

Multiple modular symmetries as the origin of flavour

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See e.g. <https://arxiv.org/pdf/1706.08749> *Fermi*

Consider a complex field τ , ($\text{Im} \tau > 0$)
a Symmetry $\bar{\Gamma}$ with elements γ acts

$$\gamma : \tau \rightarrow \gamma\tau = \frac{a\tau + b}{c\tau + d},$$

It is convenient to represent as 2×2

$$\bar{\Gamma} = \left\{ \begin{pmatrix} a & b \\ c & d \end{pmatrix} / (\pm 1), a, b, c, d \in \mathbb{Z}, ad - bc = 1 \right\}.$$

(2)

The group has 2 gens:

$$S_\tau^2 = (S_\tau T_\tau)^3 = \mathbf{1}.$$

$$S_\tau : \tau \rightarrow -\frac{1}{\tau}, \quad T_\tau : \tau \rightarrow \tau + 1,$$

$$S_\tau = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}, \quad T_\tau = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}.$$

③

A subgroup $\bar{\Gamma}(N)$

$$a = k_a N + 1, \quad d = k_d N + 1, \quad b = k_b N, \quad c = k_c N,$$

$$\bar{\Gamma}(N) = \left\{ \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in PSL(2, \mathbb{Z}), \quad \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \pmod{N} \right\}.$$

Make factor group

$$\bar{\Gamma} / \bar{\Gamma}(N) \sim \Gamma_N$$

$$\Gamma_2 \sim S_3, \quad \Gamma_3 \sim A_4, \quad \Gamma_4 \sim S_4, \quad \Gamma_5 \sim A_5$$

④

Reminder: Factor Group

G with Inv. subgroup H ; make cosets

$H, g_1 H, \dots$ These form a group

where multiplication is

$$g_i H \cdot g_j H = (\delta_i \delta_j) H$$

$$S_3: \{e, (12), (23), (31); (123), (321)\}$$

$$Z_3: \{e, (123), (321)\} \cong H \quad S_3/Z_3 \sim Z_2$$
$$\{H, (12)H\} \sim Z_2$$

(5)

In a \mathbb{R}^N invariant theory,
chiral superfield ϕ

$$\phi_i(\tau) \rightarrow \phi_i(\gamma\tau) = (c\tau + d)^{-2k_i} \rho_{I_i}(\gamma) \phi_i(\tau),$$

SUSY action

$$S = \int d^4x d^2\theta d^2\bar{\theta} K(\phi_i, \bar{\phi}_i; \tau, \bar{\tau}) + \left[\int d^4x d^2\theta W(\phi_i; \tau) + \text{h.c.} \right],$$

$$K(\phi_i, \bar{\phi}_i; \tau, \bar{\tau}) \rightarrow K(\phi_i, \bar{\phi}_i; \tau, \bar{\tau}) + f(\phi_i, \tau) + \bar{f}(\bar{\phi}_i, \bar{\tau}),$$

$$W(\phi_i; \tau) \rightarrow W(\phi_i; \tau). \quad \text{invariant } W$$

(6)

$$W(\phi_i; \tau) = \sum_n \sum_{\{i_1, \dots, i_n\}} \sum_{I_Y} (Y_{I_Y} \phi_{i_1} \cdots \phi_{i_n})_1 \cdot \tau$$

"Coefficients"

Complicated way of writing a general form

"Coefficients" transform

$$Y_{I_Y}(\tau) \rightarrow Y_{I_Y}(\gamma\tau) = (c\tau + d)^{2k_Y} \rho_{I_Y}(\gamma) Y_{I_Y}(\tau)$$

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Stabilisers

$$\rho_I(\gamma) Y_I(\tau_\gamma) = (c\tau_\gamma + d)^{-2k} Y_I(\tau_\gamma). \quad (31)$$

This equation lead us to the following important properties for the stabiliser and the modular form:

- A modular form at a stabiliser $Y_I(\tau_\gamma)$ is an eigenvector of the representation matrix $\rho_I(\gamma)$ with respective eigenvalue $(c\tau_\gamma + d)^{-2k}$.
- The stabiliser τ_γ satisfies $|c\tau_\gamma + d| = 1$ since $(c\tau_\gamma + d)^{-2k}$ is an eigenvalue of a unitary matrix.

A special case is that when $(c\tau_\gamma + d)^{-2k} = 1$ is satisfied, $\rho_I(\gamma) Y_I(\tau_\gamma) = Y_I(\tau_\gamma)$ and we recover the residual flavour symmetry generated by γ . In general, the eigenvalue does not need to be fixed at 1 in the framework of modular symmetry.

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Symmetries and stabilisers in modular invariant flavour models

Ivo de Medeiros Varzielas, Miguel Levy, Ye-Ling Zhou

The idea of modular invariance provides a novel explanation of flavour mixing. Within the context of finite modular symmetries Γ_N and for a given element $\gamma \in \Gamma_N$, we present an algorithm for finding stabilisers (specific values for moduli fields τ , which remain unchanged under the action associated to γ). We then employ this algorithm to find all stabilisers for each element of finite modular groups for $N = 2$ to 5, namely, $\Gamma_2 \simeq S_3$, $\Gamma_3 \simeq A_4$, $\Gamma_4 \simeq S_4$ and $\Gamma_5 \simeq A_5$. These stabilisers then leave preserved a specific cyclic subgroup of Γ_N . This is of interest to build models of fermionic mixing where each fermionic sector preserves a separate residual symmetry.

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E.g. $\tau = i$ is a stabiliser for S_Z

$$S_Z(i) = -\frac{1}{i} = i$$

$\tau = i\infty$ is a stabiliser for T_Z

$$T_Z(i\infty) = 1 + i\infty = i\infty$$

Stabilisers usually depend on N

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We know what τ stabilises

Method

1. Take $\tau = \tau_i$, where $\tau_i = \gamma_i \tau_i, i = 1, \dots, 4$ is a stabiliser of \mathcal{D} ;
2. Act γ on τ : $\tau' = \gamma\tau$. Compute γ^{-1} ; \longrightarrow Go from τ to τ' with γ
3. The element that stabilises τ' is given by $\gamma^{-1}\gamma_i\gamma$.

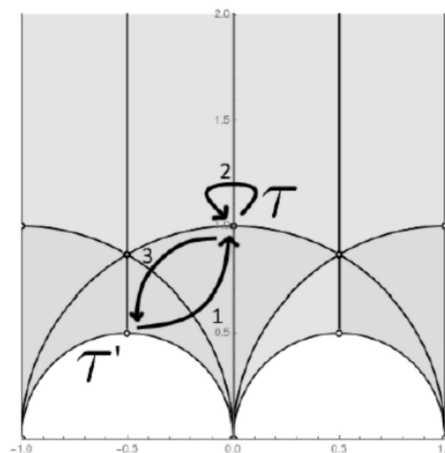
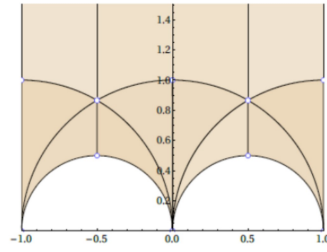


Figure 1: An example of the applied methodology to find the stabilisers of Γ_N . The example shown is for Γ_2 , where the arrows denote the actions of different elements, γ^{-1} , γ_i , γ , for 1,2,3 respectively, following the convention of the text.

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$$\Gamma_2 \sim S_3$$



Domain

Figure 2: The fundamental domain $\mathcal{D}(2)$ of $\bar{\Gamma}(2)$ (i.e., the full target space of $\Gamma_2 \simeq S_3$) with the stabilisers of modular transformations of Γ_2 denoted as dots.

	γ	τ_γ
\mathcal{C}_2	$T_\tau C_\tau$	$0, 1 + i$
	T_τ	$i\infty, \frac{1}{2} + \frac{i}{2}$
	S_τ	$i, 1$
\mathcal{C}_3	$T_\tau S_\tau$	$-\frac{1}{2} + \frac{i\sqrt{3}}{2}, \frac{1}{2} + \frac{i\sqrt{3}}{2}$
	C_τ	$-\frac{1}{2} + \frac{i\sqrt{3}}{2}, \frac{1}{2} + \frac{i\sqrt{3}}{2}$

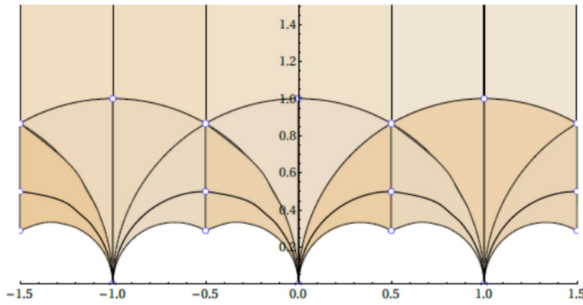
Stabilisers

Table 1: The non-identity elements of Γ_2 and respective stabilisers.

(12)

$$\Gamma_3 \sim A_4$$

Domain



Stabilisers

	γ	τ_γ
\mathcal{C}_2	C_τ^2	$-\frac{1}{2} + \frac{i\sqrt{3}}{2}, 1$
	T_τ^2	$i\infty, \frac{3}{2} + \frac{i}{2\sqrt{3}}$
	$T_\tau C_\tau$	$0, \frac{3}{2} + \frac{i\sqrt{3}}{2}$
	$C_\tau T_\tau$	$-1, \frac{1}{2} + \frac{i\sqrt{3}}{2}$
\mathcal{C}_3	C_τ	$-\frac{1}{2} + \frac{i\sqrt{3}}{2}, 1$
	T_τ	$i\infty, \frac{3}{2} + \frac{i}{2\sqrt{3}}$
	$C_\tau S_\tau$	$0, \frac{3}{2} + \frac{i\sqrt{3}}{2}$
	$T_\tau S_\tau$	$-1, \frac{1}{2} + \frac{i\sqrt{3}}{2}$
\mathcal{C}_4	$T_\tau^2 C_\tau$	$-1 + i, \frac{1}{2} + \frac{i}{2}$
	S_τ	$i, \frac{3}{2} + \frac{i}{2}$
	$T_\tau C_\tau T_\tau$	$-\frac{1}{2} + \frac{i}{2}, 1 + i$

(13)

Multiples

Multiple modular symmetries as the origin of flavour

Ivo de Medeiros Varzielas, Stephen F. King, Ye-Ling Zhou

We develop a general formalism for multiple moduli and their associated modular symmetries. We apply this formalism to an example based on three moduli with finite modular symmetries S_4^A , S_4^B and S_4^C , associated with two right-handed neutrinos and the charged lepton sector, respectively. The symmetry is broken by two bi-triplet scalars to the diagonal S_4 subgroup. The low energy effective theory involves the three independent moduli fields τ_A , τ_B and τ_C , which preserve the residual modular subgroups Z_3^A , Z_2^B and Z_3^C , in their respective sectors, leading to trimaximal TM_1 lepton mixing, consistent with current data, without flavons.

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Two A_4 modular symmetries for Tri-Maximal 2 mixing

Ivo de Medeiros Varzielas, João Lourenço

We construct lepton flavour models based on two A_4 modular symmetries. The two A_4 are broken by a bi-triplet field to the diagonal A_4 subgroup, resulting in an effective modular A_4 flavour symmetry with two moduli. We employ these moduli as stabilisers, that preserve distinct residual symmetries, enabling us to obtain Tri-Maximal 2 (TM2) mixing with a minimal field content (without flavons).

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Multiply Moduli $\gamma_J : \tau_J \rightarrow \gamma_J \tau_J = \frac{a_J \tau_J + b_J}{c_J \tau_J + d_J}$.

$\Gamma_{N_1}^1 \times \Gamma_{N_2}^2 \times \dots \times \Gamma_{N_M}^M$, Chiral Superfield

$$\begin{aligned} \phi_i(\tau_1, \dots, \tau_M) &\rightarrow \phi_i(\gamma_1 \tau_1, \dots, \gamma_M \tau_M) \\ &= \prod_{J=1, \dots, M} (c_J \tau_J + d_J)^{-2k_{i,J}} \otimes_{J=1, \dots, M} \rho_{I_{i,J}}(\gamma_J) \phi_i(\tau_1, \tau_2, \dots, \tau_M), \end{aligned}$$

SUSY Action :

$$\mathcal{S} = \int d^4x d^2\theta d^2\bar{\theta} K(\phi_i, \bar{\phi}_i; \tau_1, \dots, \tau_M, \bar{\tau}_1, \dots, \bar{\tau}_M) + \int d^4x d^2\theta W(\phi_i; \tau_1, \dots, \tau_M) + \text{h.c.},$$

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$$W(\phi_i; \tau_1, \dots, \tau_M) = \sum_n \sum_{\{i_1, \dots, i_n\}} (Y_{(I_{Y,1}, \dots, I_{Y,M})} \phi_{i_1} \cdots \phi_{i_n})_{\mathbf{1}},$$

where the "coefficients" are modular forms ...

$$\begin{aligned} Y_{(I_{Y,1}, \dots, I_{Y,M})}(\tau_1, \dots, \tau_M) &\rightarrow Y_{(I_{Y,1}, \dots, I_{Y,M})}(\gamma_1 \tau_1, \dots, \gamma_M \tau_M) \\ &= \prod_{J=1, \dots, M} (c_J \tau_J + d_J)^{2k_{Y,J}} \otimes_{J=1, \dots, M} \rho_{I_{Y,J}}(\gamma_J) Y_{(I_{Y,1}, \dots, I_{Y,M})}(\tau_1, \dots, \tau_M). \end{aligned}$$

Complicated way of writing a general form!

(16)

Example with S_4

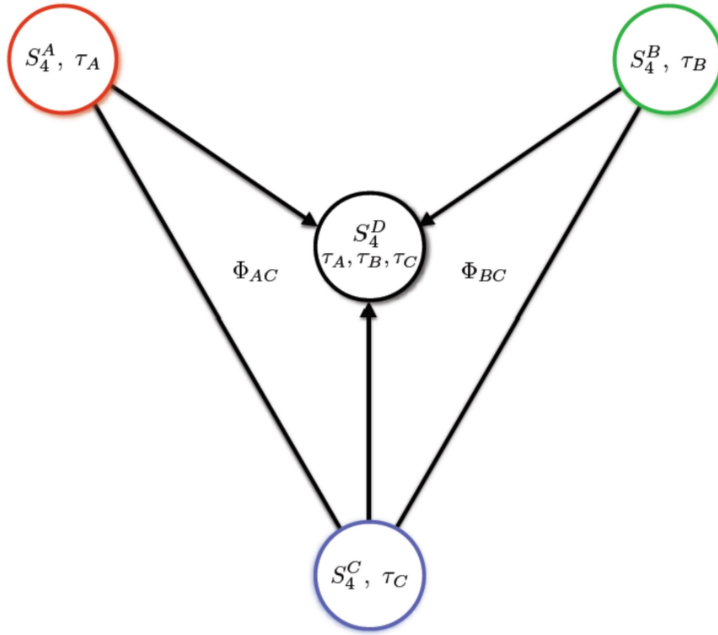
$$S = T_\tau^2, \quad T = S_\tau T_\tau, \quad U = T_\tau S_\tau T_\tau^2 S_\tau.$$

$$\hookrightarrow \rho_I(S) = \begin{pmatrix} -1 & 2 & 2 \\ 2 & \cdot & 2 \\ 2 & 2 & -1 \end{pmatrix} / 3; \quad \rho_I(\gamma) Y_I(\tau_\gamma) = Y_I(\tau_\gamma)$$

$$Y_A(\langle z_A \rangle) = \begin{pmatrix} -1 \\ 2\omega \\ 2\omega^2 \end{pmatrix}$$

$$S = \begin{pmatrix} 1 & 2 \\ 0 & 1 \end{pmatrix}, \quad T = \begin{pmatrix} 0 & 1 \\ -1 & -1 \end{pmatrix}, \quad U = \begin{pmatrix} 1 & -1 \\ 2 & -1 \end{pmatrix}.$$

(17)



(18)

Field	S_4^A	S_4^B	S_4^C	$2k_A$	$2k_B$	$2k_C$	Yuk/Mass	S_4^A	S_4^B	S_4^C	$2k_A$	$2k_B$	$2k_C$
L	1	1	3	0	0	0	$Y_e(\tau_C)$	1	1	3	0	0	6
e^c	1	1	1	0	0	-6	$Y_\mu(\tau_C)$	1	1	3	0	0	4
μ^c	1	1	1	0	0	-4	$Y_\tau(\tau_C)$	1	1	3	0	0	2
τ^c	1	1	1	0	0	-2	$Y_A(\tau_A)$	3	1	1	6	0	0
N_A^c	1	1	1	-6	0	0	$Y_B(\tau_B)$	1	3	1	0	4	0
N_B^c	1	1	1	0	-4	0	$M_A(\tau_A)$	1	1	1	12	0	0
Φ_{AC}	3	1	3	0	0	0	$M_B(\tau_B)$	1	1	1	0	8	0
Φ_{BC}	1	3	3	0	0	0	$M_{AB}(\tau_A, \tau_B)$	1	1	1	6	4	0

Φ are bi-triplets

$$\begin{aligned}
 w_\ell = & \frac{1}{\Lambda} [L\Phi_{AC}Y_A(\tau_A)N_A^c + L\Phi_{BC}Y_B(\tau_B)N_B^c] H_u \\
 & + [LY_e(\tau_C)e^c + LY_\mu(\tau_C)\mu^c + LY_\tau(\tau_C)\tau^c] H_d \\
 & + \frac{1}{2}M_A(\tau_A)N_A^cN_A^c + \frac{1}{2}M_B(\tau_B)N_B^cN_B^c + M_{AB}(\tau_A, \tau_B)N_A^cN_B^c,
 \end{aligned}$$

cross term allowed

(19)

$$\langle \Phi_{AC} \rangle_{i\alpha} = v_{AC}(P_{23})_{i\alpha}, \quad \langle \Phi_{BC} \rangle_{m\alpha} = v_{BC}(P_{23})_{m\alpha}.$$

$$P_{23} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

(these come from the potential)

$$\begin{aligned} L\Phi_{AC}Y_A(\tau_A)N_A^c &= L_1[(\Phi_{AC})_{11}(Y_A)_1 + (\Phi_{AC})_{21}(Y_A)_3 + (\Phi_{AC})_{31}(Y_A)_2]N_A^c \\ &+ L_2[(\Phi_{AC})_{13}(Y_A)_1 + (\Phi_{AC})_{23}(Y_A)_3 + (\Phi_{AC})_{33}(Y_A)_2]N_A^c \\ &+ L_3[(\Phi_{AC})_{12}(Y_A)_1 + (\Phi_{AC})_{22}(Y_A)_3 + (\Phi_{AC})_{32}(Y_A)_2]N_A^c, \\ &= (L_1, L_2, L_3)P_{23} \begin{pmatrix} (\Phi_{AC})_{11} & (\Phi_{AC})_{12} & (\Phi_{AC})_{13} \\ (\Phi_{AC})_{21} & (\Phi_{AC})_{22} & (\Phi_{AC})_{23} \\ (\Phi_{AC})_{31} & (\Phi_{AC})_{32} & (\Phi_{AC})_{33} \end{pmatrix}^T P_{23} \begin{pmatrix} (Y_A)_1 \\ (Y_A)_2 \\ (Y_A)_3 \end{pmatrix} N_A^c, \end{aligned}$$

(20)

$$S_4^A \times S_4^B \times S_4^C \rightarrow S_4^D,$$

$$w_\ell^{\text{eff}} = \left[\frac{v_{AC}}{\Lambda} LY_A(\tau_A)N_A^c + \frac{v_{BC}}{\Lambda} LY_B(\tau_B)N_B^c \right] H_u$$

$$+ [LY_e(\tau_C)e^c + LY_\mu(\tau_C)\mu^c + LY_\tau(\tau_C)\tau^c] H_d$$

$$+ \frac{1}{2}M_A(\tau_A)N_A^c N_A^c + \frac{1}{2}M_B(\tau_B)N_B^c N_B^c + M_{AB}(\tau_A, \tau_B)N_A^c N_B^c,$$

where $\int \cdot$ $LY_A(\tau_A)N_A^c = [L_1(Y_A)_1 + L_2(Y_A)_3 + L_3(Y_A)_2]N_A^c,$

$$Y_e(\langle \tau_C \rangle) = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \quad Y_\mu(\langle \tau_C \rangle) = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}, \quad Y_\tau(\langle \tau_C \rangle) = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix},$$

$$Y_A(\langle \tau_A \rangle) = \begin{pmatrix} -1 \\ 2\omega \\ 2\omega^2 \end{pmatrix}, \quad Y_B(\langle \tau_B \rangle) = \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix},$$

(21)

$$M_N = \begin{pmatrix} M_A & M_{AB} \\ M_{AB} & M_B \end{pmatrix}. \quad V = e^{i\alpha_3} \begin{pmatrix} \hat{c}_R & \hat{s}_R^* \\ -\hat{s}_R & \hat{c}_R^* \end{pmatrix},$$

own. tan β

$$M_\nu = (\mu_1 \hat{c}_R^2 + \mu_2 \hat{s}_R^{*2}) \begin{pmatrix} 1 & -2\omega^2 & -2\omega \\ -2\omega^2 & 4\omega & 4 \\ -2\omega & 4 & 4\omega^2 \end{pmatrix} + (\mu_1 \hat{s}_R^2 + \mu_2 \hat{c}_R^{*2}) \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & -1 & 1 \end{pmatrix} \\ + (\mu_1 \hat{c}_R \hat{s}_R - \mu_2 \hat{c}_R^* \hat{s}_R^*) \begin{pmatrix} 0 & -1 & 1 \\ -1 & 4\omega^2 & 2i\sqrt{3} \\ 1 & 2i\sqrt{3} & -4\omega \end{pmatrix}, \rightarrow \text{PMNS } \Rightarrow \text{TM}_1$$

$$U_{\text{TM}_1} = \begin{pmatrix} \frac{2}{\sqrt{6}} & - & - \\ -\frac{1}{\sqrt{6}} & - & - \\ -\frac{1}{\sqrt{6}} & - & - \end{pmatrix}. \quad (22)$$

Good Fit

BF	Para.	χ^2	α_1	α_2	θ_R	μ_1	μ_2
		0.74	64.53°	20.38°	43.01°	0.00633 eV	0.0114 eV
Obs.	θ_{12}	θ_{13}	θ_{23}	δ	m_2	m_3	m_{ee}
	34.33°	8.61°	49.6°	290°	0.00860 eV	0.0502 eV	0.00206 eV

(23)

Conclusions

- Modular Symmetries are powerful as the origin of Flavour
- Stabilisers play a key role
- Multiple Modular Symmetries have specific advantages

(24)

TM

Thanks

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