# Signature change of the emergent space-time in the IKKT matrix model 

Jun Nishimura (KEK, SOKENDAI)<br>Talk at Corfu2021<br>Workshop on Quantum Geometry, Field Theory and Gravity<br>September 20-27, 2021

Ref.) J.N. and Asato Tsuchiya, JHEP 1906 (2019) 077 [arXiv:1904.05919 [hep-th]]
Anagnostopoulos-Azuma-Hatakeyama-Hirasawa-Ito-J.N.-Tsuchiya-Papadoudis, work in progress

## IKKT matrix model

a conjectured nonperturbative formulation of superstring theory

$$
\begin{aligned}
S_{\mathrm{b}} & =-\frac{1}{4 g^{2}} \operatorname{tr}\left(\left[A_{\mu}, A_{\nu}\right]\left[A^{\mu}, A^{\nu}\right]\right) \\
S_{\mathrm{f}} & =-\frac{1}{2 g^{2}} \operatorname{tr}\left(\Psi_{\alpha}\left(\mathcal{C} \Gamma^{\mu}\right)_{\alpha \beta}\left[A_{\mu}, \Psi_{\beta}\right]\right)
\end{aligned}
$$

## $\mathrm{SO}(9,1)$ symmetry

$N \times N$ Hermitian matrices

$$
\begin{gathered}
A_{\mu} \quad(\mu=0, \cdots, 9) \quad \text { Lorentz vector } \\
\Psi_{\alpha} \quad(\alpha=1, \cdots, 16) \quad \text { Majorana-Weyl spinor } \\
\begin{array}{l}
\text { Lorentzian metric } \eta=\operatorname{diag}(-1,1, \cdots, 1) \\
\text { is used to raise and lower indices. }
\end{array}
\end{gathered}
$$

Wick rotation $\left(A_{0}=-i A_{10}, \quad \Gamma^{0}=i \Gamma_{10}\right)$ Euclidean matrix model $\mathrm{SO}(10)$ symmetry

Anagnostopoulos, et al. JHEP 06 (2020) 069 , arXiv: 2002.07410 [hep-th]

## Crucial properties of the IKKT matrix model as a nonperturbative formulation of superstring theory

- The connection to perturbative formulations can be seen manifestly by considering type IIB superstring theory in 10d.
worldsheet action, light-cone string field Hamiltonian, etc.
- It is expected to be a nonperturbative formulation of the unique theory underlying the web of string dualities.
- The model has $10 D \mathcal{N}=2$ SUSY, which cannot be
 realized in quantum field theories without gravity.
The low energy effective theory should inevitably include quantum gravity !
In the SUSY algebra, translation is realized as $A_{\mu} \mapsto A_{\mu}+\alpha_{\mu} \mathbf{1}$,
which suggests that the space-time is represented as the eigenvalue distribution of $A_{\mu}$.
Geometry emerges from matrix degrees of freedom dynamically in this approach .


## Plan of the talk

0. Introduction
1. Brief review of the Euclidean IKKT model
2. How to define the Lorentzian IKKT model
3. How to investigate the model
4. Results of the CL simulations
5. Summary and discussions

## 1. Brief review of the Euclidean IKKT model

## the Euclidean IKKT model

"Wick rotation" : $\quad A_{0}=-i A_{10}$

$$
\begin{gathered}
S_{\mathrm{b}} \propto \operatorname{tr}\left(F_{\mu \nu}\right)^{2} \quad \text { positive semi-definite! } \\
F_{\mu \nu}=-i\left[A_{\mu}, A_{\nu}\right]
\end{gathered}
$$

The flat direction : $\left[A_{\mu}, A_{\nu}\right] \sim 0$
Lifted in the bosonic case due to quantum effects.
Bhanot-Heller-Neuberger '82
It survives in the SUSY case if one neglects the fermionic zero modes.
In the original IKKT paper: $\quad \mid$ eigenvalues of $A_{\mu} \mid<\Lambda$
In fact, fermionic zero modes lift the flat directions.
Aoki-Iso-Kawai-Kitazawa-Tada '99
Euclidean model is well defined without any cutoff.
Krauth-Nicolai-Staudacher ('98),
Austing-Wheater ('01)

## Results for the Euclidean IKKT model $\mathrm{SO}(10) \xrightarrow{\text { SSB }} \mathrm{SO}(3)$

SSB of $\mathrm{SO}(10)$ observed by decreasing the deformation parameter $m_{\mathrm{f}}$. ten eigenvalues of $T_{\mu \nu}=\frac{1}{N} \operatorname{tr}\left(A_{\mu} A_{\nu}\right)$

2. How to define the Lorentzian IKKT model

## Partition function of the Lorentzian IKKT model

## partition function

$Z=\int d A d \Psi e^{i\left(S_{\mathrm{b}}+S_{\mathrm{f}}\right)}=\int d A e^{i S_{\mathrm{b}} \operatorname{Pf} \mathcal{M}(A)}$
This seems to be natural from the
connection to the worldsheet theory.
c.f.) $\quad S=\int d^{2} \xi \sqrt{g}\left(\frac{1}{4}\left\{X^{\mu}, X^{\nu}\right\}^{2}+\frac{1}{2} \bar{\Psi} \gamma^{\mu}\left\{X^{\mu}, \Psi\right\}\right)$

$$
\xi_{0} \equiv-i \xi_{2}
$$

(The worldsheet coordinates should also be Wick-rotated.)

## Regularizing the Lorentzian model

- Unlike the Euclidean model, the Lorentzian model is NOT well defined as it is.

$$
Z=\int d A d \Psi e^{i\left(S_{\mathrm{b}}+S_{\mathrm{f}}\right)}=\int_{\text {pure phase factor }} d A \underbrace{e^{i S_{\mathrm{b}}} \mathrm{Pf} \mathcal{M}(A)}_{\text {polynomial in } A}
$$

- Wick rotation
(Yuhma Asano '19, private communication)

$$
S_{\mathrm{b}} \mapsto \tilde{S}_{\mathrm{b}}=N e_{\text {on the worldsheet }}^{e^{i \frac{\pi}{2} s}}\left\{\frac{1}{2} e^{-i \pi k} \operatorname{tr}\left[\tilde{A}_{0}, \tilde{A}_{i}\right]^{2}-\frac{1}{4} \operatorname{tr}\left[\tilde{A}_{i}, \tilde{A}_{j}\right]^{2}\right\}
$$

This corresponds to deforming the integration contour in the Lorentzian model.

$$
\left\{\begin{array}{rlrl}
A_{0}=\mathrm{e}^{i \frac{\pi}{8} s s i \frac{\pi}{2} k} \tilde{A}_{0} & =\mathrm{e}^{-i \frac{3 \pi}{8} u} \tilde{A}_{0} & u=0: \text { Lorentzian } \\
A_{i}=\mathrm{e}^{i \frac{\pi}{8} s} \widetilde{A}_{i} & =\mathrm{e}^{i \frac{\pi}{8} u} \tilde{A}_{i} & u=1 \text { : Euclidean } \\
s=k(=u) & &
\end{array}\right.
$$

## Path deformed theory is well-defined for $0<u \leq 1$

(Yuhma Asano '19, private communication)

$$
\begin{gathered}
e^{i S_{\mathrm{b}}(A)}=e^{-S(\widetilde{A})} \quad\left\{\begin{array}{l}
A_{0}=\mathrm{e}^{-i \frac{3}{8} \pi u} \tilde{A}_{0} \\
A_{i}=\mathrm{e}^{i \frac{1}{8} \pi u} \tilde{A}_{i}
\end{array} \quad \tilde{F}_{\mu \nu}=-i\left[\tilde{A}_{\mu}, \widetilde{A}_{\nu}\right]\right. \\
S(\widetilde{A}) \sim 2 e^{i \frac{\pi}{2}(1-u)} \operatorname{tr}\left(\tilde{F}_{0 i}\right)^{2}+\underbrace{-i \frac{\pi}{2}(1-u}_{\text {positive real part for } 0<u \leq 1} \operatorname{tr}\left(\tilde{F}_{i j}\right)^{2} \\
\operatorname{Re} S(\widetilde{A}) \geq 0
\end{gathered}
$$

$S(\tilde{A})$ : real positive at $u=1$ (Euclidean).
According to Cauchy's theorem, $\left\langle\mathcal{O}\left(\mathrm{e}^{-i \frac{3}{8} \pi u} \tilde{A}_{0}, \mathrm{e}^{i \frac{1}{8} \pi u} \widetilde{A}_{i}\right)\right\rangle_{u}$ is independent of $u$.

If we define the Lorentzian model by taking the $u \rightarrow+0$ limit,

$$
\left\langle\mathcal{O}\left(A_{0}, A_{i}\right)\right\rangle_{\mathrm{L}}=\left\langle\mathcal{O}\left(\mathrm{e}^{-i \frac{3 \pi}{8}} \tilde{A}_{0}, \mathrm{e}^{i \frac{\pi}{8}} \tilde{A}_{i}\right)\right\rangle_{\mathrm{E}}
$$

## Confirmation of the equivalence by CL simulation

10D bosonic model


The emergent space-time should be interpreted as being Euclidean !
3. How to investigate the model

## Complex Langevin equation

J.N. and Asato Tsuchiya, JHEP 1906 (2019) 077
[arXiv:1904.05919 [hep-th]]
The effective action

$$
\begin{aligned}
S_{\mathrm{eff}}= & -i N\left\{\frac{1}{2} \operatorname{tr}\left[A_{0}, A_{i}\right]^{2}-\frac{1}{4} \operatorname{tr}\left[A_{i}, A_{j}\right]^{2}\right\} \\
& -\log \Delta(\alpha)-\sum_{a=1}^{N-1} \tau_{a}
\end{aligned}
$$

Complex Langevin equation

$$
\left\{\begin{aligned}
\frac{d \tau_{a}}{d t} & =-\frac{\partial S_{\mathrm{eff}}}{\partial \tau_{a}}+\eta_{a} \\
\frac{d\left(\mathcal{A}_{i}\right)_{a b}}{d t} & =-\frac{\partial S_{\mathrm{eff}}}{\partial\left(\mathcal{A}_{i}\right)_{b a}}+\left(\eta_{i}\right)_{a b}
\end{aligned}\right.
$$

$\tau_{a}$ : complex variables, $\quad \mathcal{A}_{i}$ : general complex matrices.
In this work, we omit the fermionic matrices to reduce computation time

# Defining "time" in the IKKT model in complex Langevin simulation 

J.N. and Asato Tsuchiya, JHEP 1906 (2019) 077 [arXiv:1904.05919 [hep-th]]

Fixing the $U(N)$ symmetry: $A_{\mu} \mapsto U A_{\mu} U^{\dagger}$

$$
\begin{gathered}
Z=\int d A_{0} d A_{i} e^{-S}=\int d \alpha d A_{i} \Delta(\alpha) e^{-S} \\
A_{0}=\operatorname{diag}\left(\alpha_{1}, \cdots, \alpha_{N}\right) \\
\alpha_{1}<\alpha_{2}<\cdots<\alpha_{N} \\
\Delta(\alpha)=\prod_{a>b}\left(\alpha_{a}-\alpha_{b}\right)^{2}: \text { van der Monde determinant }
\end{gathered}
$$

We make the change of variables

$$
\alpha_{1}=0, \quad \alpha_{2}=e^{\tau_{1}}, \quad \alpha_{3}=e^{\tau_{1}}+e^{\tau_{2}}, \quad \cdots, \quad \alpha_{N}=\sum_{a=1}^{N-1} e^{\tau_{a}}
$$

to introduce the "time ordering" respecting holomorphicity.

## The expectation value of the time coordinates

$$
\begin{gathered}
\left\langle\mathcal{O}\left(A_{0}, A_{i}\right)\right\rangle_{\mathrm{L}}=\left\langle\mathcal { O } \left(\mathrm{e}^{\left.\left.-i \frac{3 \pi}{8} \tilde{A}_{0}, e^{i \frac{\pi}{8}} \tilde{A}_{i}\right)\right\rangle_{\mathrm{E}}}\right.\right. \\
\left\langle\alpha_{i}\right\rangle_{\mathrm{L}}=e^{-i \frac{3 \pi}{8}}\left(\left\langle\tilde{\alpha}_{i}\right\rangle_{\mathrm{E}}\right) \in \mathbb{R}
\end{gathered}
$$

We introduce a constraint : $\alpha_{N}-\alpha_{1}=\sqrt{\kappa} \in \mathbb{C}$
One cannot deform the contour as we did above.
The model is not equivalent to the Euclidean model any more.
 How about space?

## Extracting time-evolution from the Lorentzian model

 Kim-J.N.-Tsuchiya PRL 108 (2012) 011601 [arXiv:1108.1540]

The extent of space $\quad R^{2}(t)=\left\langle\frac{1}{n} \operatorname{tr}\left(\bar{A}_{i}(t)\right)^{2}\right\rangle$

$$
\begin{gathered}
\left\langle\mathcal{O}\left(A_{0}, A_{i}\right)\right\rangle_{\mathrm{L}}= \\
\left\langle\mathcal{O}\left(\mathrm{e}^{-i \frac{3 \pi}{8}} \tilde{A}_{0}, e^{i \frac{\pi}{8}} \tilde{A}_{i}\right)\right\rangle_{\mathrm{E}} \\
\left\langle\frac{1}{N} \operatorname{tr}\left(A_{i}\right)^{2}\right\rangle_{\mathrm{L}}=e^{i \frac{\pi}{4}}\left\langle\frac{1}{N} \operatorname{tr}\left(\tilde{A}_{i}\right)^{2}\right\rangle_{\mathrm{E}}
\end{gathered}
$$

This is not true any more once we introduce the constraint $\quad \alpha_{N}-\alpha_{1}=\sqrt{\kappa} \in \mathbb{C}$

$$
\begin{aligned}
R^{2}(t) & =\left\langle\frac{1}{n} \operatorname{tr}\left(\bar{A}_{i}(t)\right)^{2}\right\rangle \\
& \propto e^{i \frac{\pi}{4}}(\text { Euclidean regime }) \\
& >0(\text { Lorentzian regime })
\end{aligned}
$$

Thus, the signature of the space time can change dynamically in the IKKT model.

## 4. Results of the CL simulations

## Eigenvalues of $A_{0} \quad N=128$



## the time evolution of space

$N=128$ (preliminary results)
block size $n=16$

$$
t_{\rho}=\sum_{\nu=1}^{\rho}\left|\bar{\alpha}_{\nu+1}-\bar{\alpha}_{\nu}\right|
$$


$\propto e^{i \frac{\pi}{4}}$ (Euclidean regime) Scaling behavior observed!

## 5. Summary and Discussions

## Summary

- IKKT matrix model = a nonperturbative formulation of superstring theory
- The Euclidean model exhibits SSB of SO(10) to SO(3) due to the phase of the fermion determinant (or Pfaffian).
- In fact, the Lorentzian model becomes equivalent to Euclidean model if we define it by deformation of the integration contour.
- We introduce a "boundary condition" on both ends of the eigenvalue spectrum of $A_{0}$.
- Signature change from Euclidean to Lorentzian may naturally occur. (a bouncing universe scenario unlike Hartle-Hawking's no boundary)
- Can we make the duration of the real time regime longer by the boundary condition at larger N ?

Does the space become "real" at late times ?
Does the expanding behavior (like inflation) show up ?

## Discussions

- The expanding behavior observed in the solution to the EOM of the Lorentzian model with the IR cutoffs.


We expect similar expanding behavior to show up at late times.

Hatakeyama-Matsumoto-J.N.-Tsuchiya-Yosprakob, PTEP 2020 (2020) 4, 043B10

- Including fermionic matrices (SUSY model).

Does the SSB in the Euclidean model imply that SO(3) is realized in the present model as well ?
6. Backup slides

## 3. Complex Langevin method

## The complex Langevin method

 Parisi ('83), Klauder ('83)$$
Z=\int d x \neq(x) \quad x \in \mathbb{R}
$$

MC methods inapplicable due to sign problem !

Complexify the dynamical variables, and consider their (fictitious) time evolution :

$$
z^{(\eta)}(t)=x^{(\eta)}(t)+i y^{(\eta)}(t)
$$

defined by the complex Langevin equation

$$
\begin{aligned}
\frac{d}{d z^{(\eta)}(t)}=\sqrt[v\left(z^{(\eta)}(t)\right)]{ }+\eta(\eta(t)) & \begin{array}{ll}
\text { Gaussian noise (real) } \\
\text { probability } \propto \mathrm{e}^{-\frac{1}{4} \int d t \eta(t)^{2}} \\
\left.\langle\mathcal{O}\rangle \stackrel{?}{=} \lim _{t \rightarrow \infty} \sqrt{\mathcal{O}\left(z^{(\eta)}(t)\right)}\right\rangle \eta & v(x) \equiv \frac{1}{w(x)} \frac{\partial w(x)}{\partial x}
\end{array}
\end{aligned}
$$

Rem 1: When $w(x)$ is real positive, it reduces to one of the usual $M C$ methods.
Rem 2: The drift term $v(x) \equiv \frac{1}{w(x)} \frac{\partial w(x)}{\partial x}$ and the observables $\mathcal{O}(x)$
should be evaluated for complexified variables by analytic continuation.

## Complex Langevin equation

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The effective action

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\begin{aligned}
S_{\mathrm{eff}}= & -i N\left\{\frac{1}{2} \operatorname{tr}\left[A_{0}, A_{i}\right]^{2}-\frac{1}{4} \operatorname{tr}\left[A_{i}, A_{j}\right]^{2}\right\} \\
& -\log \Delta(\alpha)-\sum_{a=1}^{N-1} \tau_{a}+\frac{1}{4} \gamma_{\alpha}\left(\alpha_{N}-\sqrt{\kappa}\right)^{4}
\end{aligned}
$$

Complex Langevin equation

$$
\left\{\begin{aligned}
\frac{d \tau_{a}}{d t} & =-\frac{\partial S_{\mathrm{eff}}}{\partial \tau_{a}}+\eta_{a} \\
\frac{d\left(\mathcal{A}_{i}\right)_{a b}}{d t} & =-\frac{\partial S_{\mathrm{eff}}}{\partial\left(\mathcal{A}_{i}\right)_{b a}}+\left(\eta_{i}\right)_{a b}
\end{aligned}\right.
$$

$\tau_{a}$ : complex variables, $\mathcal{A}_{i}$ : general complex matrices.
In this work, we omit the fermionic matrices to reduce computation time

## 5. Comments on our previous work

## A phase diagram of the IKKT model



Emergence of (3+1)-dim. expanding behavior

6D bosonic model

$$
N=128, \quad \kappa=0.02, \quad \beta=8, \quad(s, k)=(-1,0), \quad n=16
$$

$$
\text { eigenvalues of } T_{i j}(t)=\frac{1}{n} \operatorname{tr}\left\{X_{i}(t) X_{j}(t)\right\}
$$



SSB : SO(5) $\rightarrow$ SO(3) occurs at some point in time.

## But the space is not continuous

6D bosonic model $N=128, \quad \kappa=0.02, \quad \beta=8, \quad(s, k)=(-1,0), \quad n=16$ eigenvalues of $Q=\sum_{i=1}^{5}\left\{X_{i}(t)\right\}^{2}$



Only 2 Evs of $Q$ become large suggesting the Pauli-matrix structure.

Recent development : the condition for correct convergence


In the Lorenzian case, adding a small "mass" term in the Dirac operator can cure the problem!

The Dirac operator in the Lorentzian model has real eigenvalues for Hermitian configurations !

6D SUSY model with deformation parameter $m_{\mathrm{f}}=1.0$

$$
N=32, \beta=1.4, \kappa=1.0
$$




