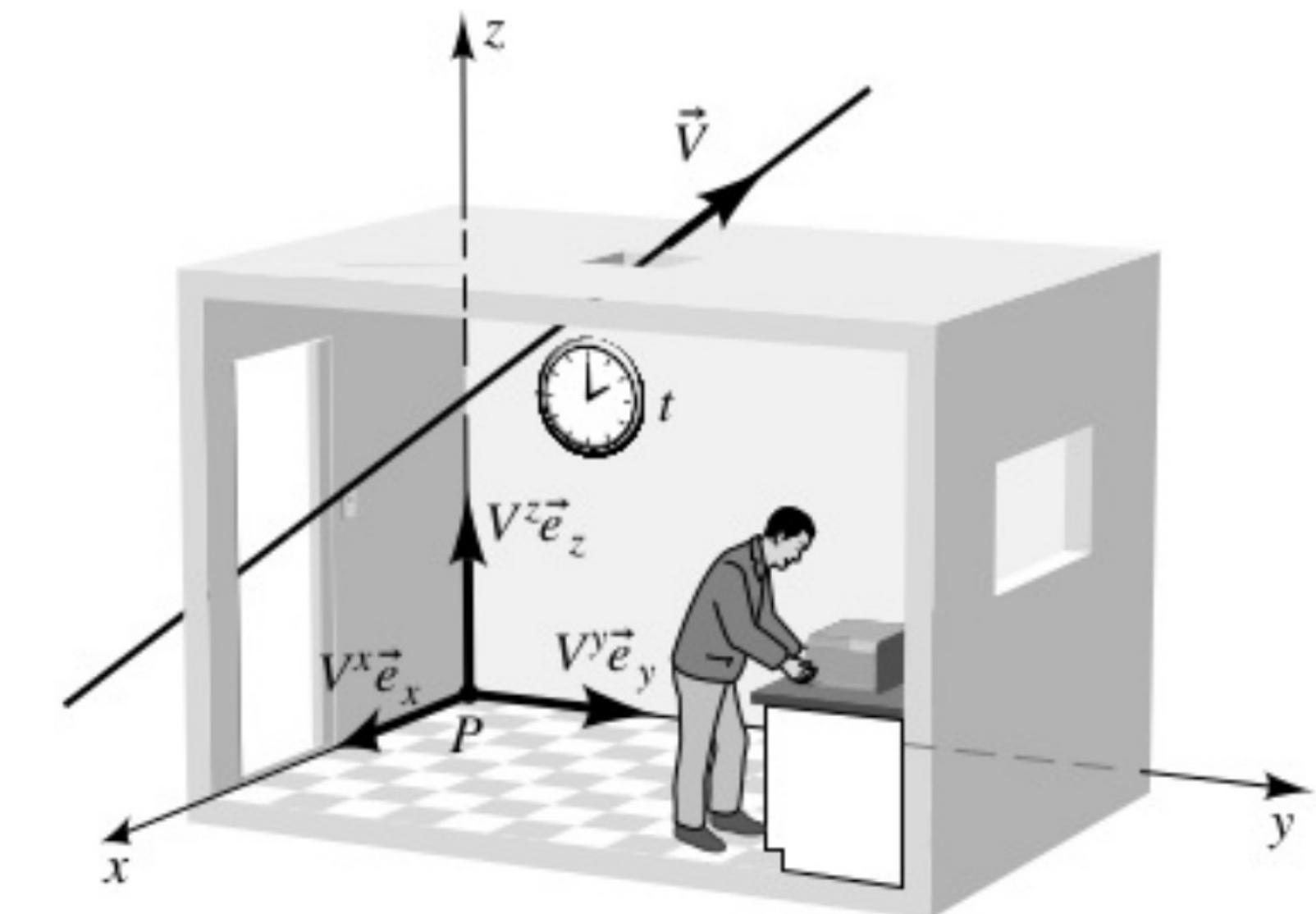


$\{e_0, e_1, e_2, e_3\}$  define the local light cone:

$$g(V, V) < 0 \quad \text{timelike}$$

$$g(U, U) = 0 \quad \text{null/lightlike}$$

$$g(W, W) > 0 \quad \text{spacelike}$$



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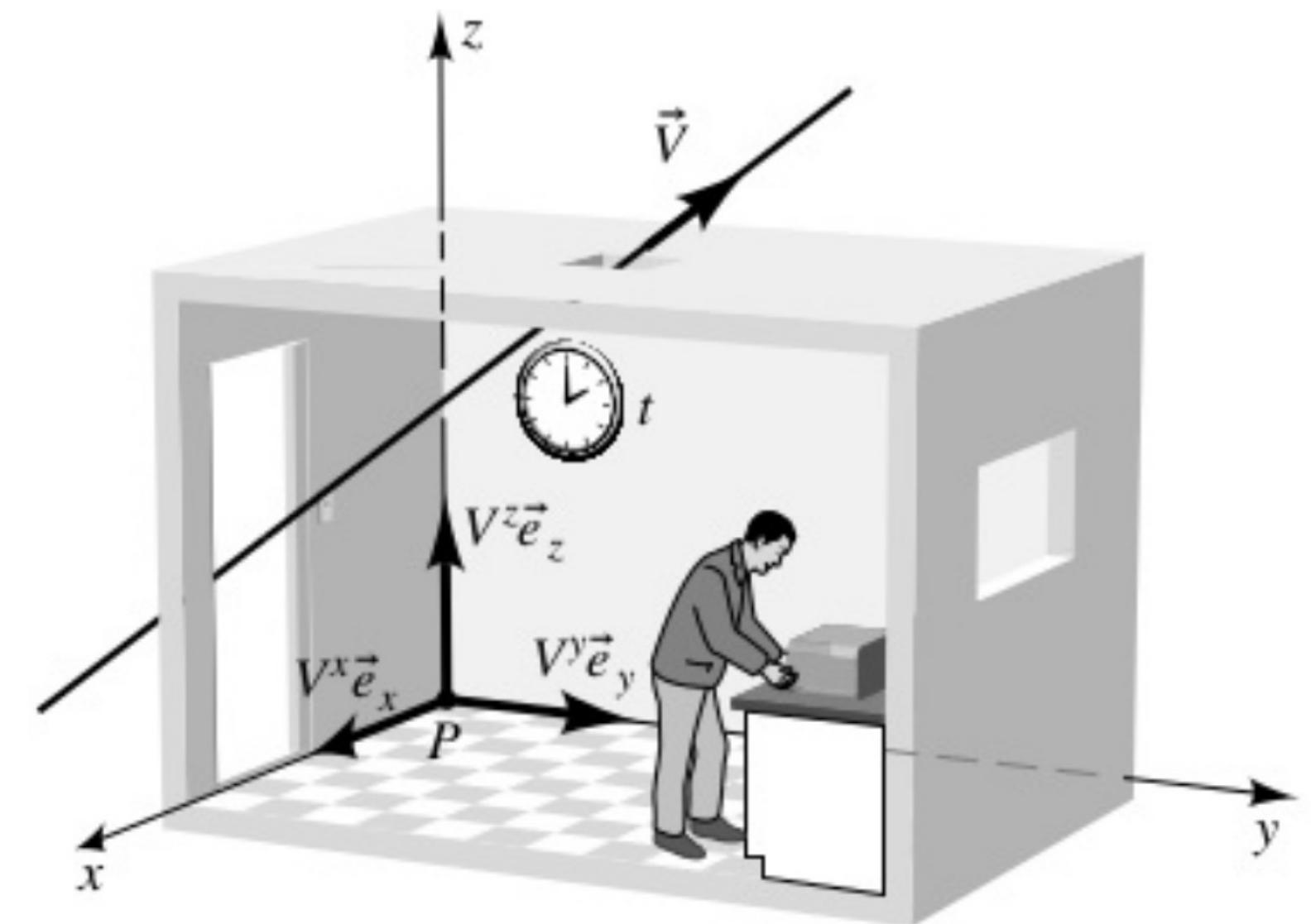
$$u = (1, 0, 0, 0) = e_0$$

Velocity of a passing by particle

$$V = (\gamma, \gamma u, 0, 0) = \gamma e_0 + \gamma u e_1$$

velocity

4-velocity



Hartle, Fig 7.6

## Local Frames

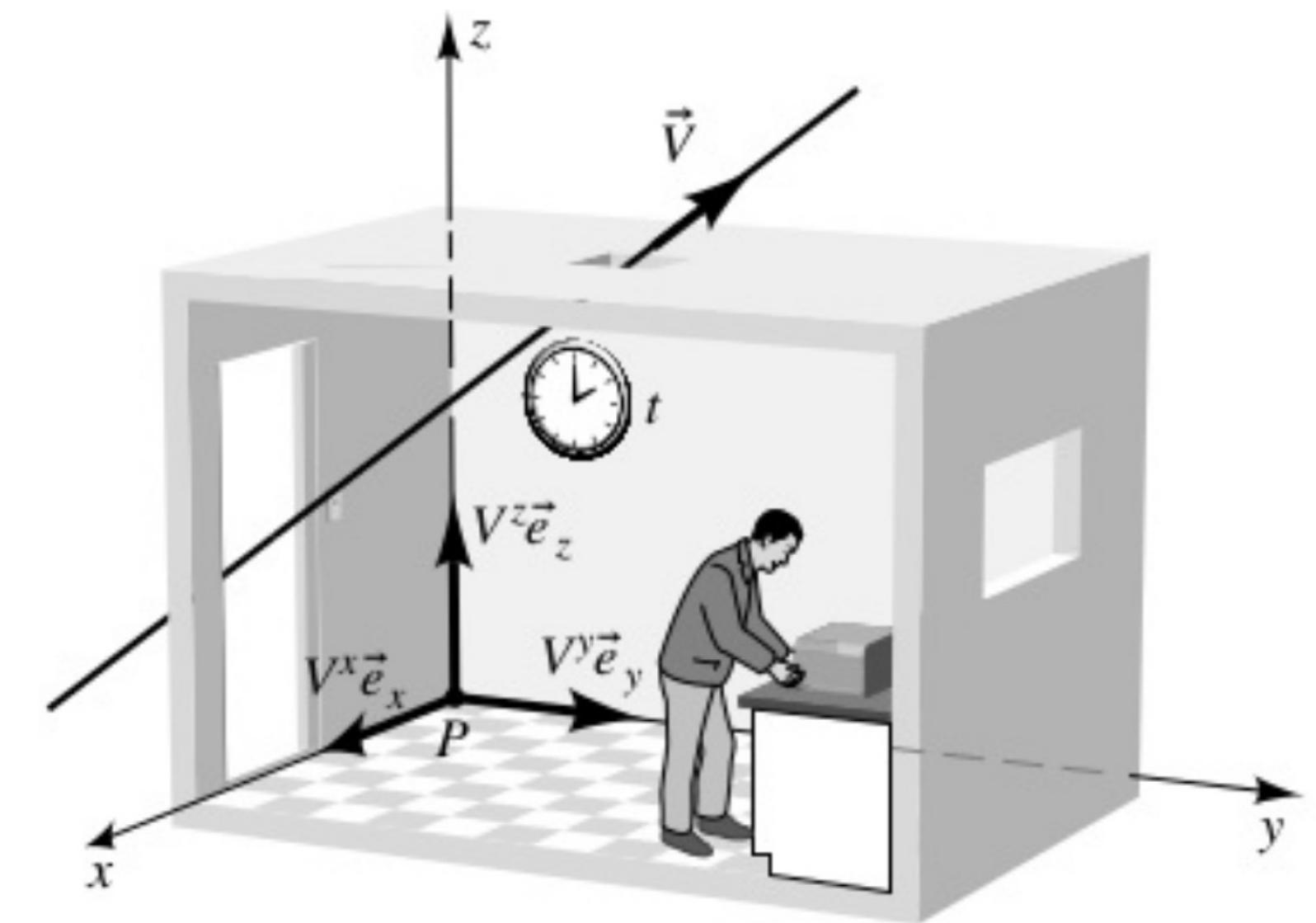
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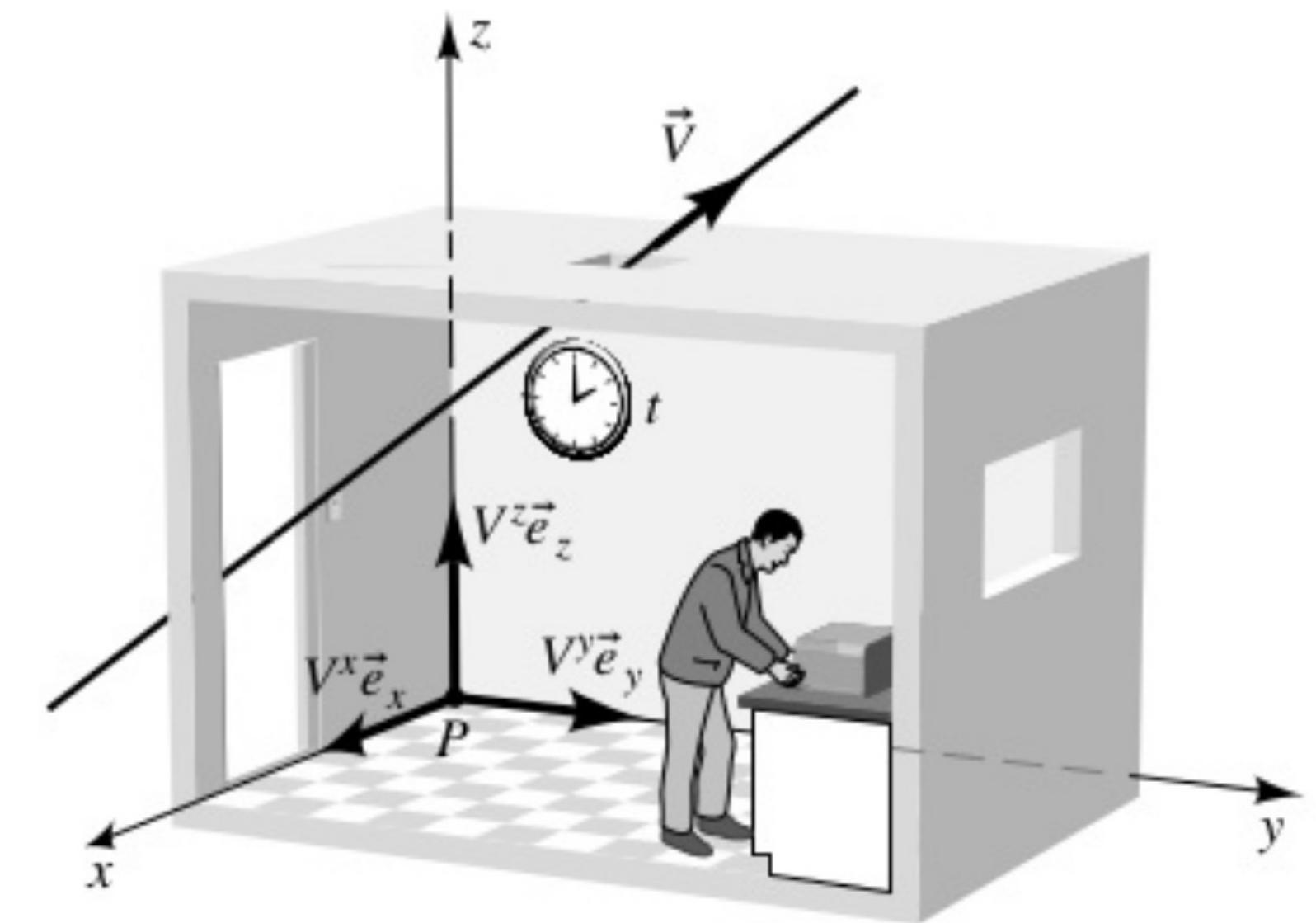
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$$u = \left(1 - \frac{1}{\gamma^2}\right)^{1/2} = \left(1 - (u_\mu V^\mu)^{-2}\right)^{1/2}$$

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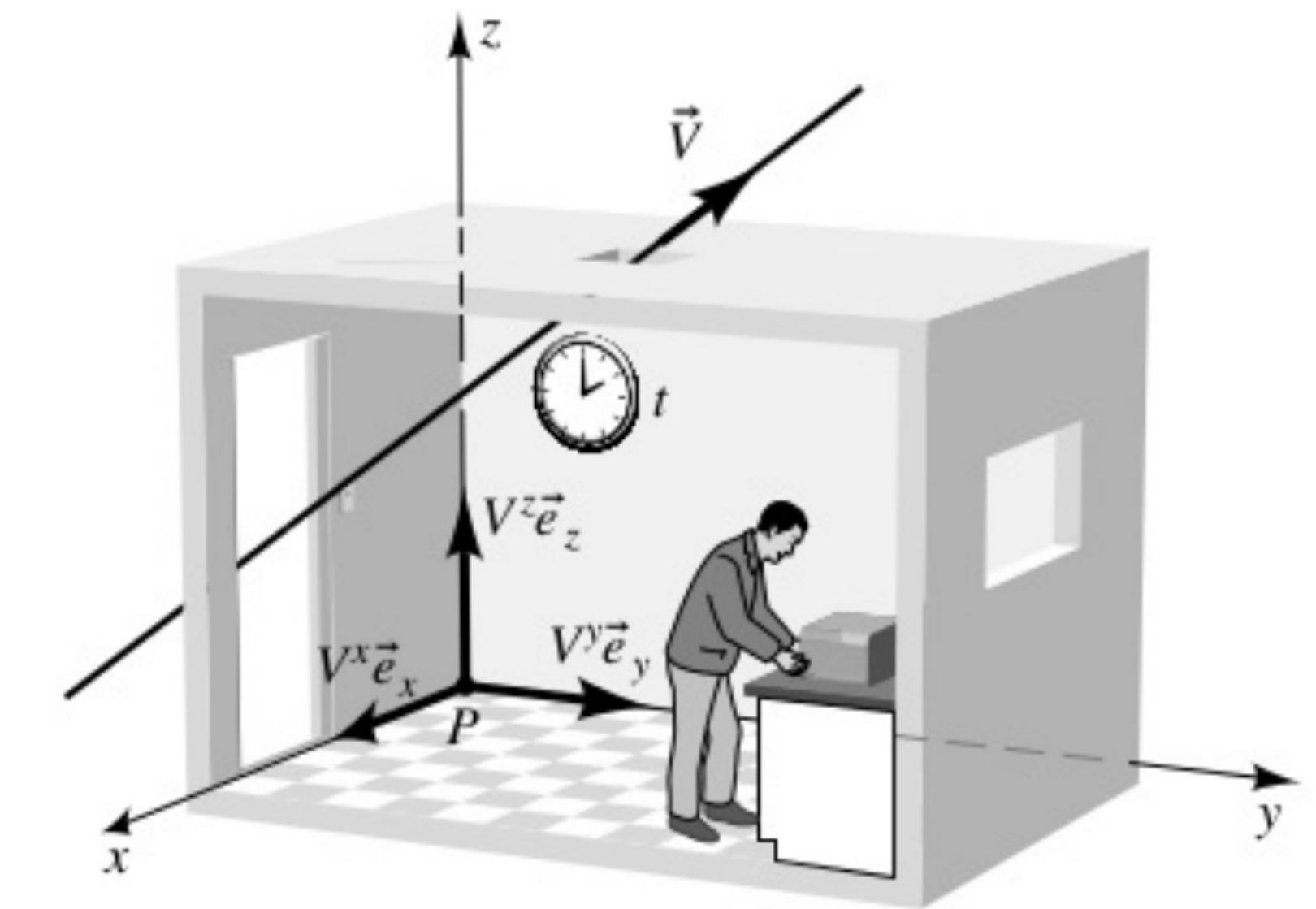
$$u = (1, 0, 0, 0) = e_0$$

Velocity of a passing by particle

$$V = (\gamma, \gamma u, 0, 0) = \gamma e_0 + \gamma u e_1 \Rightarrow$$

$$g_{\mu\nu} u^\mu V^\nu = (-1) \cdot 1 \cdot \gamma + (1) \cdot 0 \cdot \gamma u = -\gamma = -\frac{1}{\sqrt{1-u^2}} \Rightarrow$$

$$u = \left(1 - \frac{1}{\gamma^2}\right)^{1/2} = \left(1 - (u_\mu V^\mu)^{-2}\right)^{1/2}$$



Hartle, Fig 7.6

coordinate independent formula,  
gives relative speed in any coord. system

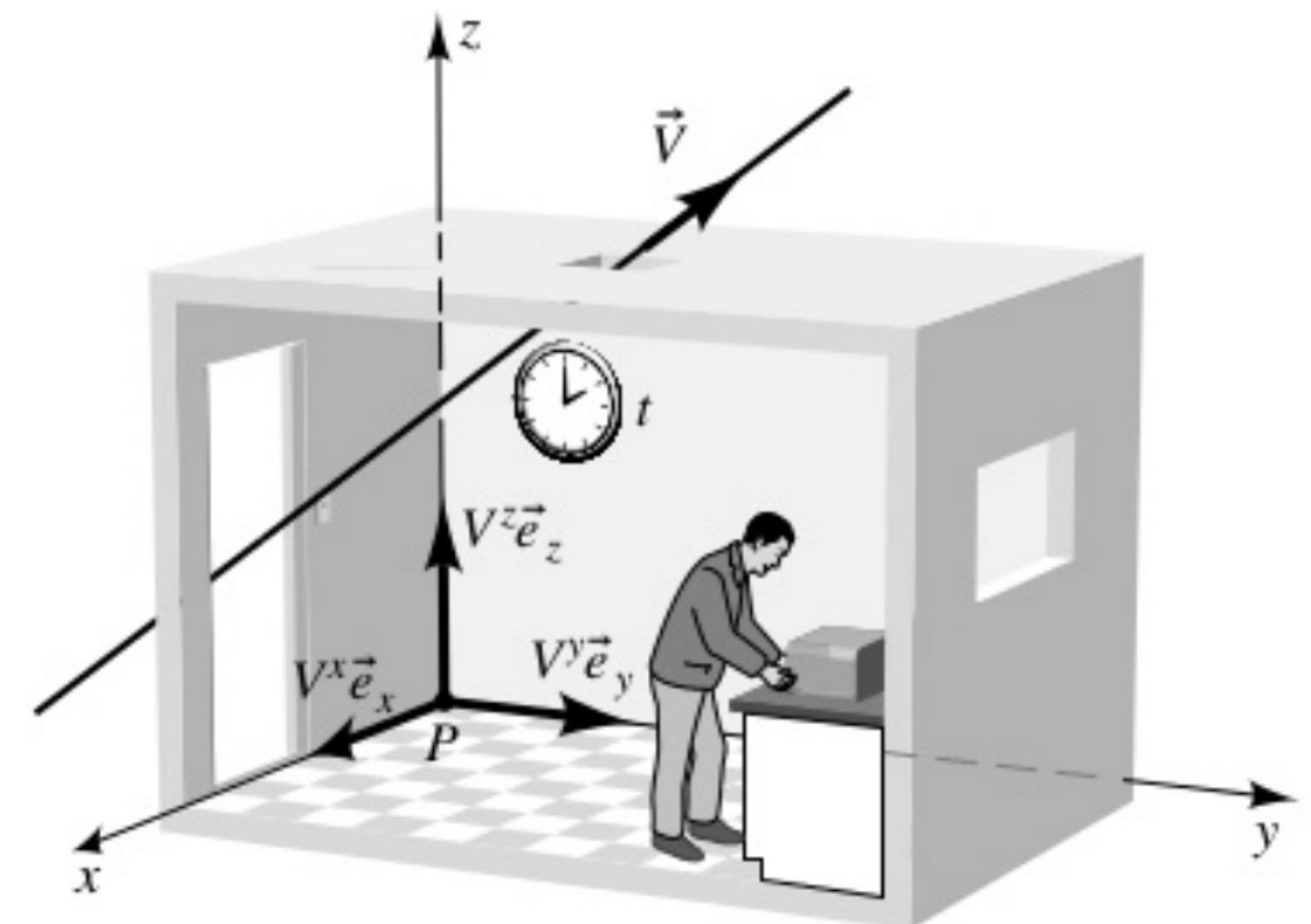
# Local Frames

Orthonormal bases define an "observer"  
four-velocity of observer  $u = e_0$

$$u = (1, 0, 0, 0) = e_0$$

four-momentum of particle:

$$p^{\mu} = (E, p^1, p^2, p^3)$$



Hartle, Fig 7.6

# Local Frames

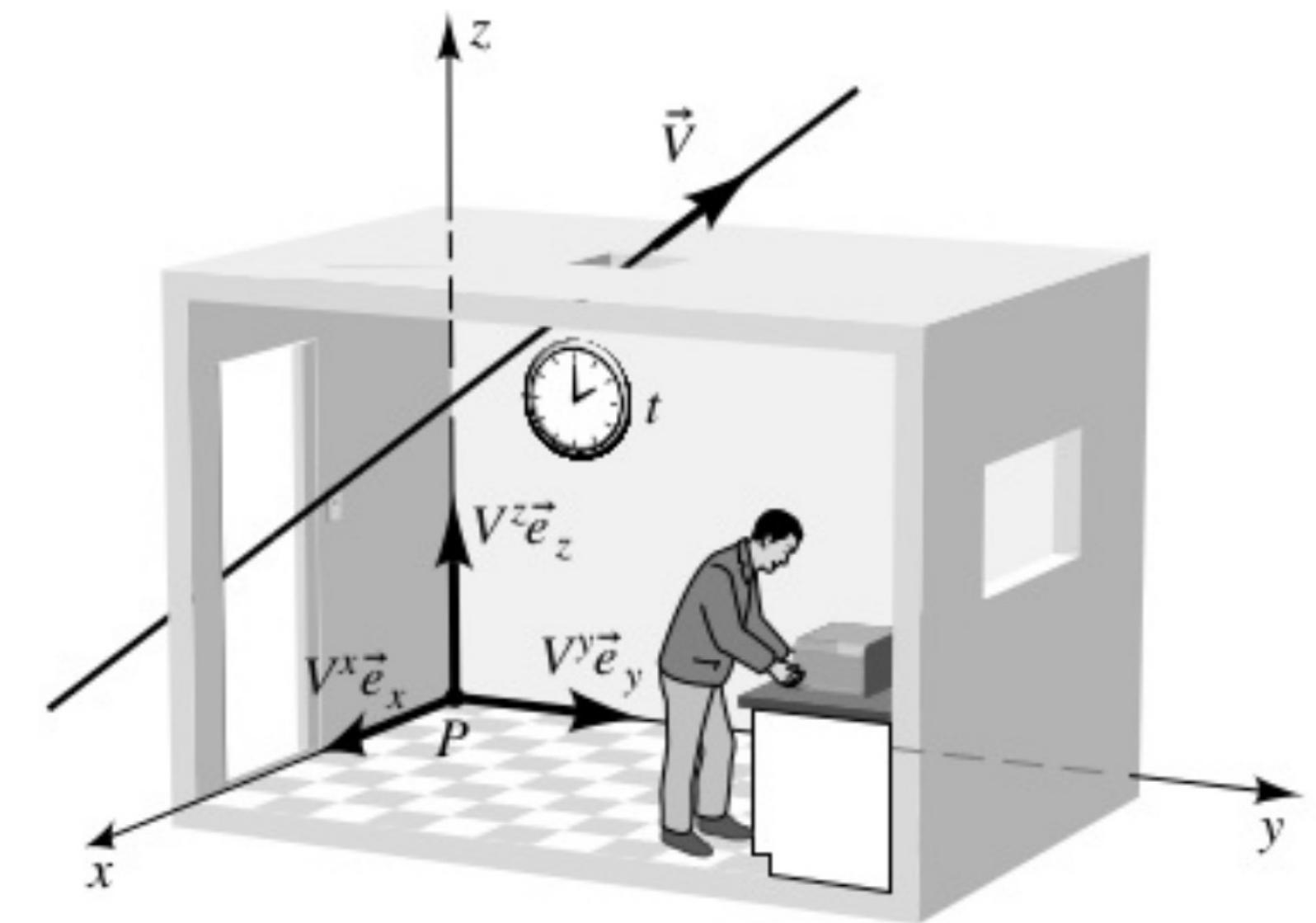
Orthonormal bases define an "observer"

four-velocity of observer  $u = e_0$

$$u = (1, 0, 0, 0) = e_0$$

four-momentum of particle:

$$\left. \begin{array}{l} p^\mu = (E, p^1, p^2, p^3) \\ u^\mu = (1, 0, 0, 0) \end{array} \right\} \Rightarrow p_\mu u^\mu = -E$$

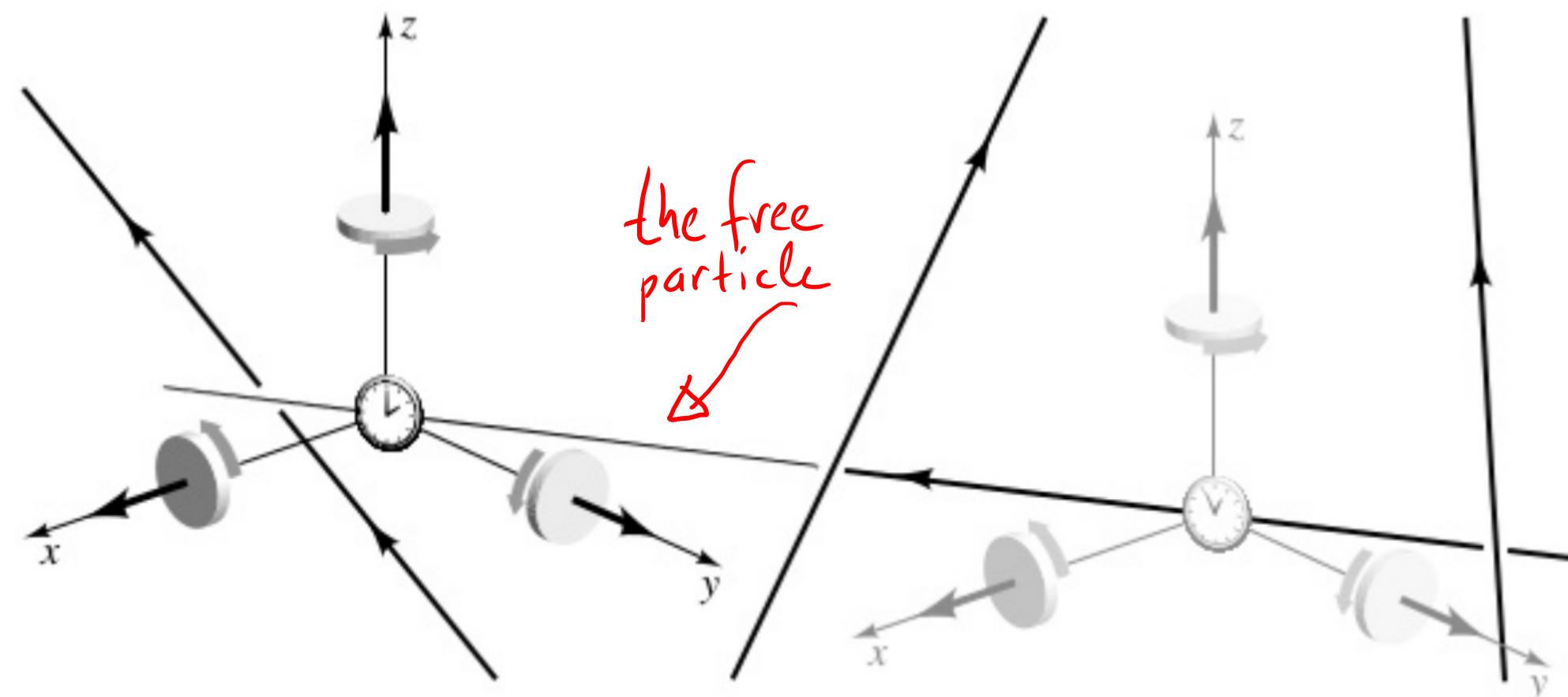


Hartle, Fig 7.6

- a coordinate independent expression
- E and v easily defined for a local observer  
NOT for distant observers !!!

# Local Inertial Observers

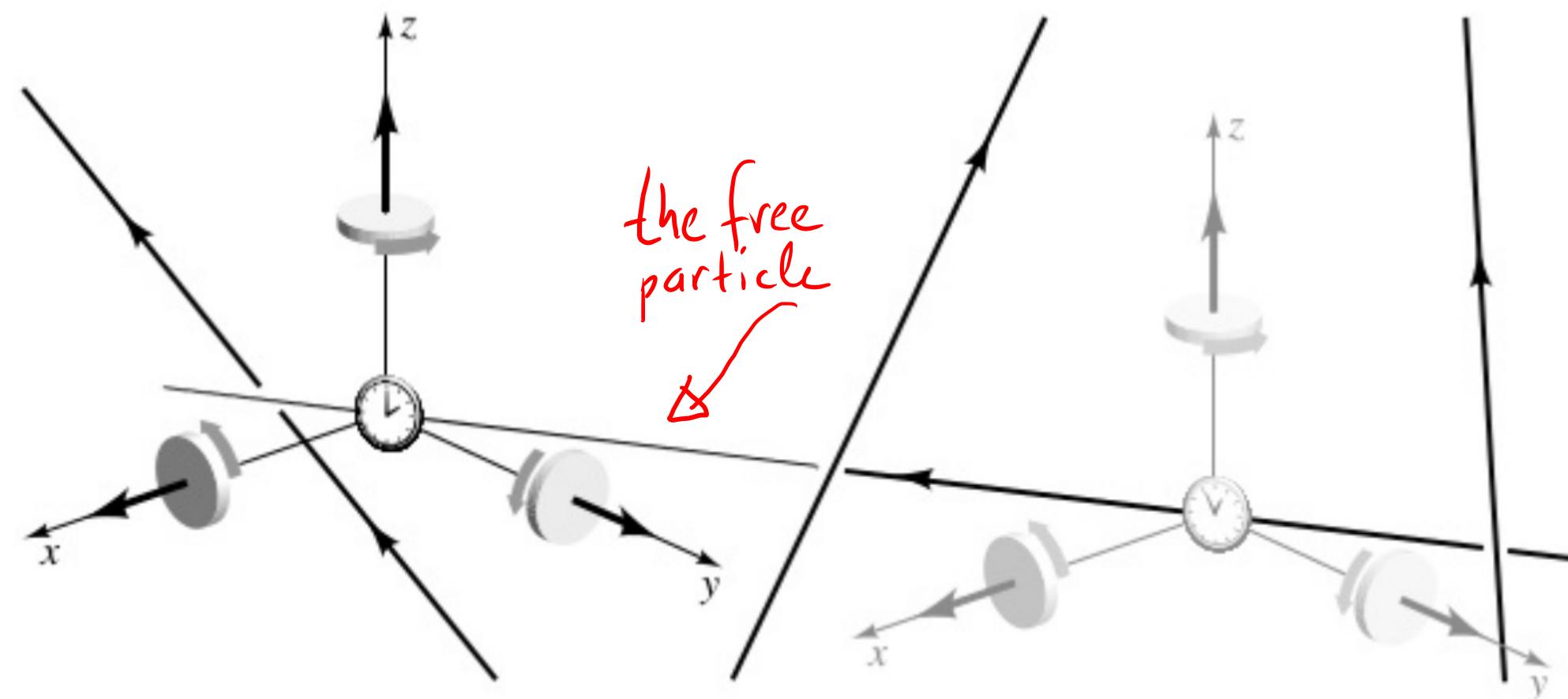
\* Observers that observe free particles to move on straight lines @ constant rate are the inertial observers



Hartle Fig 3.3

# Local Inertial Observers

\* Observers that observe free particles to move on straight lines @ constant rate are the inertial observers  
~ freely "falling"



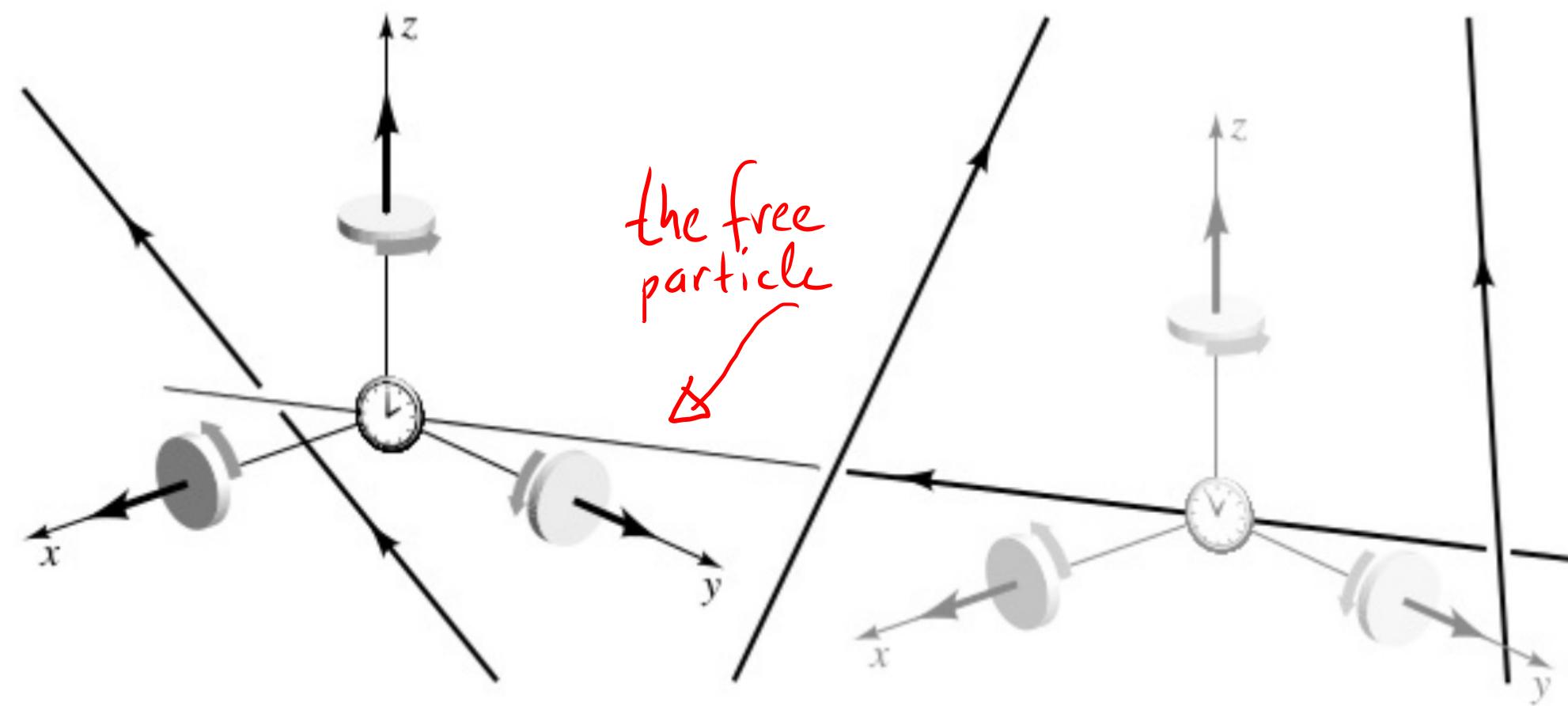
Hartle Fig 3.3

# Local Inertial Observers

\* Observers that observe free particles to move on straight lines @ constant rate are the inertial observers  
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How to become one:

- follow a free massive particle and set origin of axes on it



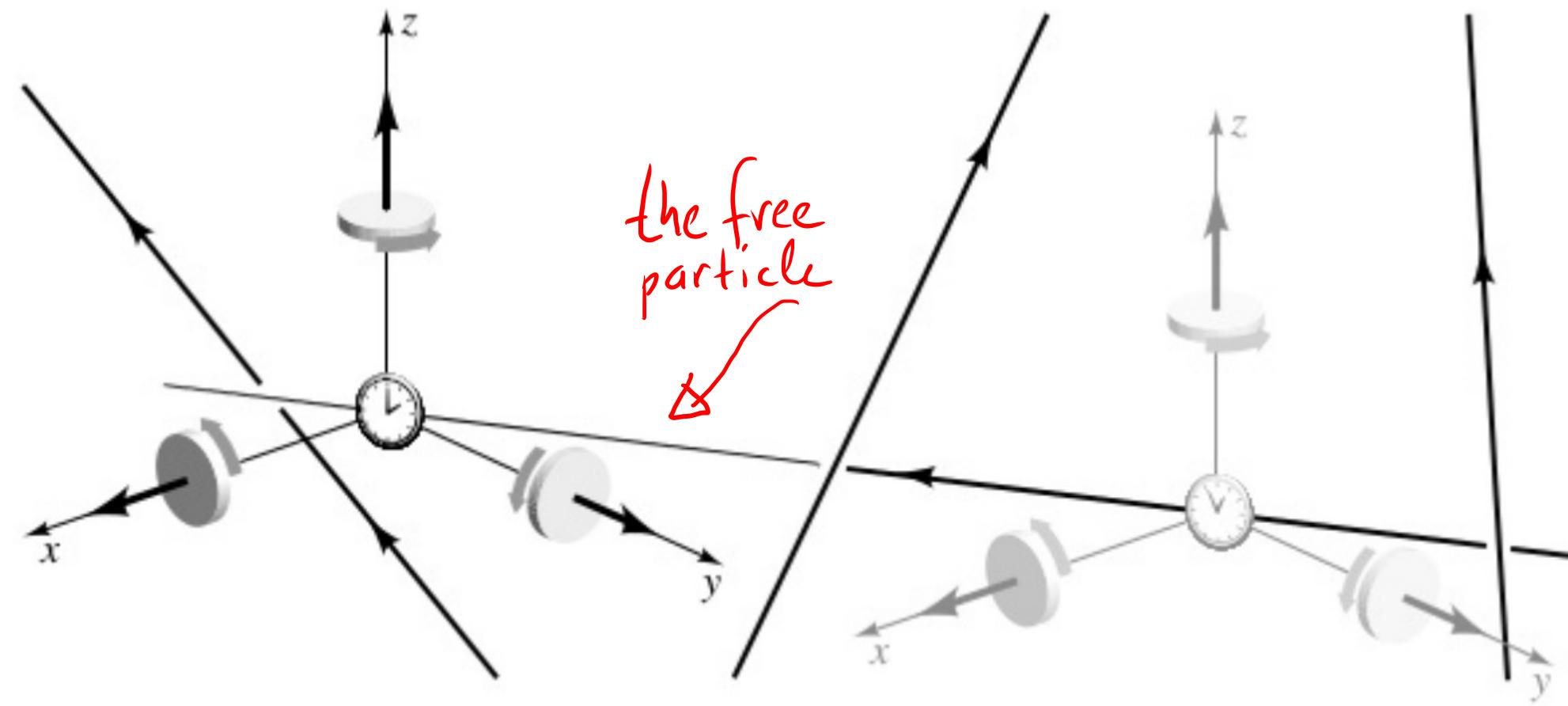
Hartle Fig 3.3

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How to become one:

- follow a free massive particle and set origin of axes on it
- choose 3 perpendicular axes, set gyroscopes to spin in their direction



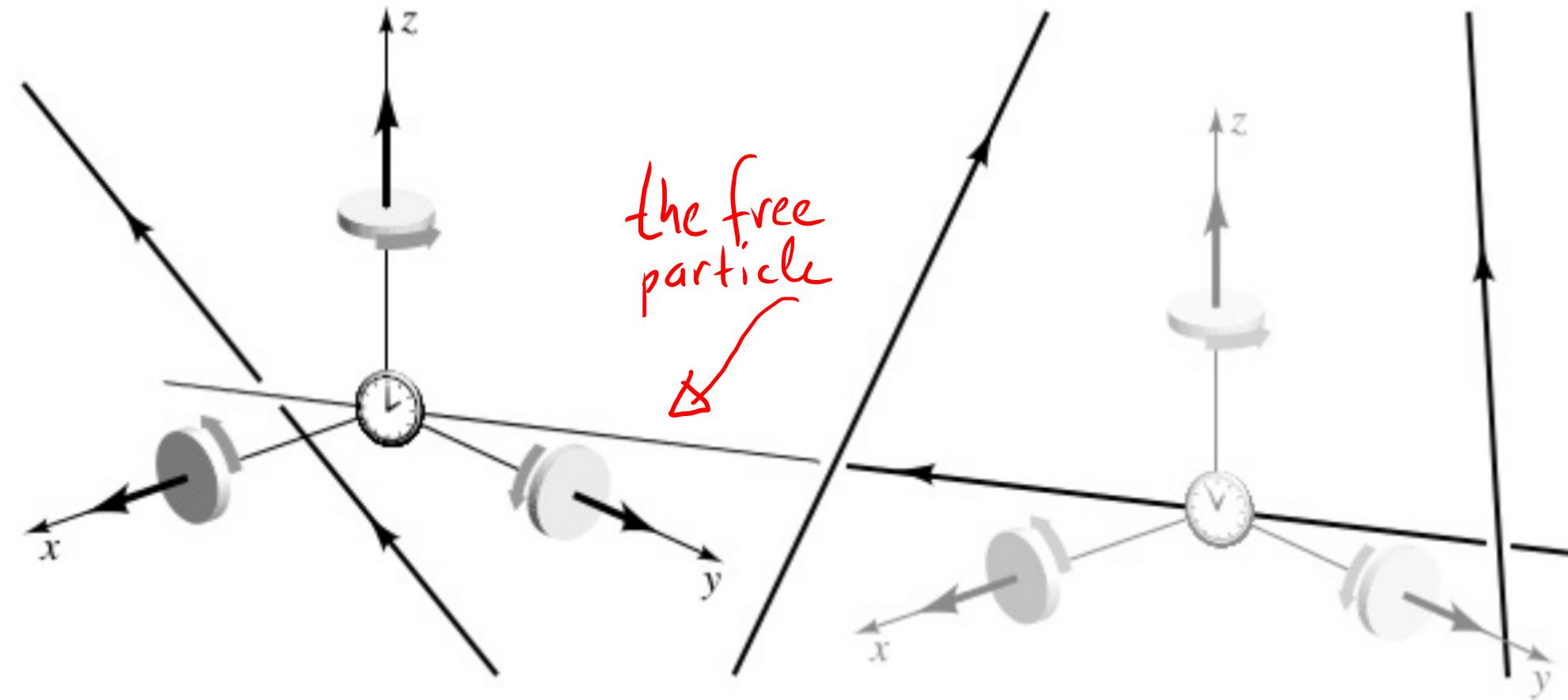
Hartle Fig 3.3

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- choose 3 perpendicular axes, set gyroscopes to spin in their direction
- let gyros spin freely, use them as Cartesian axes  
 $\Rightarrow g_{\mu\nu}|_0 = \gamma_{\mu\nu}$  and  $\partial^\sigma g_{\mu\nu}|_0 = 0$



Hartle Fig 3.3

# Local Inertial Observers

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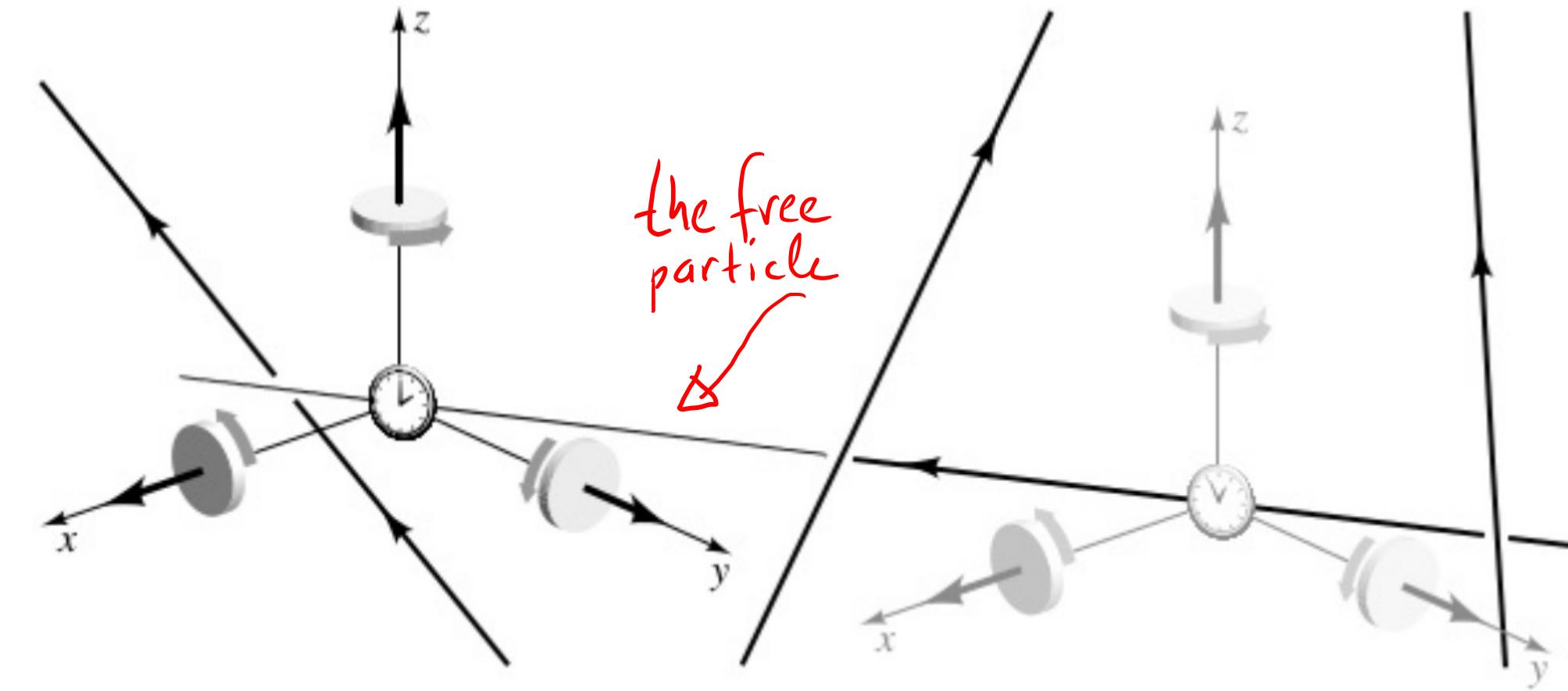
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How to become one:

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- choose 3 perpendicular axes, set gyroscopes to spin in their direction
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$$\Rightarrow g_{\mu\nu}|_0 = \gamma_{\mu\nu} \quad \text{and} \quad \partial_\sigma g_{\mu\nu}|_0 = 0$$

Voilà: in a small enough region you can do SR physics!

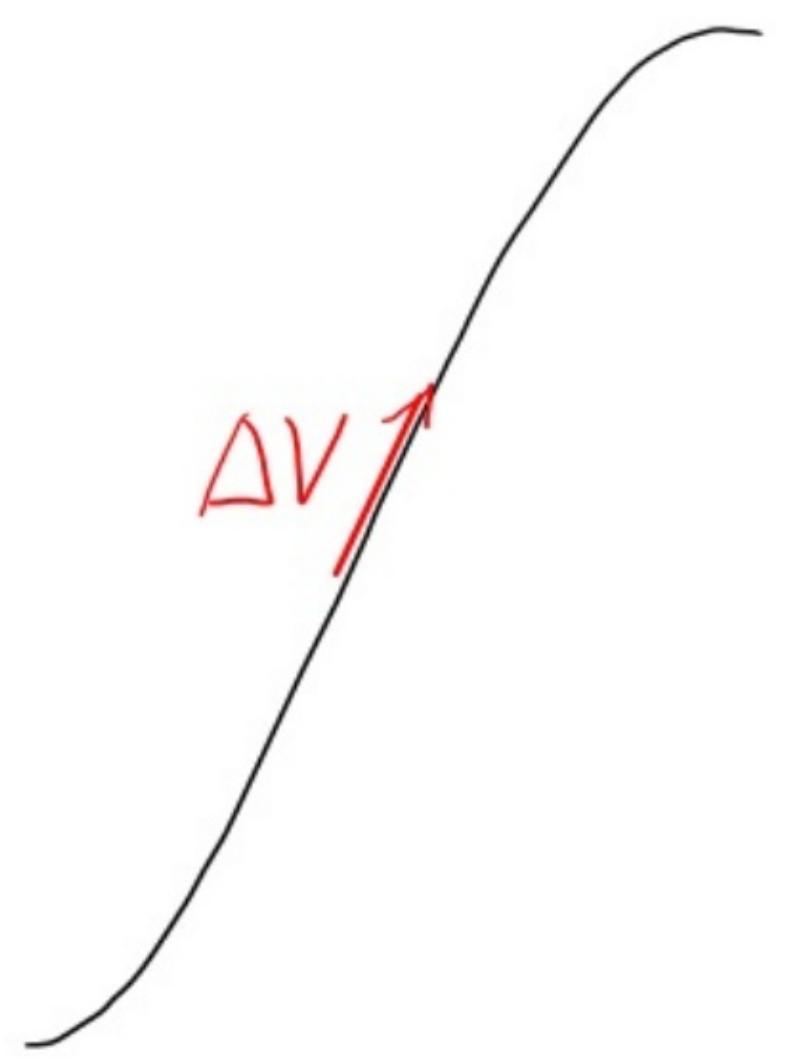


Hartle Fig 3.3

## Line element

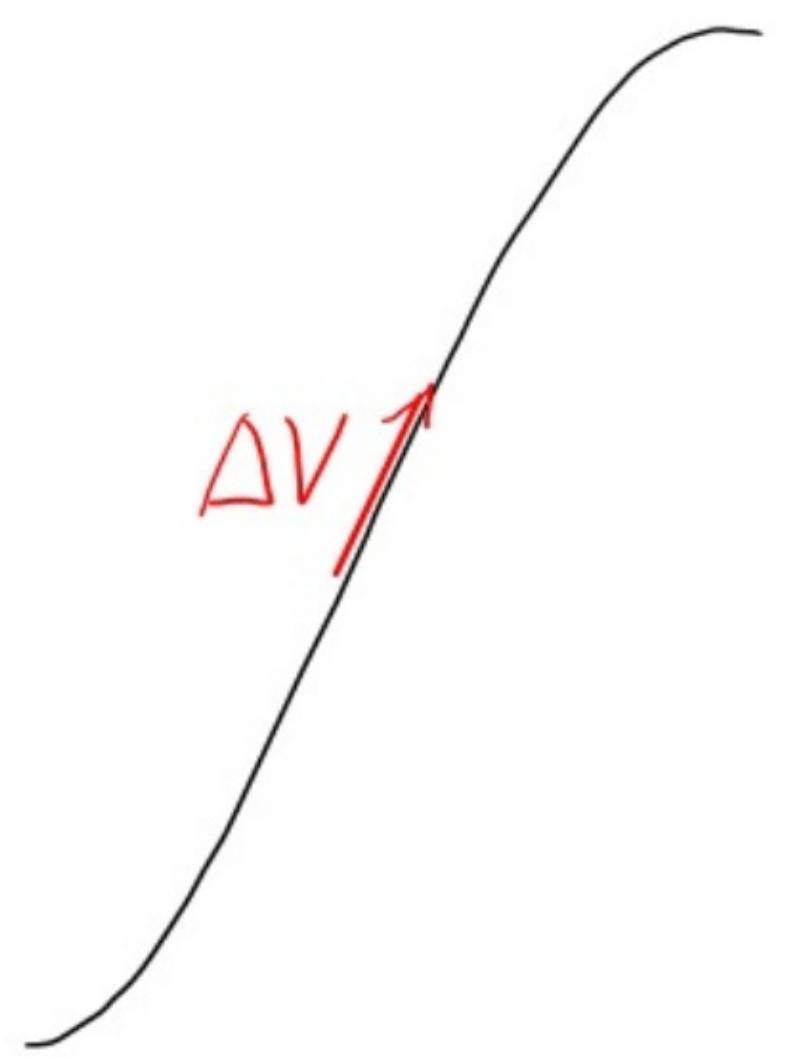
$$g = g_{\mu\nu} dx^\mu \otimes dx^\nu$$

$$\Delta V = \Delta x^\mu \partial_\mu$$



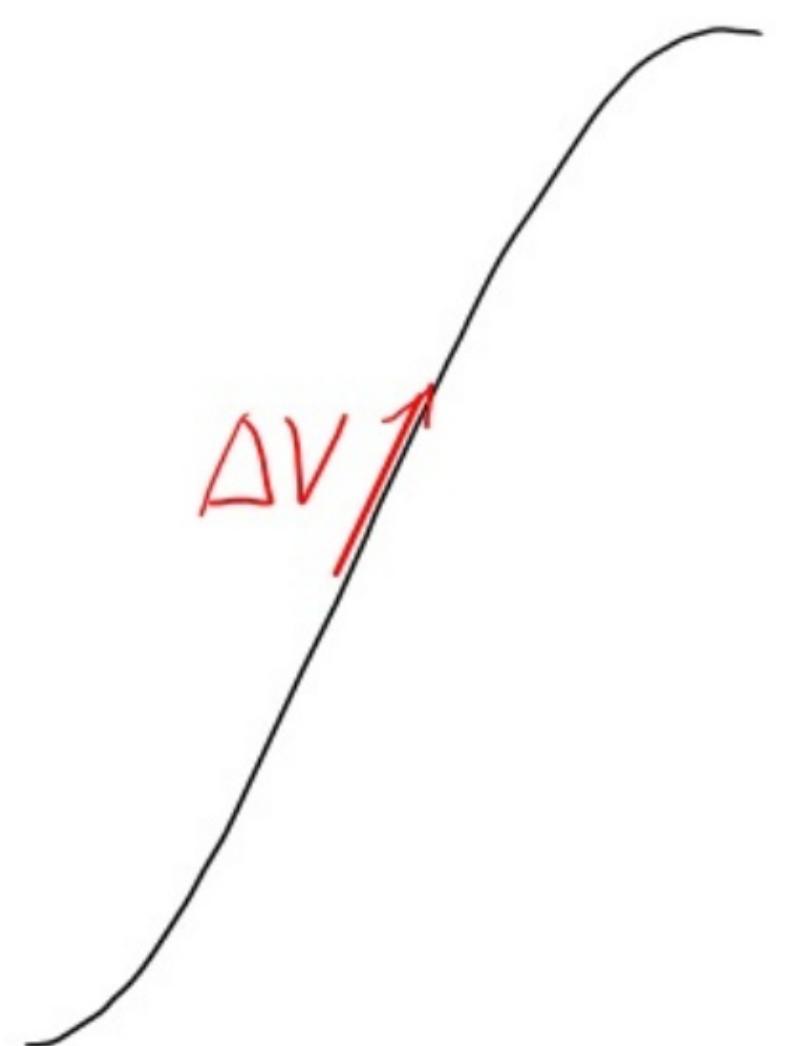
## Line element

$$\left. \begin{aligned} g &= g_{\mu\nu} dx^\mu \otimes dx^\nu \\ \Delta V &= \Delta x^\mu \partial_\mu \end{aligned} \right\} \Rightarrow \begin{aligned} g(\Delta V, \Delta V) &= g(\Delta x^\mu \partial_\mu, \Delta x^\nu \partial_\nu) \\ &= g(\partial_\mu, \partial_\nu) \Delta x^\mu \Delta x^\nu \\ &= g_{\mu\nu} \Delta x^\mu \Delta x^\nu \end{aligned}$$



## Line element

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We write  $ds^2 = g_{\mu\nu} dx^\mu dx^\nu$

↳ In bibliography this could mean  $g \equiv ds^2$ ,  $dx^\mu dx^\nu = dx^\mu \otimes dx^\nu \neq dx^\nu dx^\mu$

## Line element

$$\left. \begin{aligned} g &= g_{\mu\nu} dx^\mu \otimes dx^\nu \\ \Delta V &= \Delta x^\mu \partial_\mu \end{aligned} \right\} \Rightarrow g(\Delta V, \Delta V) = g(\Delta x^\mu \partial_\mu, \Delta x^\nu \partial_\nu) = g(\partial_\mu, \partial_\nu) \Delta x^\mu \Delta x^\nu = g_{\mu\nu} \Delta x^\mu \Delta x^\nu$$

$\Delta V$

We write  $ds^2 = g_{\mu\nu} dx^\mu dx^\nu$ , and we use it as infinitesimal line element

$$S_{AB} = \int_A^B ds = \int_A^B \{ |g_{\mu\nu} dx^\mu dx^\nu| \}^{1/2} dt = \int_{t_A}^{t_B} dt \{ |g_{\mu\nu} \frac{dx^\mu}{dt} \frac{dx^\nu}{dt}| \}^{1/2}$$

We focus on 3 types of curves:

$ds^2 < 0$  everywhere  $\rightarrow$  timelike curves

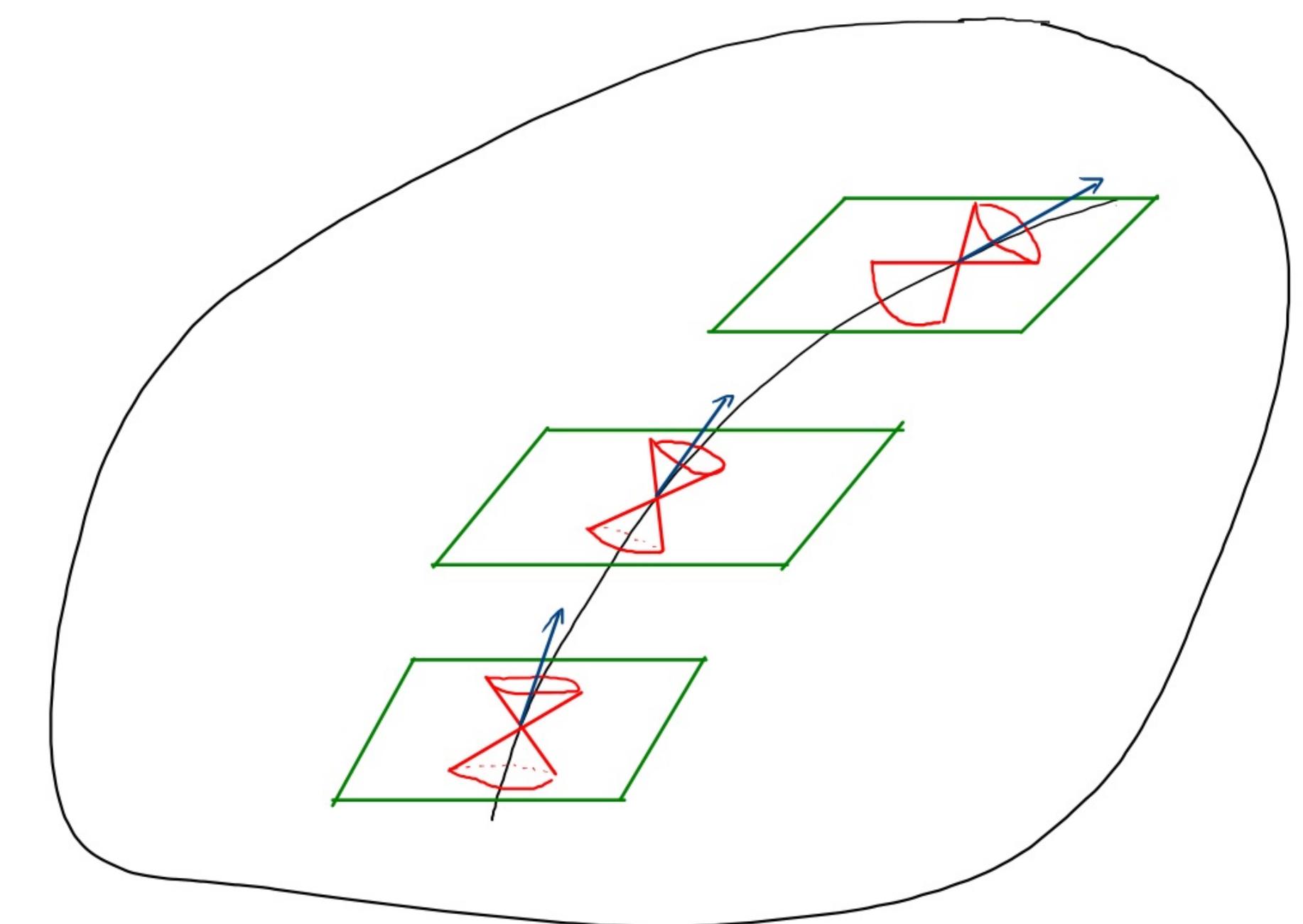
$ds^2 = 0$  "  $\rightarrow$  null/lightlike "

$ds^2 > 0$  "  $\rightarrow$  space like "

$\Rightarrow$  tangent vector  $V$  is of the same type at each point ( $g(V, V)$  does not change sign)

tangent vectors are the 4-velocities of particles ( $ds^2 \leq 0$ )

$$V^\mu = \frac{dx^\mu}{dt}$$

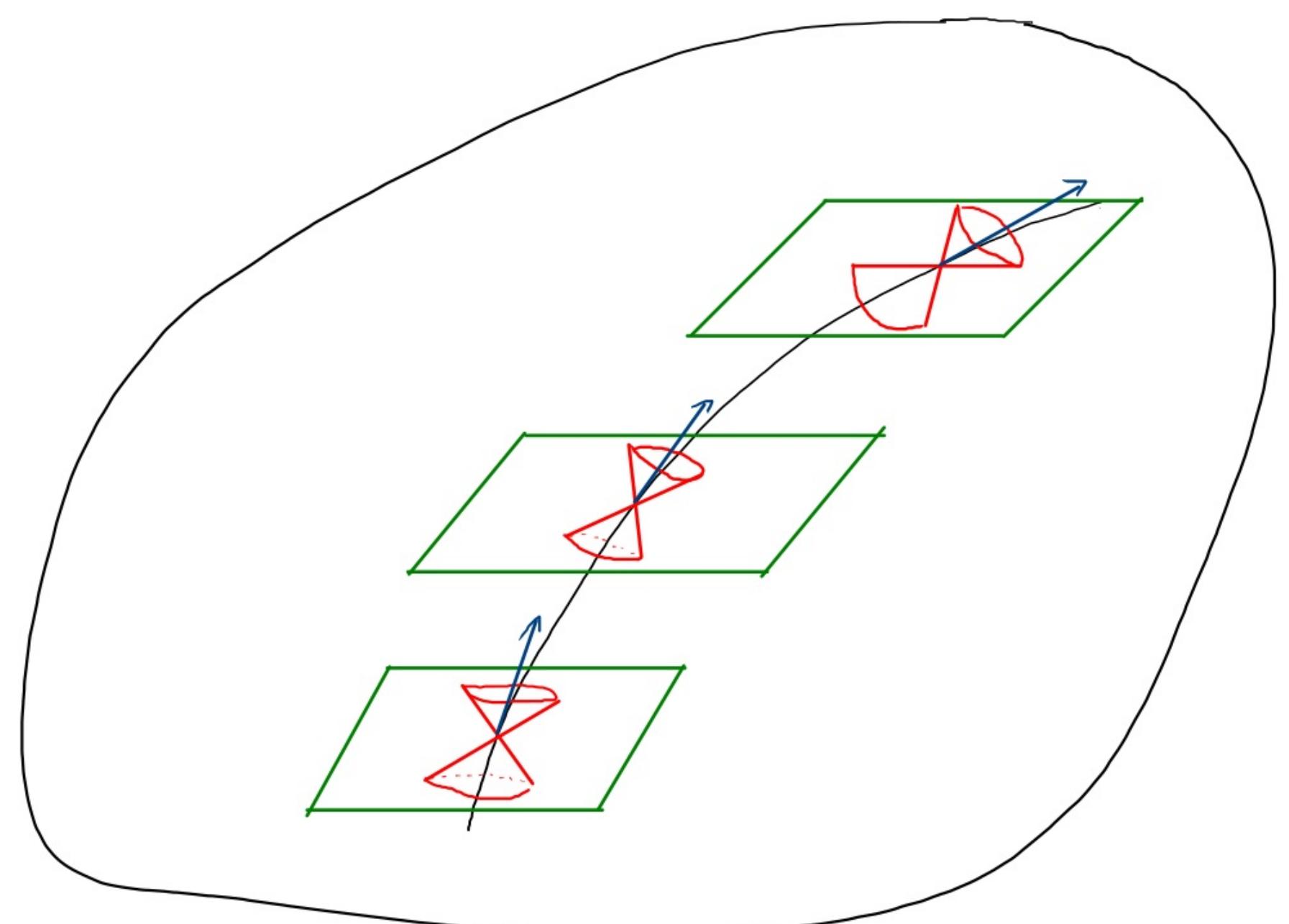


We focus on 3 types of curves:

$ds^2 < 0$  everywhere  $\rightarrow$  timelike curves

$ds^2 = 0$  "  $\rightarrow$  null/lightlike "

$ds^2 > 0$  "  $\rightarrow$  space like "



\* Timelike curves are worldlines of observers and massive particles

\* Null curves are worldlines of massless particles

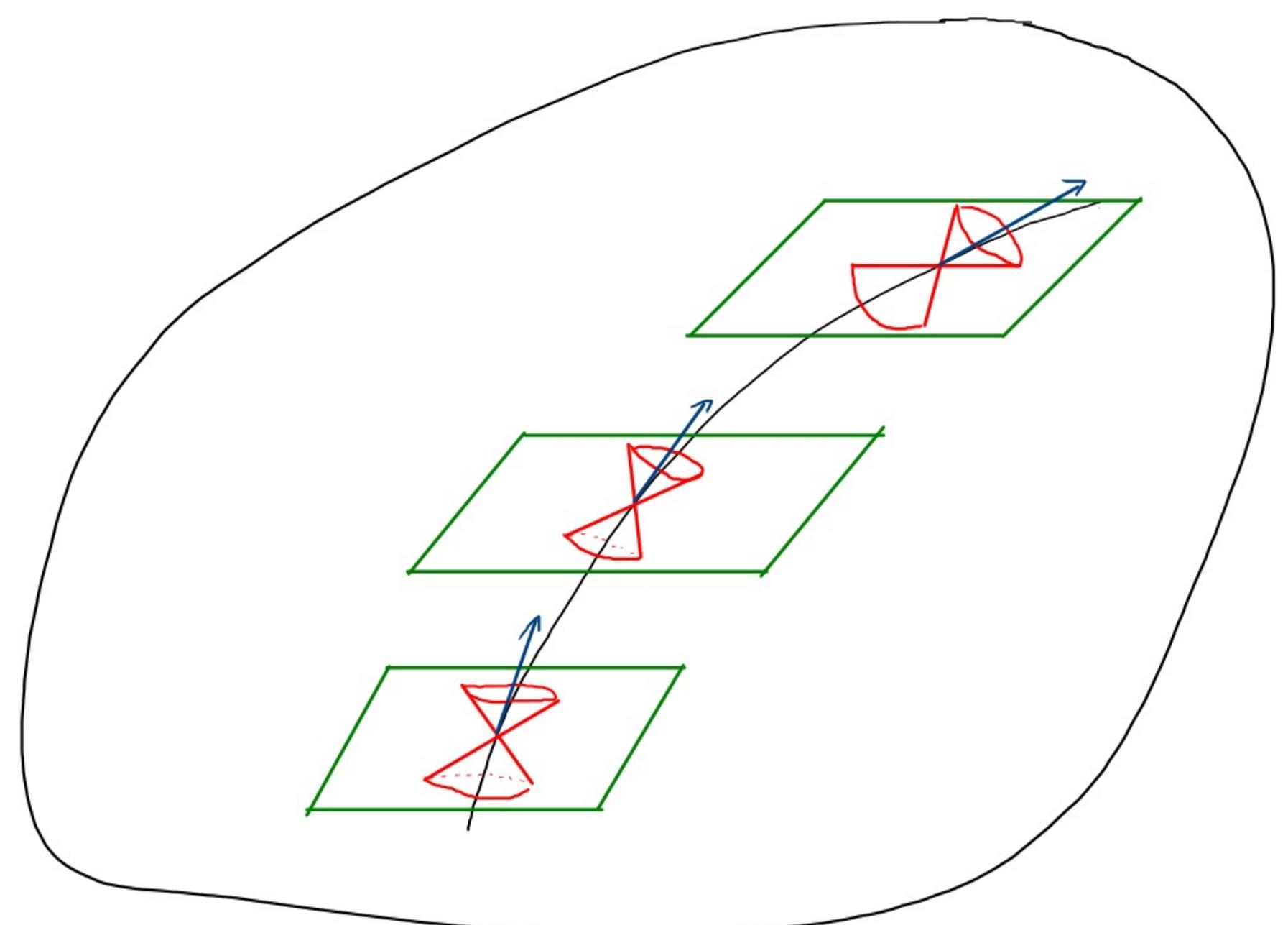
\* Causal curves: any event on curve can influence/be influenced by any other event on curve (timelike or null)

We focus on 3 types of curves:

$ds^2 < 0$  everywhere  $\rightarrow$  timelike curves

$ds^2 = 0$  "  $\rightarrow$  null/lightlike "

$ds^2 > 0$  "  $\rightarrow$  space like "



\* Light always travels in a direction  
on the local light cone

Not "exceeding speed of light" a **local** concept; particles  
always move in a direction within or on the local light cone  
 $\leadsto$  distances between faraway particles can increase at a rate  $> 1$ !